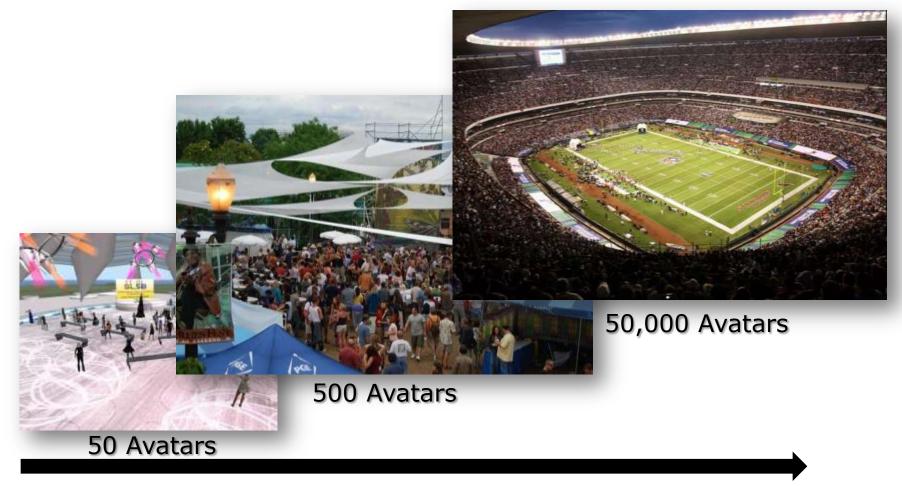


Designing Extensible and Scalable Virtual World Platforms

Dan Lake Intel Labs

March 2010

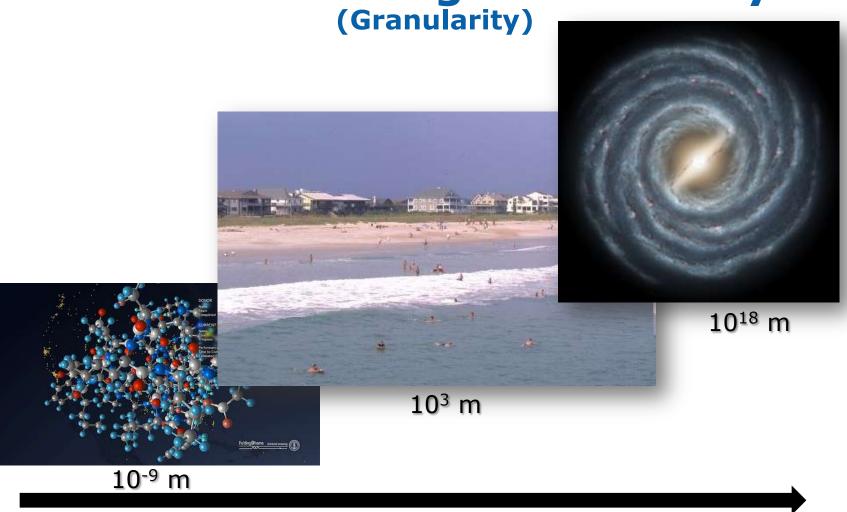
Grand Challenge: Scalability (Interaction)



INTERACTION



Grand Challenge: Scalability



GRANULARITY



Problem Formulation

- Scene: A data structure defining a space and the objects it contains
- Operator: a function that observes a scene and/or modifies the objects in a scene
 - Examples: Clients, scripts, physics, other external simulations



Research Problem

 How to map a scene and its operators to the available compute and communication resources to yield an optimal experience for the maximum number of users?



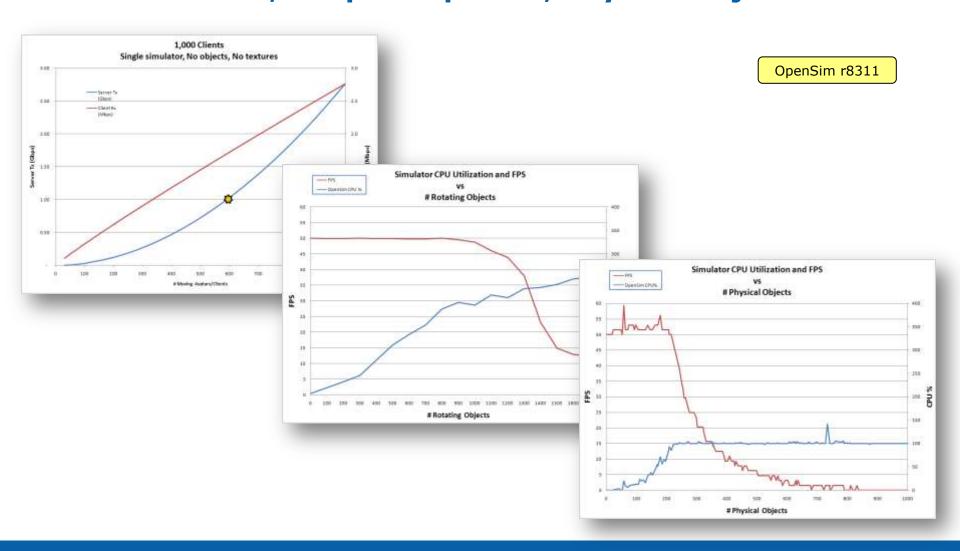
Current OpenSim Architecture

- Scene and actors are integrated in simulator
 - -Script, physics, client stacks and modules
- Heartbeat controls and synchronizes actors
 - -Steps Physics
 - Updates objects
 - -For each scene presence...
 - -Handles client view, map, inventory, chat, etc



Simulator Scaling Limits

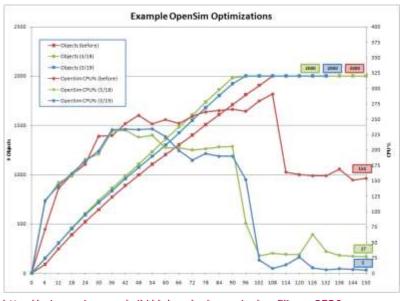
Avatars, Scripted Updates, Physical objects



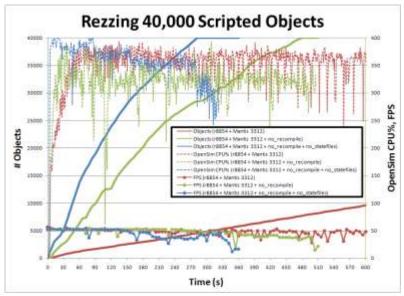


Simulator Optimizations (2009)

- Increased prim count by 5X, avatar count by 4X
- Reduced startup time of large scenes by 95%, steady state CPU by over 90%, object creation time by 95%, and memory usage by 2/3



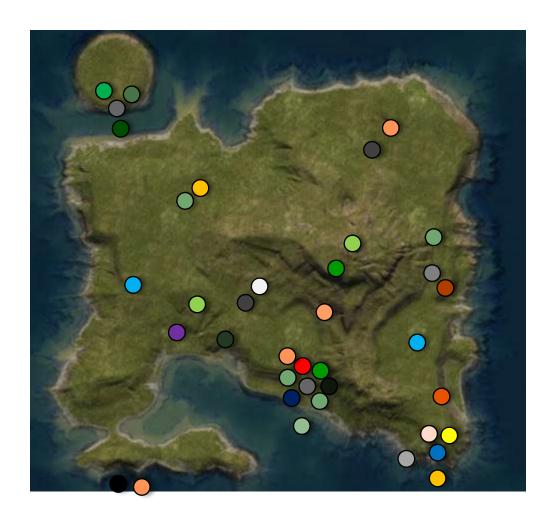
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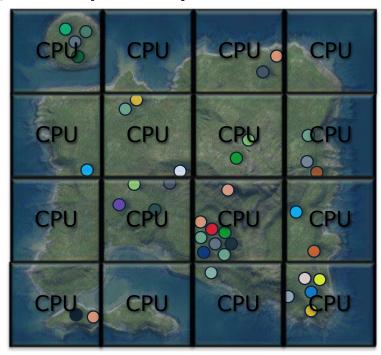
Scaling the Simulation Architecture





Current Architecture: Static Partitioning

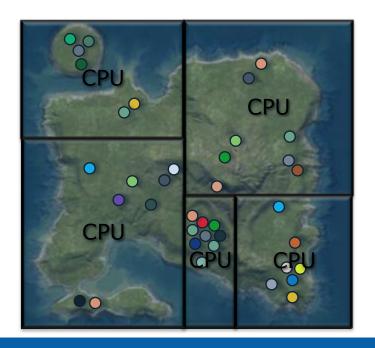
- Some regions are overloaded, others underutilized
- One actor may become bottleneck to performance
 - Too many clients, scripts, physics or other sim modules
- Interactions, complexity limited to server capacity





Another Option: Dynamic Partitioning

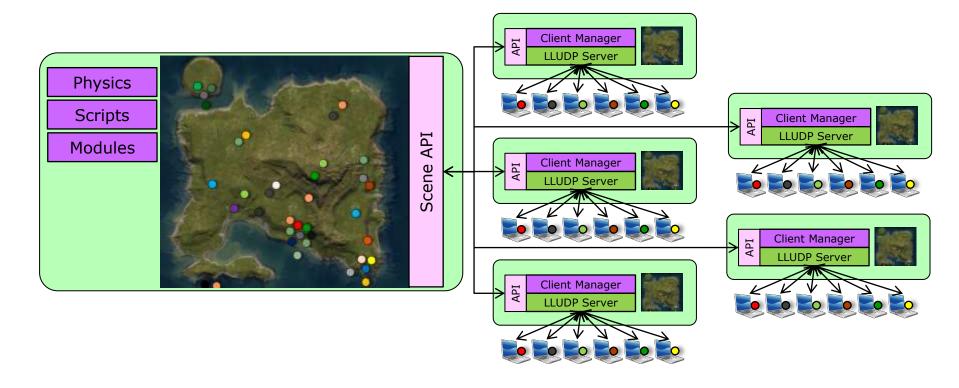
- Distributes load across available servers
- More boundary crossings as partitions get smaller
- Still limited by single server simulator capacity
- We hypothesize: The actors limit scene scaling





Proof of Concept: Client Management

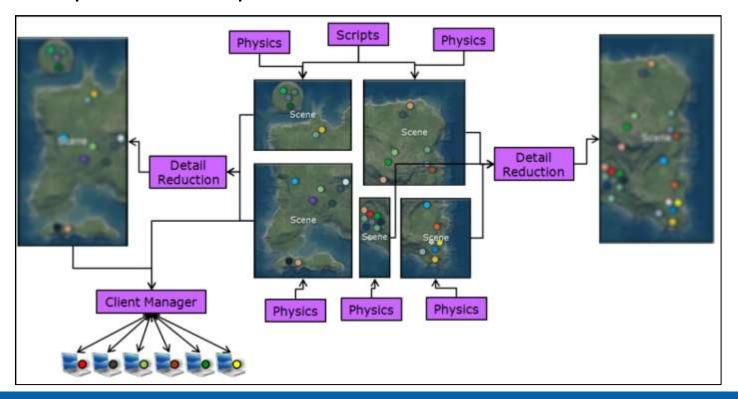
- Servers provisioned for high speed networking
- Prototyped 400 clients moving simultaneously
- Simulator serviced 4 connections instead of 400





Proposal: Distributed scene service

- Scene becomes container with pub/sub service layer
- Physics and scripts run asynchronously on appropriate HW
- Client managers provisioned for communication
- Scene partitions replicated with reduced detail if needed





Conclusions

- OpenSim is a capable platform for visual applications
- Large, complex environments being built today
- Truly massive scaling will enable <u>new applications</u>
- Requires a distributed architecture
 - Distributed scene service with common API
 - Actors mapped onto appropriate hardware
 - Eliminates synchronous scene control bottleneck
 - Reduces redundant computation of shared perspectives
 - Presents a larger, more interactive scene to clients



