

- **Contactless, robust sensor system**
- **Infinite resolution, no hysteresis**
- **Calibrated output signals:**
 0...20 mA, 4...20 mA, ± 10 V, 0...10 V

- **Integral electronics for DC in / DC out**
- **Accuracy 0.5% or 0.25%**
- **Definite repeatability**
- **Protection class IP 66**

Construction and operating principle

The displacement transducer operates according to the new principle of fractional inductivity allotment within the hollow coil. Depending on the position of the core the inductivity changes within the corresponding coil section. This kind of layout provides for more position data than the classical half-bridge or LVDT configuration. An integral electronic circuit transforms these data into a signal proportional to the displacement of the plunger core.

The electronic circuits contains an oscillator, demodulator, an amplifier and in some cases a current output source. Its SMD-design is short-circuit proof and protected against reverse polarity. The sensor system is completely sealed within a non-corrosive steel case to ensure positive protection against vibration, shock, humidity, oil and corrosive matter.

The new principle of fractional inductivity allotment as described above brings about an outstanding increase of the measuring stroke. In comparison to the IW 250 model the useful range of the IW 260 model increases by 70 to 100% based on the same length of the case.

Standard measuring strokes : 80 mm, 170 mm, 360 mm

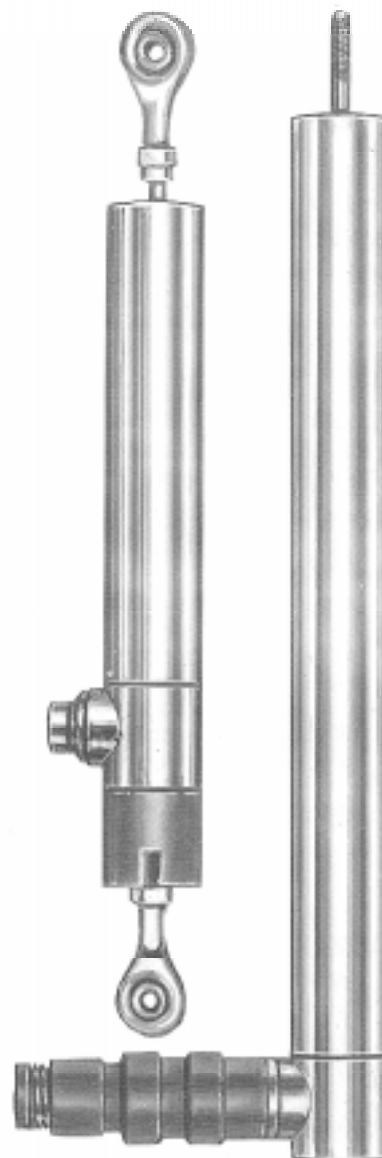
Special calibration using the standard case lengths can be provided upon request, e.g. measuring stroke 150 mm equals 20 mA at case $L_2 = 250$ mm.

Standard versions and calibrations

Type	Output-signal	V_S^{**}	Output sense *	Mid-point at
IW 261	0 ... 20 mA	21.5 - 32 V	increasing	10 mA
IW 262			decreasing	
IW 263	4 ... 20 mA	21.5 - 32 V	increasing	12 mA
IW 264			decreasing	
IW 265	± 10 V	± 13 - ± 16 V	increasing	0 V
IW 266			decreasing	
IW 26A	0 ... 10 V	21.5 - 32 V	increasing	5 V
IW 26B			decreasing	
IW 269	Special variants			

* Increasing means that the output signal increases positively when the plunger is moved in the direction towards the plug.

** Other supply voltages upon request.



Technical Data

- Supply voltage range V_S : 21.5 to 32 VDC or (prot'd against reverse polarity) ± 13 to ± 16 VDC
 - Accuracy : 0.5% or 0.25% *
 - Temperature drift : < 0.01%/°C
 - Stability : < 0.1% in 24 hours
 - Measurement frequency : 100 Hz max.
 - Operating temperature range : -10°C to +80°C
 - Storage temperature range : -30°C to +80°C
 - Resistance to shock : 250g SRS at 20 to 2000 Hz
 - Resistance to vibration : 20g rms (50g peak) at 20 to 2000 Hz
 - Protection class : IP 66
- * For special calibration 0.5% only.

Current output (IW 261 to IW 264)

- Output signal : 0...20 mA or 4...20 mA
- Supply current I_s : 60 mA max.
- Load resistance R_L : 0...500 Ω
- Ripple : < 0.005 mA_{p-p}
- Dependence on R_L : < 0.001% for $\Delta R_L = 100 \Omega$
- Dependence on V_s : < 0.05% for $\Delta V_s = 1 V$
- Maximum output current : 25 mA

Voltage output (IW 265 to IW 26B)

- Output signal : ± 10 VDC or 0...10 VDC *
 - Supply current I_s : 50 mA max.
 - Permissible load R_L : 2 k Ω (short-circuit proof)
 - Ripple : < 5 mV_{p-p}
 - Dependence on V_s : < 0.05% for $\Delta V_s = 1 V$
- * Residual voltage 0.1 VDC

Note: Unless otherwise stated, all values are valid at +20°C ambient temperature and 24 VDC or ± 15 VDC supply voltage, starting 10 minutes after switch-on.

Special Versions and accessories

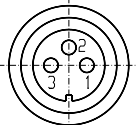
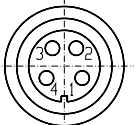
- Version KV : With ball joint on plunger without guide.
- Version KFN : With ball joint on plunger and special guide.
- Version KHN : With ball joint on case (plug end). Can be combined with KFN.
- Version PK : With cable exit and gland

- Mating plug : Coupling socket BI 681 (to IP 40), included in supplied items.
Coupling socket BI 723M (to IP 66) metal case with outer ring connected to ground, must be ordered separately.
Version 3 PS (3-way)
Version 4 PS (4-way)
All contacts gold-plated.

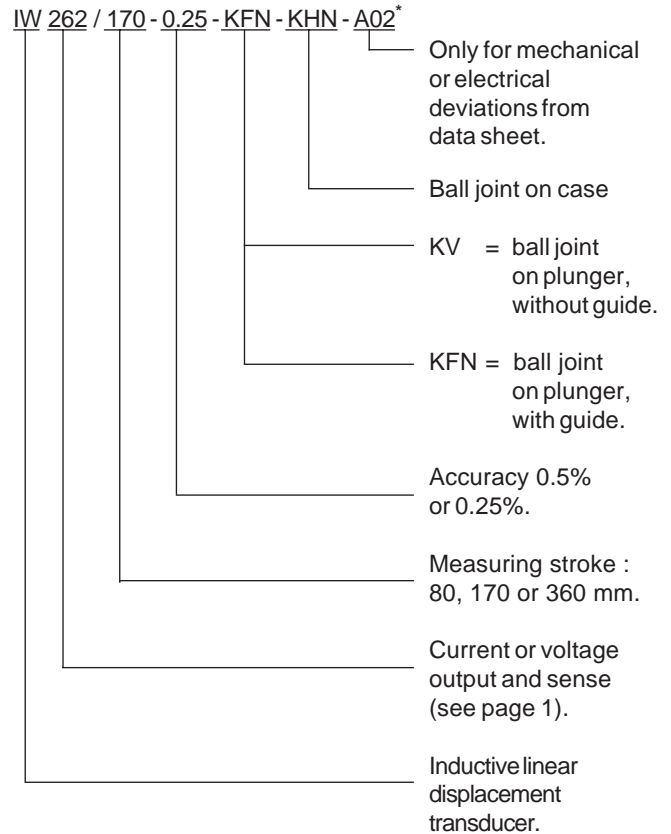
- MB 25 : Mounting block with clamp fixing (must be ordered separately).

Electrical connections

(with view on the contacts at the transducer case.)

IW 261, IW 262, IW 263, IW 264, IW 26A, IW 26B	IW 265 and IW 266
<p>1 = +V_s 2 = -V_s (0V) -I_o 3 = +I_o (output signal)</p> 	<p>1 = +V_s 2 = 0V (V_s common) 3 = -V_s 4 = +V_o (output signal)</p> 

Order code format



* The applicable A-No. is allocated after the definition of the deviation when ordering. No A-No. is given for standard versions as specified in the data sheet.

Materials

- External and internal tube : Chrome-nickel steel
- Plunger : Chrome-nickel steel
- Core : Mu-metal
- Connector case : Brass, nickel-plated
- Connector contacts : Gold-plated

Calibration

Both the sensor system and plunger core are calibrated as one unit. They carry the same serial number.

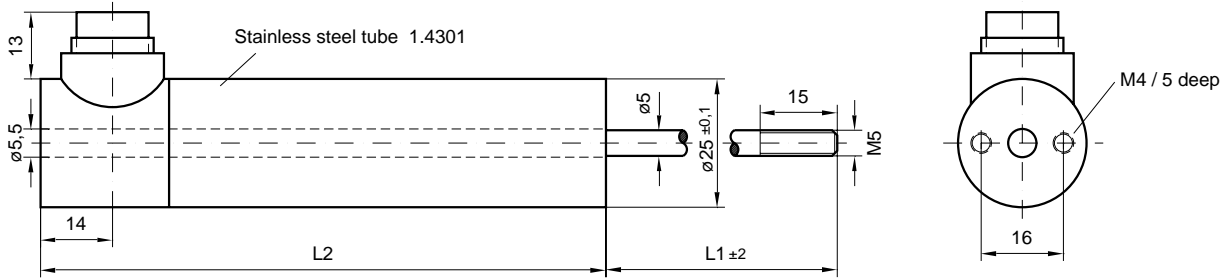
Lengths and masses (refer to drawings page 3)

Type	L1* mm	L2 mm	without plunger g	plunger only g
IW 260/80	70	140	240	19
IW 260/170	115	250	380	31
IW 260/360	210	500	720	56
KV or KFN:	22 g	Mating plug BI 681 (IP 40) : 30 g		
KHN :	55 g	Mating plug BI 723 M (IP 66) : 75 g		

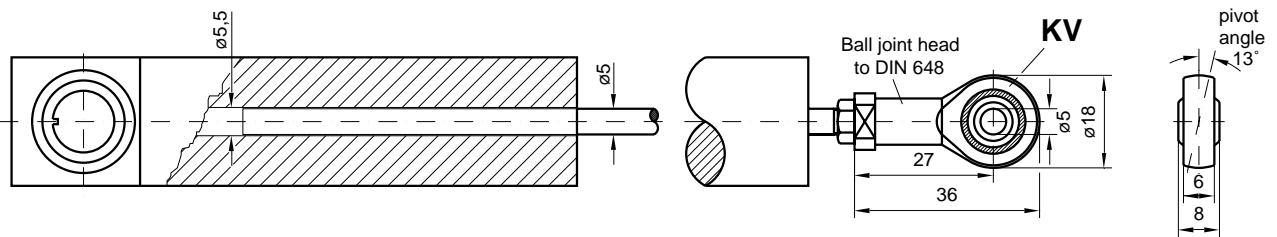
* L1 = Plunger in central position: $I_o = 10$ (12) mA, resp. $V_o = 0$ (5) V.

Dimensions in mm

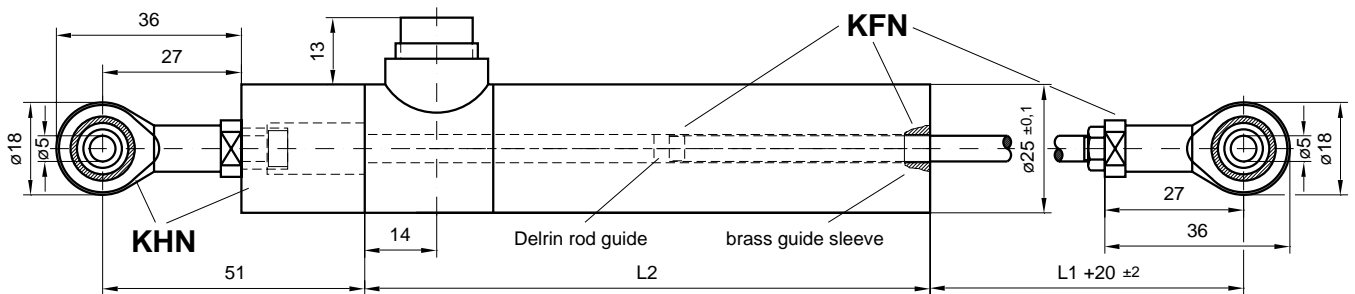
Standard version



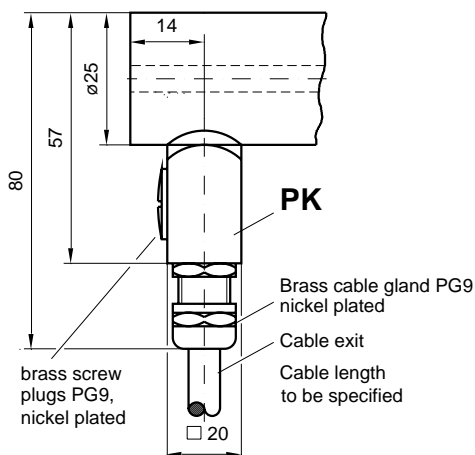
Version with ball joint on plunger (KV)



Version with ball joints on plunger (KFN) and on end of case (KFH)



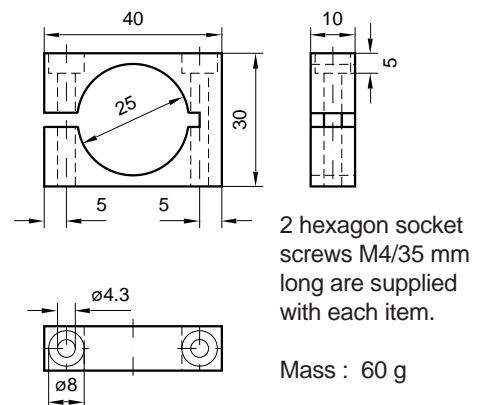
Version PK with cable exit and gland



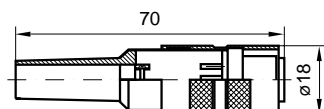
Electrical connections

IW 261 to IW 264 IW 26A + IW 26B		IW 265 + IW 266	
brown	+ V _S	brown	+ V _S
white	- V _S (0V)	yellow	0V
green	V ₀	white	- V _S
		green	V ₀

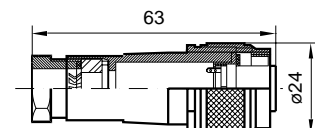
MB 25 Mounting block, brass Nickel plated (to be ordered separately)



Mating Plugs



Metal case (included in supplied items)
BI 681 3PS or 4PS (IP40)



Metal case with outer ring connected to ground (must be ordered separately) . BI 723M 3PS or 4PS (IP66)