

Inductive Linear Displacement Transducers Miniature models IW 10 and IW 101

Measuring strokes : 4 mm, 5 mm, 8 mm, 10 mm, 15 mm

- Model IW 10 : Measuring strokes up to 8 mm
- Model IW 101 : Measuring strokes up to 15 mm
- Contactless, robust sensor system
- Infinite resolution, no hysteresis

- Exitation and signal processing by external electronic modules
- Various mechanical configurations
- Protection to IP 66



Construction and operating principle

The displacement transducers operate according to the principle of the differential choke, i.e. an inductive half bridge. They consist of two coils which are encapsulated in a stainless steel cylinder ensuring positive protection against vibration, shock, humidity, oil and corrosive matter. A mu-metal plunger core causes opposing changes of inductance when it is displaced through the centre of the coils.

The displacement transducers are designed for a carrier frequency of 10 kHz. Other frequencies can be used but may involve changes of output values.



An external electronic oscillator/demodulator and amplifier module produces the carrier frequency and a DC voltage output signal. There are several different types of modules available.

The IW 10 Transducers are supplied either with connecting leads or with plug and socket connectors. They are also available with spring returns for gauge application.

Standard measuring strokes

- Model IW 10:
- 4 and 8 mm Model IW 101 : 5, 10 and 15 mm

Technical Data

- Linearity :
- ≤ 0.5 % or ≤ 0.25 %
- Operating temperature ranges □ IW 10 : □ IW 101 :
 - 55°C to + 120°C -40°C to + 85°C $\leq \pm 0.01\%/^{\circ}C$
- Temperature drift : Resistance to shock :
 - 20g SRS at 20 to 2000 Hz 3g rms at 20 to 2000 Hz

IP 66

- Resistance to vibration :
- Protection class : Further data :
- see table on page 2
- **Mechanical variants**

The model IW 10 transducers are available either with cylindrical or square shaped case. The plunger travels loose in an open bore. Double ended plungers or plungers with reduced core diameter can be supplied upon request.

For gauge type applications a spring return is provided.

The model IW 101 transducers have a cylindrical case. They are available either with flat cable or with angular plug connections. The mating plug is either straight or angular shaped (protection to IP 66). A special plug with screened cable (protection to IP 67) is also available.

For gauge type applications a spring return is provided.

Exitation and signal processing

For details please refer to table page 4.



Dimensions in mm

Model IW 10 (plunger in central position)



Mass: 9g

Materials:

Tube : Coil former :	Mu-metal, stainless Dialylphtalat
Core :	Mu-metal
Plunger rod :	brass
Leads :	32 AWG Kynar standed wire, 300 mm long
Encapsulation:	Epoxy resin

Modell IW 10R (plunger in central position)



Mass: 61 g

Materials:

Case :	Steel, Nickel plated
Leads :	20 AWG, Kynar standed wire
Other parts :	as for IW 10

Plunger with core for IW 10 (standard)



Double plunger with core for IW 10 (optional)



Core diameters d₂: 3.8 mm (standard) or 3.0 mm (optional). (When 3 mm dia is used the clearence between core and coil increases to allow slight radial play of the plunger.- Additional order code is "B").

Model IW 10 ... T (Gauge)



IW 10 T Stroke▼	BM mm	B1 mm	Pre-travel mm	Over-travel mm	Spring force at BM	Mass g
4 mm	18	23.5	3.5	4.5	1 N	17
8 mm	18	23.5	1.5	2.5	1 N	17

BM = Plunger in central position, B1 = Plunger full out.

Electrical connections



Using these connections a positively increasing signal is obtained when moving the plunger towards the electric exit.

Nominal sensitivity

 $1000\,mV/mm$, when using module OD 15 (without amplification).

Order code format



* The applicable A-No. is allocated after the definition of the deviation when ordering. No A-No. is given for standard versions as specified in the data sheet.

Mounting block MB10 (Brass, Nickel plated) (to be ordered separately)





Dimensions in mm





Materials:

Tube :	Mu-metal, strainless
Coil former :	Delrin
Core :	Mu-metal
Plunger rod :	brass
Leads :	Flate cable 3 x 0.14 mm ²
Encapsulation:	Epoxy resin

Model IW 101 ... S (with connector)



For	core o	diameters	d ₂ s	ee IW1	0/	page 2	2.
					_		

IW 101 stroke▼	L1 mm	L2 mm	L3 mm	L4 mm	Mass"K" g	Mass"S" g	Plunger Mass g
5 mm	35	40	~ 18	64	14	17	3
10 mm	35	40	~ 18	64	14	17	3
15 mm	35	50	~ 28	74	17	20	4
1 1 – Plunger in central position							

L1= Plunger in central position

Model IW 101 ... KT (gauge)



Model IW 101 ... ST



IW 101T stroke▼	L2 mm	BM mm	B1 mm	Pre-travel mm	Over-travel mm	Mass"KT" g	Mass"ST" g
5 mm	50	22	36	11.5	8	22	25
10 mm	50	22	36	9	5,5	22	25
15 mm	60	26	40	6.5	7	25	28

BM = Plunger in central position, B1 = Plunger full out.

Electrical connections for IW 101 ... K



Electrical connections for IW 101 ... S



Using these connections a positively increasing signal is obtained when moving the plunger towards the electric exit.

Nominal sensitivity (using OD 15, without amplification)

stroke 🕨	5	10	15	
mV / mm	900	900	670	

Order code format



* The applicable A-No. is allocated after the definition of the deviation when ordering. No A-No. is given for standard versions as specified in the data sheet.



The plug STK65 is always supplied with cable :

length 6.50 m

- □ 4 wires 0.34 mm ²
- With common screen
- □ PVC sheathing
- □ Outside dia 5 mm



Electronic Modules for the excitation of Inductive Transducers and for the processing of the output signal

Type of Module	OD 15-2	OV 15-2	OE 30-1 (OE 30-2)		
Supply voltage V_s	± 11.5 ± 16 \	/DC symmetrical	+ 21.5 + 32 VDC		
Supply current Is	~ 30 mA	~ 30 mA	\leq 45 mA at I ₀ = 20 mA		
Oscillator frequency		10 kHz nominal			
Oscillator voltage		10 V _{rms}			
Output signal $V_0(I_0)$	ttput signal $V_0(I_0)$ $\pm 2 \dots \pm 5$ VDC depending on type of transducer		0 20 mA (4 20 mA)		
Sensitivity	not adjustable	adjustable *	adjustable*		
Zero-point	not adjustable	adjustable *	not adjustable		
Ripple	\leq 10 mV _{p-p}	≤ 5 mV _{p-p}	\leq 0.01 mA _{p-p}		
Attenuation	1% c	of V_0 at measuring frequency 100	iency 100 Hz		
Load resistance R_L	≥ 2 kΩ	$\ge 2 \text{ k}\Omega$	500 Ω max.		
Temperatur drift of $V_0^{}$ (I $_0^{}$)	0.005% / °C				
Switch-on drift of V_0 (I_0) 2 mV / 15 min. (ty		1 mV / 15 min. (typ.)	2 µA / 15 min. (typ.)		
Dependence of ${\rm V_{_0}}\left({{\rm I_0}} \right)$ on ${\rm V_{_S}}$	at $\Delta V_{s} \pm 1V \Delta V_{0} \pm 0.05\%$ at $\Delta V_{s} \pm 1V \Delta I_{0} =$				
Operating temperature range	- 10° + 80°C				

* Wiring instructions will be supplied with each item.

Series OA and DE-modules as well as Multi-channel PC-boards are described in data sheet 10219AE

Basic block diagrams





The transmission line between the transducer and the electronic module may measure up to 100 meters. Screened cables should be used to avoid the interference of outside noise.



Mounting grid 1:1 (5 mm pitch / view of mounting face)



- 4 -