Classical model of the electron and the definition of electromagnetic field momentum

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The classical model of the electron in a vacuum is discussed in terms of a simple procedure for its assembly. The description of the assembly in two different inertial frames clarifies the traditional Lorentz-transformation difficulties of the model and confirms the appropriateness of the standard definition of the electromagnetic momentum density $\vec{g} = (1/4\pi c)\vec{E} \times \vec{B}$. Recent suggestions for alternative definitions of electromagnetic momentum are seen to destroy the conceptual simplicity of classical electrodynamics as revealed in the example.

The proper definition of the linear momentum in the electromagnetic field provides one of the recurring problems in physics. It appears most frequently in studies of the classical electron model in a vacuum. After more than a half century of use of the standard electromagnetic momentum density $\vec{g} = (1/4\pi c)\vec{E} \times \vec{B}$, several prominent textbook writers have called for a change. I believe this change is an error. In this paper the assembly of the classical electron is discussed in a simple example which clarifies the traditional Lorentz-transformation difficulties of the classical electron model and which again confirms the standard definition of the electromagnetic momentum density as the correct choice for classical electromagnetic theory.

The classical model of the electron consists of a spherically symmetric distribution of electric charge; for simplicity in this discussion, we will specialize the distribution to a thin spherical shell of radius a, total charge e, and mechanical mass m. The naive discussions of the classical model of the electron consider the mechanical and electromagnetic aspects of the model while completely ignoring the additional nonelectromagnetic forces, the Poincaré stresses, which stabilize the model. We are interested in clarifying the Lorentz-transformation difficulties of this naive view and hence will define our system to include only the mechanical and electromagnetic aspects; the nonelectromagnetic stabilizing forces are accordingly external to our system.

In the unprimed inertial frame S in which the spherical shell is at rest, the system, consisting of the shell mass and its electromagnetic fields, has a total energy

$$U_{\text{tot}} = U_{\text{mech}} + U_{\text{em}} = mc^2 + e/2a$$
 (1)

consisting of the mechanical rest energy $U_{\text{mech}} = mc^2$ and the electromagnetic energy

$$U_{\rm em} = \frac{1}{8\pi} \int d^3 r (E^2 + B^2) = \frac{e^2}{2a}$$
 (2)

in the electrostatic field. The mass of the sphere is at rest and there is no magnetic field, $\vec{B}=0$, so that the momentum vanishes: $\vec{P}_{tot}=\vec{P}_{mech}+\vec{P}_{em}=0$.

We now wish to examine this same system from a second primed inertial frame S' moving with velocity $-\vec{V} = -i\vec{V}$ relative to S so that the shell moves with velocity $+\vec{V}$ relative to S'. If we use the traditional definition $\vec{p} = m\gamma\vec{v}$ with $\gamma = (1 - v^2/c^2)^{-1/2}$ for the momentum associated with the mechanical mass and the usual definition $\vec{g} = (1/4\pi c)\vec{E} \times \vec{B}$ for the density of momentum of the electromagnetic field, then here the total momentum of our system in S' is

$$\vec{\mathbf{P}}'_{\text{tot}} = \vec{\mathbf{P}}'_{\text{mech}} + \vec{\mathbf{P}}'_{\text{em}}$$

$$= m\gamma \vec{\mathbf{V}} + (1/4\pi c) \int d^3x' (\vec{\mathbf{E}}' \times \vec{\mathbf{B}}') . \qquad (3)$$

The evaluation of the integral for the electromagnetic momentum is carried out in the Appendix and yields

$$\vec{\mathbf{P}}_{\text{em}}' = (1/4\pi c) \int d^3x' (\vec{\mathbf{E}}' \times \vec{\mathbf{B}}')$$

$$= \frac{4}{3} \vec{\mathbf{V}} \gamma U_{\text{em}} / c^2 , \qquad (4)$$

where $U_{\rm em}=e^2/2a$ is the electrostatic energy in (2). Now if we expected the energy $U_{\rm em}$ and the momentum $\vec{P}_{\rm em}$ in the electromagnetic field to be a Lorentz four-vector, then we would anticipate

from a Lorentz transformation between S and S'

$$\vec{P}_{\rm em}' = \vec{V} \gamma U_{\rm em} / c^2 . \tag{5}$$

Clearly the discrepancy in the factor of $\frac{4}{3}$ between the expressions of Eqs. (4) and (5) frustrates this expectation. Why is that $\frac{4}{3}$ there? What is involved? Should we redefine the density of electromagnetic field momentum so as to remove the factor of $\frac{4}{3}$?

The problem of the factor of $\frac{4}{3}$ appearing in Eq. (4) is an old one.³ It has been approached from a number of points of view, but apparently never from the assembly of the classical electron which is for me the simplest and clearest. Accordingly, a simple example of the assembly of a charged spherical shell as seen in two different inertial frames is outlined below.

The assembly of the classical model of the electron is imagined in terms of a thin spherical shell of total mechanical mass m and charge e sent rushing inwards from spatial infinity with the initial kinetic energy $mc^2(\gamma_v - 1)$ at spatial infinity equal to the final electrostatic potential energy $U_{\rm em} = e^2/2a$. Since the shell is perfectly spherically symmetric, there is no radiation loss and all the initial kinetic energy at spatial infinity is converted into electrostatic potential energy when the shell comes momentarily to rest at radius a. Just at this instant when the spherical shell comes to rest, the stabilizing forces are applied. These forces prevent the reexpansion of the shell. The external forces are applied simultaneously at zero velocity and hence transfer neither energy nor momentum to the spherical shell. We have thus assembled our classical electron as a thin-shell charge of energy

$$U_{\rm tot} = mc^2 + e^2/2a$$

and vanishing momentum \vec{P}_{tot} =0.

The above description of the assembly of the classical electron is given from the point of view of an observer in the frame S in which the total momentum of the electron is zero. Let us view the same assembly process from the primed frame S' moving with velocity $-\vec{V}=-\hat{i}V$ relative to the initial frame S. When the massive charged shell has infinite radius, the electric and magnetic fields \vec{E}' , \vec{B}' vanish, and all the particle energy and momentum is that associated with mechanical mass. Now the behavior of noninteracting mechanical mass is well known in special relativity, and the energy and momentum transform as a Lorentz four-vector. Hence, initially the system momentum, which is all mechanical momentum, is given by

$$\vec{P}'_{\text{tot}} = \vec{P}'_{\text{mech}}(t' \rightarrow -\infty) = \vec{V} \gamma U_{\text{tot}}/c^2$$
.

As time passes the electromagnetic fields increase from their initial zero values and part of the mechanical momentum is converted into electromagnetic momentum. However, since there are no external forces on the system for times less than some t'_s , the total momentum is conserved and

$$\vec{\mathbf{P}}'_{\text{tot}} = \vec{\mathbf{P}}'_{\text{mech}} + \vec{\mathbf{P}}'_{\text{em}}$$

$$= \vec{\mathbf{V}} \gamma U_{\text{tot}} / c^2, \quad t' < t'_{\delta} ; \qquad (6)$$

the proper Lorentz transformation properties still hold. The crucial change comes when the external stabilizing forces are applied beginning at $t'=t'_{\delta}$. In the frame S these stabilizing forces are applied simultaneously; consequently the net external force on the system vanishes and there is no change in the momentum of the system. Contrastingly in the S' frame the external stabilizing forces are applied at different times to different parts of the spherical shell. Thus starting with the application of the first force and until the moment in the S' frame when all the external forces have been applied, there is a net external force on the shell, and hence net momentum is transferred to the shell. The total momentum of the shell is thus increased from the value

$$\vec{P}'_{tot} = \vec{V} \gamma U_{tot} / c^2$$

which held before the external forces were applied. The change in momentum $\Delta \vec{P}'$ of the charge shell as seen in the S' frame is equal to the net impluse \vec{I}' delivered by the external stabilizing forces as seen in the S' frame. The net impulse \vec{I}' can be computed as in the Appendix with the value for $\Delta \vec{P}' = \vec{I}'$ given by

$$\Delta \vec{\mathbf{P}}' = \frac{1}{3} \vec{\mathbf{V}} \gamma U_{\rm em} / c^2 . \tag{7}$$

But this is precisely the discrepancy associated with the factor of $\frac{4}{3}$. The total system momentum $\vec{P}_{\text{tot}}^{\prime(\text{after})}$ after all the external stabilizing forces have been applied has been changed in the S' frame from the value in Eq. (6) over to

$$\vec{\mathbf{P}}_{\text{tot}}^{\prime (\text{after})} = \vec{\mathbf{V}} \gamma U_{\text{tot}} / c^2 + \frac{1}{3} \vec{\mathbf{V}} \gamma U_{\text{em}} / c^2$$

$$= \vec{\mathbf{V}} \gamma m + \frac{4}{3} \vec{\mathbf{V}} \gamma U_{\text{em}} / c^2$$
(8)

corresponding to the momentum of the mechanical mass m and exactly the electromagnetic momentum (4) involving the integral over the traditional field momentum density

$$\vec{g}' = (1/4\pi c)\vec{E}' \times \vec{B}'$$
.

The factor of $\frac{4}{3}$ in the electromagnetic momentum is by no means extraneous; it is needed crucially to maintain the validity of the force-momentum balance in the S' frame.

A physical particle or system will in general involve contributions to the total momentum from both the electromagnetic fields and other sources. In our example the mechanical momentum of the shell at spatial infinity is converted into electromagnetic momentum as the shell rushes inward. As Poincaré pointed out in 1906 only the total energy and momentum can be expected to satisfy covariant behavior when transformed between different inertial frames.

Various authors⁴ have taken a view which is opposite to that expressed here and have suggested that the factor of $\frac{4}{3}$ above is an embarrassment which should be removed. One method for removing the factor involves redefining the electromagnetic momentum of the system so that it is not the integral of the density

$$\vec{\mathbf{g}} = (1/4\pi c)\vec{\mathbf{E}} \times \vec{\mathbf{B}}$$

as used above, but rather is⁵

$$\vec{\mathbf{P}}_{em} = (\gamma/4\pi c) \int d^3x \left[\vec{\mathbf{E}} \times \vec{\mathbf{B}} + \vec{\mathbf{v}} \cdot \vec{\mathbf{E}} \vec{\mathbf{E}} + \vec{\mathbf{v}} \cdot \vec{\mathbf{B}} \vec{\mathbf{B}} \right] - \frac{1}{2} \vec{\mathbf{v}} (E^2 + B^2) , \qquad (9)$$

where

$$\gamma = (1 - v^2/c^2)^{-1/2}$$

and \vec{v} is the velocity of the inertial frame relative to some preferred inertial frame.

This redefinition, I believe, is an error. The usual ideas of force, energy, and momentum hold together properly with the traditional definition and not with the use of the density function given in Eq. (9) which eliminates the factor of $\frac{4}{3}$. The example given above is one illustration of this; if the laws of physics are to hold for all inertial frames in this open system in which nonelectromagnetic external forces are applied, then the electromagnetic field momentum should not transform as a Lorentz four-vector and the factor of $\frac{4}{3}$ is a consistent reflection of this fact. My opinion is that these other authors err in taking seriously as a model for a point charged particle the electromagnetic energy and momentum behavior of the classical model of the electron despite the nonelectromagnetic forces required for the classical model's stability. The nonelectromagnetic stabilizing forces play a crucial role and the attempts to circumvent the role played by these forces by redefining the electromagnetic momentum density only destroy the conceptual simplicity of the traditional view of classical electrodynamics.

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APPENDIX

1. Electromagnetic momentum for a spherical charge shell

The fields \vec{E}' and \vec{B}' needed in the integrand of Eq. (4) are easily found by Lorentz transformation⁶ from the electrostatic fields in the S frame. Also if we change the variables of integration from x', y', z' at fixed time t' over to x, y, z at t', and use the spherical symmetry of the fields in S to replace $E_y^2 + E_z^2$ by $\frac{2}{3}E^2$, then we have

$$\vec{\mathbf{P}}_{\text{em}}' = (1/4\pi c) \int d^3x' (\vec{\mathbf{E}}' \times \vec{\mathbf{B}}')$$

$$= (\hat{i}/4\pi c) \int (d^3x/\gamma) (V\gamma^2/c) (E_y^2 + E_z^2)$$

$$= \frac{4}{3} \vec{\mathbf{V}} \gamma U_{\text{em}}/c^2 , \qquad (A1)$$

where $U_{\rm em} = e^2/2a$ is the electrostatic energy in Eq. (2).

2. Net impulse of the external forces

The external forces applied at time t_0 in the S frame are exactly such as to balance the electrostatic forces of the sphere on itself:

$$f_{\text{ext}}^{\mu}(t,\vec{\mathbf{r}}) = -f_{\text{em}}^{\mu}(t,\vec{\mathbf{r}})\theta(t-t_0) , \qquad (A2)$$

where f^{μ} stands for the force density and $\theta(t-t_0)$ is the unit step function. The electromagnetic force density $f_{\rm em}^{\mu}(t,\vec{r})$ can be obtained from the symmetric electromagnetic stress-energy-momentum tensor $f_{\rm em}^{\mu}=-\partial_{\nu}\Theta_{\rm em}^{\mu\nu}$, where $\Theta_{\rm em}^{\mu\nu}$ involves simply the electrostatic field

$$\vec{E} = \theta(r-a)e\vec{r}/r^3$$
.

Thus it follows that

$$f_{\rm em}^{\mu} = (0, (e/4\pi a^2)\delta(r-a)e\hat{r}/2a^2)$$
 (A3)

The force density at a space-time point is a Lorentz four-vector which in the S' frame has three-components

$$f'_{\text{ext}x} = \gamma f_{\text{ext}x}, \quad f'_{\text{ext}y} = f_{\text{ext}y},$$

$$f'_{\text{ext}z} = f_{\text{ext}z}.$$
(A4)

By symmetry it is clear that the net impulse $\vec{\mathbf{I}}$ 'has a component only in the x direction parallel to the relative velocities of the frames. Thus the resultant impluse $\vec{\mathbf{I}}$ ' (t'_*) delivered by the external forces to the shell as measured in the S' frame is

$$\vec{\mathbf{I}}'(t'_{*}) = \hat{i} \int_{t'=-\infty}^{t'=t'_{*}} dt' \int d^{3}x' f'_{\text{ext}x}(t', \vec{\mathbf{r}}') .$$
(A5)

Now using the Lorentz invariance of the spacetime volume element $dt'd^3x' = dt d^3x$, the Lorentz transformations for the coordinates, and the expressions (A2), (A3) and (A4), the integral for $\vec{l}'(t'_*)$ becomes

$$\vec{I}'(t'_{*}) = -\hat{i} \int d^{3}x \int_{t=-\infty}^{t=t'_{*}/\gamma - Vx/c^{2}} dt \, \gamma \theta(t-t_{0})$$

$$\times \delta(r-a)e^{2}x / 8\pi a^{5} . \tag{A6}$$

If the time t'_* is sufficiently large that all the external forces have been applied, then the integration becomes

$$\vec{\mathbf{I}}'(t'_{*}) = -\hat{i}\gamma \int_{0}^{\infty} r^{2}dr \int_{\theta=0}^{\pi} d\theta \sin\theta \int_{\phi=0}^{2\pi} d\phi \int_{t=0}^{t=t_{*}/\gamma - V_{r}\cos\theta/c^{2}} dt \, \delta(r-a)\cos\theta e^{2}/8\pi a^{4}$$

$$= -\hat{i}\gamma a^{2} \int_{\theta=0}^{\pi} d\theta \sin\theta 2\pi \left[\frac{t_{*}}{\gamma} - \frac{Va\cos\theta}{c^{2}} \right] \cos\theta \frac{e^{2}}{8\pi a^{4}}$$

$$= \frac{1}{3} \vec{\mathbf{V}}\gamma e^{2}/2ac^{2} \tag{A7}$$

as required for Eq. (7).

Note added. My analysis above was written with two aims; first to provide a simple model for the formation of the classical electron model which I believe sharply clarifies the famous factor of $\frac{4}{3}$, and second to suggest that the example illustrates the validity of the traditional definition for momentum in the classical electromagnetic field and the inappropriateness of the new definition which is creeping into the advanced-textbook literature.⁸

My views are not shared by Professor F. Rohrlich. His rebuttal to my discussion appears in the following paper.⁹

It should be noted immediately that neither Professor Rohrlich nor I now disputes the accuracy of the other's calculations; at least I believe this is so. I do differ with Professor Rohrlich on two assertions of his reply (following paper⁹) and with his conclusion on the definition of electromagnetic momentum providing greatest conceptual clarity.

In the abstract to his article⁹ Professer Rohrlich states: "The fundamental question is whether electromagnetic interactions can be separated from nonelectromagnetic ones in a Poincaré-invariant way. This question is answered in the affirmative." For me this is not at all the fundamental question. By suitable redefinitions in relatively

moving frames, any quantity can be made Poincaré covariant, and Professor Rohrlich does this for the electromagnetic field momentum. I believe the fundamental question is what definitions are physically natural and conceptually useful. This difference in perspective may be one ground for the disagreement between Professor Rohrlich and me.

In the body of the article Professor Rohrlich writes: "It must be emphasized that the separation (7) of the momentum into an electromagnetic and nonelectromagnetic part is not an observable separation but serves the convenience of the theory. It corresponds to the separation of the observed mass into an electromagnetic and nonelectromagnetic part." In my view this comment is appropriate for a system, such as a point charge, which cannot be regarded as composed of constituent pieces, but it is completely inappropriate for composite systems, such as colliding point charges. My strong impression is that Professor Rohrlich is always writing with the former example in mind and never from the more general perspective, and on this account he arrives at a conclusion different from my own.

If we look at the discussions provided by Professor Rohrlich and me, we see immediately that we are not discussing the same model but rather different ones. I assemble the charged sphere by

sending a massive charged shell rushing inward from infinite radius. Before the application of the external stabilizing forces, the total energymomentum $P_{\text{tot}}^{\mu} = P_{\text{mech}}^{\mu} + P_{\text{em}}^{\mu}$ is a four-vector where the mechanical and electromagnetic momentum in any Lorentz frame have their natural definitions at a single time in that frame. Neither the mechanical part nor the electromagnetic part is separately a four-vector. This is just as in the collision between point charges where the total energy-momentum is a four-vector but we do not expect mechanical and electromagnetic energymomentum to form separate four-vectors. I show that the ideas of momentum balance fit beautifully and naturally with the traditional definition of momentum in the classical electromagnetic field.

In contrast Professor Rohrlich assembles his sphere quasistatically. Thus, as he states above his Eq. (8), for him the mechanical momentum P_m^{μ} is separated and assumed to be a four-vector by itself. Thus Professor Rohrlich never discusses any interplay between mechanical momentum and electromagnetic momentum, but rather only the interplay between electromagnetic momentum and nonelectromagnetic forces where the unnaturalness of his definition of electromagnetic momentum for composite systems is not fully exposed. I believe the unnaturalness is easily exposed if we think in terms of Poynting's theorem.

Classical electromagnetism is a theory of consid-

erable detail and beauty to which Professor Rohrlich has contributed significantly. In particular, classical electromagnetism allows the use of nonelectromagnetic external forces and nonelectromagnetic masses which are connected with the energy and momentum of the classical electromagnetic fields through Poynting's theorem¹⁰ and its momentum analog¹¹ when using the traditional defintions of energy and momentum. One of the striking illustrations¹² of Poynting's theorem involves charged particles passing each other with arbitrary constant velocities, $v_i < c$. The nonelectromagnetic external forces, which are required to balance the interparticle Lorentz forces and so keep the particles moving with constant velocity, do not satisfy Newton's third law. Rather the work done by the external forces, the impulse supplied by the external forces, and the angular impulse supplied by the external forces lead exactly as a relativistic calculation with no approximation in every Lorentz frame to the appropriate changes of energy, linear momentum, and angular momentum in the electromagnetic field when the traditional definitions are made for the energy, momentum, and angular momentum in the electromagnetic field. I believe the conceptual simplicity of the traditional definitions of classical electrodynamics is given yet another striking illustration above in my example of the assembly of the classical model of the electron.

¹Discussions of the electromagnetic momentum in connection with the classical model of the electron appear in the following: H. A. Lorentz, *The Theory of Electrons*, 2nd ed. (Dover, New York, 1952), Secs. 24—28 (this is a republication of the 1915 edition); E. Fermi, Z. Phys. 24, 340 (1922); W. Wilson, Proc. Phys. Soc. London A48, 376 (1936); B. Kwal, J. Phys. Radium 10, 103 (1949); F. Rohrlich, Am. J. Phys. 28, 639 (1960); Phys. Today 15, 19 (1962); Am. J. Phys. 34, 987 (1966); 38, 1310 (1970); J. W. Zink, *ibid*. 34, 211 (1966); 36, 639 (1968); 39, 1403 (1971); J. W. Butler, *ibid*. 37, 1258 (1969); R. Benumof, *ibid*. 39, 392 (1971).

²F. Rohrlich, Classical Charged Particles (Addison-Wesley, Reading, Mass., 1965), Sec. 6-3; J. D. Jackson, Classical Electrodynamics, 2nd ed. (Wiley, New

York, 1975), Sec. 17.5

³Apparently the factor of $\frac{4}{3}$ was found first by J. J. Thomson in 1881. See Rohrlich's account in Chap. 2 of the work listed in Ref. 2.

⁴See Ref. 2 and the articles by Rohrlich and Butler in Ref. 1.

⁵See, for example, F. Rohrlich, Am. J. Phys. <u>38</u>, 1310 (1970), Eq. (3.24).

⁶See Jackson in Ref. 2, p. 552, Eq. (11.148).

⁷See Jackson in Ref. 2, Section 12.10b.

⁸See Jackson in Ref. 2, pp. 792-796.

⁹F. Rohrlich, following paper, Phys. Rev. D <u>25</u>, 3251 (1982).

¹⁰See Jackson in Ref. 2, pp. 236-237.

¹¹See Jackson in Ref. 2, pp. 237-239.

¹²T. H. Boyer, Am. J. Phys. <u>39</u>, 257 (1971).

Comment on the preceding paper by T. H. Boyer

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It is shown that the proposed new noncovariant way of calculating the electromagnetic energy and momentum of a classical moving charged sphere is neither conceptually simpler nor physically acceptable. The fundamental question is whether electromagnetic interactions can be separated from nonelectromagnetic ones in a Poincaré-invariant way. This question is answered in the affirmative.

Theorists have been pondering the structure of the electron long before quantum mechanics came into existence, and in fact already in prerelativistic times. The classical models of the electron proposed by Abraham and Lorentz near the turn of the century considered the possibility that the electron is of purely electromagnetic nature. That hope has long since been abandoned. However, while the lack of a full understanding of the stability and self-energy of the electron persists to the present day, much of it is now well understood.¹

The preceding paper by Boyer² raises some questions that have been settled some time ago: whether the electromagnetic energy and momentum of the Coulomb field surrounding a charged particle are or are not the components of a four-vector. Since only uniformly moving charges are considered, radiation fields do not enter the discussion. The uniformly moving charge then carries only the (generalized) Coulomb field which is the Lorentz-transformed static Coulomb field.

In that paper (in the following referred to as CME) it is proposed to define the electromagnetic energy and momentum densities of the (generalized) *Coulomb* field as (we use c=1 and Gaussian units as in CME)

$$U = \frac{1}{8\pi} (E^2 + B^2) \text{ and } \vec{S} = \frac{1}{4\pi} \vec{E} \times \vec{B}$$
 (1)

in every inertial frame such that the total energy and momentum due to that field are

$$P_e^0 = \int d^3x U$$
 and $\vec{P}_e = \int d^3x \vec{S}$. (2)

For Coulomb fields these do not transform as the components of a four-vector. Equations (1) and (2) are known to be valid for radiation fields where they do transform as components of a four-vector; they are also used in nonrelativistic macroscopic Maxwell theory for open systems; and they date from prerelativistic days.

Two claims are made in CME: (a) that these equations are demanded by a consideration of the cohesive forces that are needed to prevent a charged sphere from expanding, and (b) that these equations lead to a conceptually simpler theory than the expressions that are used to define a *four-vector* of Coulomb energy and momentum.^{3,4} The present paper proposes to show that both these claims are unwarranted.

The model of this classical charged particle is a sphere of radius a, mass m, and uniformly distributed surface charge e. As a free object it is a closed system that has a total energy P^0 and momentum \vec{P} which transform as components of a four-vector. If the entire particle were expressible by means of a field and an associated energy tensor $\Theta^{\mu\nu}$ such a tensor would necessarily have to satisfy

$$\partial_{\alpha}\Theta^{\alpha\mu} = 0 \tag{3}$$

since the system is closed. The momentum defined by

$$P^{\mu} = \int_{-\pi}^{\pi} d^3 \sigma_{\alpha} \Theta^{\alpha \mu}(x) \tag{4}$$

would therefore be independent of the choice of the spacelike surface σ .

The particle however is not purely electromagnetic but contains an electromagnetic component (the Coulomb field) and a nonelectromagnetic one. We shall accept the usual assumption that these two components are additive in the energy tensors,

$$\Theta^{\mu\nu} = \Theta^{\mu\nu}_e + \Theta^{\mu\nu}_n \ . \tag{5}$$

Neither of the two components of $\Theta^{\mu\nu}$ are separately conserved,

$$\partial_{\alpha}\Theta_{e}^{\alpha\mu} = -\partial_{\alpha}\Theta_{n}^{\alpha\mu} \neq 0. \tag{6}$$

This means that the decomposition of P^{μ} into P_e^{μ} and P_n^{μ} ,

$$P^{\mu} = \int_{\sigma} d^{3}\sigma_{\alpha} \Theta_{e}^{\alpha\mu} + \int_{\sigma} d^{3}\sigma_{\alpha} \Theta_{n}^{\alpha\mu}$$
$$\equiv P_{e}^{\mu} + P_{n}^{\mu} , \qquad (7)$$

involves two surface integrals which are *not* separately independent of σ . But the sum is independent of σ as long as the same σ is chosen in both integrals. Of special interest will be two choices of σ :

(I) σ is the surface t = const in the inertial system of the observer. Each observer has his own surface σ .

(II) σ is the surface t_R =const in the (inertial) rest system of the particle. All observers agree to use that surface in (7). It must be emphasized that the separation (7) of the momentum into an electromagnetic and nonelectromagnetic part is not an observable separation but serves the convenience of the theory. It corresponds to the separation of the observed mass into an electromagnetic and a nonelectromagnetic part.

A macroscopic charged sphere would be described by an energy tensor only for its electromagnetic fields. The nonelectromagnetic component would be described by a force density $f^{\mu}(x)$. In CME this component is broken up into two parts: a "mechanical" part leading to a momentum P_m^{μ} and a part describing the cohesive forces that prevent the charged sphere from expanding. The part f_{coh}^{μ} is just the force density that provides the Poincaré stresses.⁵ It is not an external force as stated in CME (end of its second paragraph) and is in fact not physically separable from the rest of the nonelectromagnetic components in a classical macroscopic body. Without its inclusion the physical charged particle cannot possibly be proven to have a momentum (4) that is a four-vector.

If the momentum P_m^{μ} is separated and assumed to be a four-vector by itself (as done in CME) the local conservation law (3) is reduced to

$$\partial_{\alpha}\Theta_{e}^{\alpha\mu} + f_{\rm coh}^{\mu} = 0. \tag{8}$$

For the sake of argument we follow the scenario of CME where the charged sphere is produced by contraction of an infinite sphere but apply the stabilizing f_{coh}^{μ} at all times, contracting adiabatically to r=a. This ensures a closed system giving

$$P^{\mu} = P_{m}^{\mu} + P_{e}^{\mu} + P_{\text{coh}}^{\mu} , \qquad (9)$$

$$P_e^{\mu} = \int_{\sigma} d^3 \sigma_a \Theta_e^{\alpha \mu}$$
, $P_{\text{coh}}^{\mu} = -\int_{V_{4,\sigma}} d^4 x f_{\text{coh}}^{\mu}$.

(10)

The integral for P_{coh}^{μ} is to be taken over a four-dimensional volume that extends from the space-like surface σ into $-\infty$.⁶ As emphasized before, the two σ in P_e^{μ} and P_{coh}^{μ} must be the same.

If one now makes the choice (I) as is proposed in CME, one obtains for the system S in which the particle moves with velocity \vec{v} the following. The electromagnetic momentum is as in CME

$$P_e^0 = \int d^3x U = \gamma m_e (1 + \frac{1}{3} \vec{\mathbf{v}}^2) ,$$

$$\vec{\mathbf{P}}_e = \int d^3x \vec{\mathbf{S}} = \frac{4}{3} \gamma m_e \vec{\mathbf{v}} ,$$
(I) (11)

where⁷

$$m_e = \int d^3x_R \, U_R = \frac{e^2}{2a} \ . \tag{12}$$

Thus, P_e^{μ} is *not* a four-vector. This is not surprising since each observer S chooses a different σ , and P_e^{μ} depends on σ .

In the rest frame f_{coh}^{μ} is we shall drop the subscript coh on f_{coh}^{μ} from here on

$$f_R^0 = 0, \quad \vec{\mathbf{f}}_R = -2\pi\sigma^2 \hat{r} \delta(r - a) ,$$

$$\sigma = \frac{e}{4\pi a^2}$$
(13)

as also given in CME. The evaluation of P_{coh}^{μ} in (10) is now done by transforming from S back to S_R . If L is the Lorentz transformation that maps S_R to S then we have

$$\begin{split} P_{\mathrm{coh}}^{0} &= -\int_{V_{4},\sigma} d^{4}x f^{0} \\ &= -\int_{V_{4},L^{-1}\sigma} d^{4}x_{R} \gamma (f_{R}^{0} - \overrightarrow{\mathbf{v}} \cdot \overrightarrow{\mathbf{f}}_{R}) \\ &= -\frac{1}{3} m_{e} \gamma \overrightarrow{\mathbf{v}}^{2} \;, \end{split}$$

$$\begin{split} \vec{\mathbf{P}}_{\mathrm{coh}} &= -\int_{V_4,\sigma} d^4x \; \vec{\mathbf{f}} \\ &= -\int_{V_4,L^{-1}\sigma} d^4x_R (\gamma \vec{\mathbf{f}}_R^{\parallel} + \vec{\mathbf{f}}_R^{\perp} - \gamma \vec{\mathbf{v}} f_R^0) \\ &= -\frac{1}{3} m_e \gamma \vec{\mathbf{v}} \; . \end{split}$$

In the notation $P^{\mu} = (P^0, \vec{P})$, therefore,

$$P_{\text{coh}}^{\mu} = -\frac{1}{3} m_e \gamma(\vec{\mathbf{v}}^2, \vec{\mathbf{v}}) \quad (\mathbf{I})$$

and with (11)

$$P_e^{\mu} + P_{\text{coh}}^{\mu} = \gamma m_e(1, \vec{\mathbf{v}}) = m_e v^{\mu}$$
. (I)

This is the result obtained in CME in slightly different form. It is argued there that the fact that the non-four-vector of cohesive momentum thus obtained just compensates the non-four-vector of electromagnetic momentum and yields a sum which is a four-vector justifies the choice of surface (I). Our presentation shows that this choice (I) is one of the arbitrary choices one can make, each choice giving a different unobservable separation of $m_e v^{\mu}$ into P_e^{μ} and P_{coh}^{μ} .

We now repeat this calculation for the choice (II), where P_e^{μ} involves an integration over $\sigma = L \sigma_R$:

$$\begin{split} P_e^0 &= \int_{L\sigma_R} d^3\sigma_\alpha \Theta_e^{\alpha 0} = \int d^3x_R \gamma (U - \vec{\mathbf{v}} \cdot \vec{\mathbf{S}}) = \gamma m_e \ , \\ P_e^k &= \int d^3\sigma_\alpha \Theta_e^{\alpha k} = \int d^3x_R \gamma (S^k + v_l \Theta_e^{lk}) = \gamma m_e v^k \ . \end{split}$$

Since this calculation exists only in either nonrelativistic approximation⁹ or in a didactic context in rather complicated form, ¹⁰ the details are shown in the Appendix. They were unfortunately omitted in Ref. 3, p. 90.

The above components lead to

$$P_e^{\mu} = m_e v^{\mu} , \quad (\text{II}) \tag{16}$$

which is a four-vector. This is also not surprising since all observers use the same reference plane σ_R and integrate over it as they see it.

We next evaluate P_{coh}^{μ} using the choice (II). With (13)

$$\begin{split} P_{\text{coh}}^{0} &= -\int_{V_{4},L\sigma_{R}} d^{4}x f^{0} \\ &= -\int_{V_{4},\sigma_{R}} d^{4}x_{R} \gamma (f_{R}^{0} - \vec{\mathbf{v}} \cdot \vec{\mathbf{f}}_{R}) = 0 , \\ \vec{\mathbf{P}}_{\text{coh}} &= -\int_{V_{4},L\sigma_{R}} d^{4}x \vec{\mathbf{f}} \\ &= -\int_{V_{4},\sigma_{R}} d^{4}x_{R} (\gamma \vec{\mathbf{f}}_{R}^{\parallel} + \vec{\mathbf{f}}_{R}^{\perp} - \gamma \vec{\mathbf{v}} f_{R}^{0}) \\ &= 0 ; \end{split}$$

the integrals vanish term by term so that

$$P_{\mathrm{coh}}^{\mu} = 0 \tag{17}$$

and the cohesive forces contribute nothing to the momentum and energy of the particle. They give (trivially) a four-vector. The choice II permits one to ignore them in most cases.

From this calculation one concludes that the choice (II) is the simpler choice both conceptually and formally. In addition there are very good reasons to have an electromagnetic energy-momentum four-vector (16) rather than the expressions (11). These are basically that one wants to be able to formulate a theory of electromagnetic interactions in a Poincaré-invariant way. This is not entirely possible on the classical level because of the cohesive forces which are necessarily nonelectromagnetic. But at least they do not need to spoil the four-vector character of P_e^μ . Indeed, both in

the Lorentz-Dirac theory and in quantum electrodynamics one uses four-vector momenta. All relativistic quantum field theories also give *Poincaréinvariant separations* between electromagnetic and nonelectromagnetic interactions.

Finally, one should note that a more careful study of P_e^{μ} on the quantum-mechanical level shows that in the point limit $a \rightarrow 0$, P_e^{μ} vanishes because m_e vanishes.¹¹ In that point limit therefore P_e^{μ} is trivially a four-vector.

Note added. In a note added to his paper Professor Boyer makes a third claim in favor of the choice I for the specification of σ in electromagnetic momenta: the choice II "is completely inappropriate for composite systems, such as colliding point charges." I shall demonstrate in the following that this claim is also incorrect by deriving the covariant integral Poynting theorem.

Consider a closed system of N point charges in mutual electromagnetic interaction. The electromagnetic energy tensor $\Theta_e^{\mu\nu}$ satisfies

$$\partial_{\alpha}\Theta_{e}^{\alpha\mu} = F^{\mu\alpha}j_{\alpha} , \qquad (18)$$

where j^{μ} is the sum of all point-charge current four-vector densities

$$j^{\mu}(x) = \sum_{a=1}^{N} j_{a}^{\mu}(x) ,$$

$$j_{a}^{\mu}(x) = e_{a} \int_{-\infty}^{\infty} \delta_{4}(x - z_{a}) v_{a}^{\mu} d\tau ;$$
(19)

 $z_a(\tau)$ and $v_a(\tau) = \dot{z}_a(\tau)$ are the position and velocity four-vectors of particle a. Equation (18) is the local form of Poynting's theorem.

One can integrate both sides of (18) over a fourdimensional volume between two spacelike planes σ_1 and σ_2 , later than σ_1 . Using Gauss's theorem (Ref. 3, p. 281),

$$\int \epsilon_{\sigma} d^3 \sigma_{\alpha} \Theta_e^{\alpha \mu} = \int d^4 x F^{\mu \alpha} j_{\alpha} .$$

Following the choice (I) for σ one has $d^4x = d^3x dt$. If the surfaces σ_1 and σ_2 are separated infinitesimally,

$$\frac{d}{dt} \int \epsilon_{\sigma} d^3 \sigma_{\alpha} \Theta_e^{\alpha \mu} = \int d^3 x F^{\mu \alpha} j_{\alpha} . \qquad (20)$$

Neither side of this equation is a four-vector. If, on the other hand, one uses choice II one has the invariant factorization $d^4x = d^3\sigma d\tau$ where

$$d^3\sigma = -d^3\sigma_{\mu}\hat{P}^{\mu} ,$$

 \hat{P}^{μ} being the unit vector in the direction of the total momentum of the closed system. One now obtains

$$\frac{d}{d\tau} \int \epsilon_{\sigma} d^3 \sigma_{\alpha} \Theta_e^{\alpha \mu} = \int d^3 \sigma F^{\mu \alpha} j_{\alpha}$$

$$= \sum_{\alpha=1}^{N} e_{\alpha} F^{\mu \nu} (z_{\alpha}) v_{\alpha \nu} . \qquad (21)$$

Both sides of this equation are four-vectors. Both (20) and (21) are integral forms of Poynting's theorem. Professor Boyer is willing to accept only the form (20). The manifestly covariant form, however, is (21). It is only the latter which is appropriate for a manifestly covariant formulation of the theory.

The explicit form of the left-hand sides of (20) and (21) are as follows: (20) gives the familiar result with

$$d^3\sigma^{\mu} = (d^3x, dtd^2\vec{\sigma})$$

in the notation used in (14) and (15):

$$\frac{d}{dt} \int d^3x \Theta_e^{0\mu} + \int d^2\sigma_k \Theta_e^{k\mu} . \tag{22}$$

The left side of (21) gives, with the covariant separation

$$(P_{\perp}^{\alpha\beta} = \eta^{\alpha\beta} + \hat{P}^{\alpha}\hat{P}^{\beta}) ,$$

$$d^{3}\sigma_{\parallel}^{\mu} = d^{3}\sigma\hat{P}^{\mu} , d^{3}\sigma_{\perp}^{\mu} = d\tau d^{3}\sigma_{\beta}P_{\perp}^{\beta\mu} ,$$

the less familiar covariant result

$$-\frac{d}{d\sigma}\int d^3\sigma \hat{P}_{\alpha}\Theta_e^{\alpha\mu} + \int d^2\sigma^{\beta}P_{\beta\alpha}^{\perp}\Theta_e^{\alpha\mu} \ . \tag{23}$$

It reduces to (22) in the rest frame of the system. (21) and (23) give the integral Poynting theorem in covariant form.

APPENDIX

A well-known Lorentz boost from the rest frame transforms \vec{E}_R , $\vec{B}_R = 0$ into

$$\vec{\mathbf{E}}^{\parallel} = \vec{\mathbf{E}}_{R}^{\parallel} , \quad \vec{\mathbf{E}}^{\perp} = \gamma \vec{\mathbf{E}}_{R}^{\perp} ,$$

$$\vec{\mathbf{B}}^{\parallel} = 0 , \quad \vec{\mathbf{B}}^{\perp} = \gamma \vec{\mathbf{v}} \times \vec{\mathbf{E}}_{R}^{\perp} .$$
(A1)

The superscripts || and \bot refer to vectors parallel and perpendicular to \vec{v} . Since

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$$E_R^{12} = E_R^2 - E_R^{\parallel 2}$$
,
 $(\vec{\mathbf{v}} \times \vec{\mathbf{E}}_R)^2 = \vec{\mathbf{v}}^2 (E_R^2 - E_R^{\parallel 2})$,
 $E_R^{\parallel 2} = \frac{1}{2} E_R^2$,

we have

$$8\pi U = E^2 + B^2 = E_R^{||2} + \gamma^2 E_R^{||2} + \gamma^2 (\vec{\mathbf{v}} \times \vec{\mathbf{E}}_R)^2$$
$$= E_R^2 \gamma^2 (1 + \frac{1}{3} \vec{\mathbf{v}}^2) .$$

If we define

$$m_e = \frac{1}{8\pi} \int d^3x_R E_R^2$$
, (A2)

then

$$\int Ud^3x_R = m_e \gamma^2 (1 + \frac{1}{3} \vec{\mathbf{v}}^2) . \tag{A3}$$

Similarly,

$$4\pi \vec{\mathbf{S}} = (\vec{\mathbf{E}}_R^{\parallel} + \gamma \vec{\mathbf{E}}_R^{\perp}) \times (\vec{\mathbf{v}} \times \vec{\mathbf{E}}_R^{\perp}) \gamma$$
$$= \gamma^2 \vec{\mathbf{v}} E_R^{\perp 2} - \gamma |\vec{\mathbf{v}}| E_R^{\parallel} \vec{\mathbf{E}}_R^{\perp}.$$

The last term integrates to zero so that

$$\int \vec{S}d^3x_R = \frac{4}{3}\gamma^2 m_e \vec{V} . \tag{A4}$$

Finally, using the result obtained for U, the dyadic Θ gives

$$4\pi \vec{\Theta} \cdot \vec{\mathbf{v}} = [\vec{\mathbf{E}}\vec{\mathbf{E}} + \vec{\mathbf{B}}\vec{\mathbf{B}} - \frac{1}{2}\vec{\mathbf{1}}(E^2 + B^2)] \cdot \vec{\mathbf{v}}$$
$$= (\vec{\mathbf{E}}_R^{\parallel} + \gamma \vec{\mathbf{E}}_R^{\perp})E_R^{\parallel} |\vec{\mathbf{v}}| - \frac{1}{2}\vec{\mathbf{v}}E_R^2\gamma^2(1 + \frac{1}{3}\vec{\mathbf{v}}^2).$$

The $\vec{\mathbf{E}}_R^{\perp} E_R^{\parallel}$ term integrates again to zero. The remainder is

$$\vec{\mathbf{v}} \left[\frac{1}{3} E_R^2 - \frac{1}{2} E_R^2 \gamma^2 (1 + \frac{1}{3} \vec{\mathbf{v}}^2) \right] = -\vec{\mathbf{v}} E_R^2 \left(\frac{1}{6} \gamma^2 + \frac{1}{2} \gamma^2 \vec{\mathbf{v}}^2 \right) .$$

Thus,

$$\int \vec{\Theta} \cdot \vec{\mathbf{v}} d^3 x_R = -m_e \vec{\mathbf{v}} \gamma^2 (\frac{1}{3} + \vec{\mathbf{v}}^2) . \tag{A5}$$

ley, New York, 1975).

⁵H. Poincaré, Rend. Circ. Mat. Palermo <u>21</u>, 129 (1906); see also Ref. 4, p. 792 ff.

⁶If there existed a $\Theta_{\text{coh}}^{\mu\nu}$ so that $f_{\text{coh}}^{\mu} = \partial_{\alpha}\Theta_{\text{coh}}^{\alpha\mu}$ as in field theory, then

$$-\int d^4x f^{\mu}_{\rm coh} = \int d^3\sigma_{\alpha}\Theta^{\alpha\mu}_{\rm coh}$$

since $\Theta_{\rm coh}^{\mu\nu} = 0$ on the surface at $t = -\infty$.

⁷For the sake of clarity we use a subscript R to indicate

¹For a review see F. Rohrlich, in *The Physicist's Conception of Nature*, edited by J. Mehra (Reidel, Dordrecht-Holland, 1973); C. Teitelboim, D. Villarroel, and Ch. G. Van Weert, Riv. Nuovo Cimento 3, 1 (1980).

²T. H. Boyer, preceding paper, Phys. Rev. D. <u>25</u>, 3246 (1982). This paper will be referred to as CME.

³F. Rohrlich, Classical Charged Particles (Addison-Wesley, Reading, Mass., 1965).

⁴J. D. Jackson, Classical Electrodynamics, 2nd ed. (Wi-

the rest frame, S_R . Quantities without that subscript refer to S in which the particle moves uniformly.

8See for example Ref. 3, Eq. (6-5) where there is a factor $\frac{1}{2}$ missing.

⁹F. Rohrlich, Am. J. Phys. <u>28</u>, 639 (1960).

¹⁰R. Benumof, Am. J. Phys. <u>39</u>, 392 (1971).
¹¹H. Grotch, E. Kazes, F. Rohrlich, and D. H. Sharp, Acta Phys. Austriaca, <u>54</u>, 31 (1982); E. J. Moniz and D. H. Sharp, Phys. Rev. D <u>15</u>, 2850 (1977).