# Three Address Code Examples

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### **Three Address Code**

*Three-address code* (TAC) will be the intermediate representation used in our Decaf compiler. It is essentially a generic assembly language that falls in the lower-end of the mid-level IRs. Some variant of 2, 3 or 4 address code is fairly commonly used as an IR, since it maps well to most assembly languages.

A TAC instruction can have at most three operands. The operands could be two operands to a binary arithmetic operator and the third the result location, or an operand to compare to zero and a second location to branch to, and so on. For example, below on the left is an arithmetic expression and on the right, is a translation into TAC instructions:

Notice the use of temp variables created by the compiler as needed to keep the number of operands down to three. Of course, it's a little more complicated than the above example, because we have to translate branching and looping instructions, as well as function and method calls. Here is an example of the TAC branching instructions used to translate an if-statement:

And here is an example of the TAC translation for a function call and array access:

#### **Decaf TAC Instructions**

The convention followed in the examples below is that £1, £2, and so on refer to variables (either declared variables or temporaries) and £1, £2, etc. are used for labels. Labels mark the target for a goto/branch and are used to identify function/method definitions and vtables.

### **Assignment:**

```
t2 = t1;
t1 = "abcdefg";
t1 = 8;
t3 = _L0;
(rvalue can be variable, string/int constant,
or label)
```

#### **Arithmetic:**

```
t3 = t2 + t1;
t3 = t2 - t1;
t3 = t2 * t1;
t3 = t2 / t1;
t3 = t2 % t1;
(not all arithmetic operator)
```

(not all arithmetic operators are present, must synthesize others using the primitives available)

# Relational/equality/logical:

```
t3 = t2 == t1;
t3 = t2 < t1;
t3 = t2 && t1;
t3 = t2 || t1;
(must synthesize other ops as necessary)
```

#### Labels and branches:

```
L1:
Goto L1;
IfZ t1 Goto L1;
(take branch if value of t1 is zero)
```

### **Handling parameters:**

```
PushParam t1;
(before making call, params are individually
pushed right to left)
PopParams 24;
(after call, pop all params, the number is
size in bytes to remove from stack)
```

### Function/method calls:

```
LCall L1;

t1 = LCall L1;

ACall t1;

t0 = ACall t1;

(LCall a function label known
```

(LCall a function label known at compiletime, ACall a computed function address, most likely from vtable. Each has two forms for void/non-void return value)

# **Function/method definitions:**

```
BeginFunc 12;
(the number is size in bytes for all locals and
temporaries in stack frame)
EndFunc;
Return t1;
Return;
```

#### **Memory references:**

```
t1 = *(t2);
t1 = *(t2 + 8);
*(t1) = t2;
*(t1 + -4) = t2;
```

(optional offset must be integer constant, can be positive or negative)

#### **Array indexing:**

To access arr[5], add offset multiplied by elem size to base and deref

### **Object fields, method dispatch:**

To access ivars, add offset to base, deref
To call method, retrieve function address from vtable, invoke using ACall

#### **Data specification:**

```
VTable ClassName = L1, L2, ...;
```

## **Decaf Stanford Library Functions**

These functions are invoked using Lcall instructions just like ordinary user-defined functions.

_Alloc	one int parameter, returns address of heap-allocated memory of that
	size in bytes
_ReadLine	no parameters, returns string read from user input
_ReadInteger	no parameters, returns integer read from user input
_StringEqual	two string parameters, returns integer comparison result (neg, 0, pos)
_PrintInt	one integer parameter, prints that number to the console
_PrintString	one string parameter, prints that string to the console
_PrintBool	one boolean parameter, prints true/false to the console
_GetByte	one integer parameters, gets byte at offset i0
_SetByte	two integer parameters, sets byte at offset i0 to value i1
_Halt	no parameters, stop program execution

# **TAC Examples**

What we have to do is figure out how to translate from Decaf to TAC. This includes not only generating the TAC, but figuring out the use of temp variables, creating labels, calling functions, etc. As we traverse our tree, we will create the TAC instructions one at a time. We can immediately print them out or store them for further processing. Most of the instructions can be emitted as we go and never re-visited, although in some situations (most notably when performing optimization) we may go back and make changes to earlier instructions based on information we gather later in the process.

We will simplify the Decaf language a little by excluding doubles for code generation and internally treating bools as 4-byte integers. Classes, arrays, and strings will be implemented with 4-byte pointers. This means we only ever need to deal with 4-byte integer/pointer variables.

As we visit each subtree, we will create the necessary instructions. Let's start with a trivial program:

```
void main() {
    Print("hello world");
}

BeginFunc 4;
    _t0 = "hello world";
    PushParam _t0;
    LCall _PrintString;
    PopParams 4;
    EndFunc;
```

Visualize the tree for this simple program—there is the program node at the top, its list of declarations has only one entry, the function declaration for main, within main we have a list of statements—in this case, just the one print statement. In order to generate code for a program, we traverse its list of declarations, directing each declaration to

generate code. For the main function, we generate its label and function markers and then iterate over the statements having each emit code. A print statement translates to a call to the Decaf built-in library function \_Printstring to do the actual printing. The library functions are called like any ordinary global function, but the compiler provides the code (and hooks are made the instant the compiler builds the executable.)

Here is another simple program with a little arithmetic:

Consider where the instructions above must be emitted relative to the tree traversal.

What additional processing would need to be added for a program with a complex expression?

```
void main()
                                                      main:
                                                           BeginFunc 44;
    int b;
                                                            t0 = 3;
                                                           \overline{b} = _{t0};
_{t1} = _{12};
    int a;
   b = 3;
                                                           a = _t1;
_t2 = 2;
    a = 12;
    a = (b + 2) - (a*3)/6;
                                                             t3 = b + _t2;
                                                            t4 = 3;
                                                            _t5 = a * _t4;
                                                            _t6 = 6;
                                                           _t7 = _t5 / _t6;
_t8 = _t3 - _t7;
a = _t8;
                                                           EndFunc;
```

Now let's consider what needs to be done to deal with arrays (note the TAC code below doesn't do array bounds checking, that will be your job to implement!)

```
void Binky(int[] arr)
{
    arr[1] = arr[0] * 2;
}

BeginFunc 44;
    _t0 = 1;
    _t1 = 4;
    _t2 = _t1 * _t0;
    _t3 = arr + _t2;
    _t4 = 0;
    _t5 = 4;
    _t6 = _t5 * _t4;
    _t7 = arr + _t6;
    _t8 = *(_t7);
    _t9 = 2;
    _t10 = _t8 * _t9;
    *(_t3) = _t10;
    EndFunc;
```

Before we deal with classes, we should look at how function calls are implemented. This will facilitate our study of methods as they are used in classes. A program with a simple function call:

```
int foo(int a, int b)
                                                   BeginFunc 4;
   return a + b;
                                                   t0 = a + b;
                                                   Return _t0;
                                                   EndFunc;
void main()
                                               main:
                                                    BeginFunc 12;
   int c;
                                                    PushParam d;
   int d;
                                                    PushParam c;
                                                    _t1 = LCall _foo;
PopParams 8;
   foo(c, d);
                                                    EndFunc;
```

Now for a class example with both fields and methods (notice how this is passed as a secret first parameter to a method call)

```
class Animal {
                                          Animal.InitAnimal:
  int height;
                                             BeginFunc 0;
  void InitAnimal(int h) {
                                                 *(this + 4) = h;
    this.height = h;
                                                EndFunc;
                                          VTable Animal =
}
                                                 Animal.InitAnimal,
                                          _Cow.InitCow:
class Cow extends Animal {
  void InitCow(int h) {
                                             BeginFunc 8;
                                                _t0 = *(this);
_t1 = *(_t0);
    InitAnimal(h);
}
                                             PushParam h;
                                             PushParam this;
void Binky(Cow betsy) {
                                                ACall t1;
  betsy.InitCow(5);
                                             PopParams 8;
                                                 EndFunc;
                                           VTable Cow =
                                                  _Animal.InitAnimal,
                                                  _Cow.InitCow,
                                           Binky:
                                             BeginFunc 12;
                                                 _{t2} = 5;
                                                 t3 = *(betsy);
                                                 t4 = *(t3 + 4);
                                             PushParam \overline{t}2;
                                             PushParam betsy;
                                                ACall _t4;
                                             PopParams 8;
                                                 EndFunc;
```

How about some TAC that implements control structures—the if statement, for example?

```
void main()
                                                      main:
                                                           BeginFunc 24;
                                                           _{t0} = 23;
   int a;
                                                           a = _t0;
_t1 = 23;
_t2 = a == _t1;
   a = 23;
   if (a == 23)
                                                           IfZ _t2 Goto _L0;
_t3 = 10;
       a = 10;
   else
       a = 19;
                                                           a = _t3;
                                                           Goto_L1;
                                                      _L0:
                                                           _{t4} = 19;
                                                           \bar{a} = t4;
                                                      _L1:
                                                           EndFunc;
```

Or the even snazzier while loop (for loops are left as an exercise for the reader):

```
void main()
                                                 main:
                                                     BeginFunc 40;
                                                     _{t0} = 0;
   int a;
   a = 0;
                                                     \bar{a} = _t0;
                                                  L0:
                                                     _{-1}^{t1} = 10;
   while (a < 10) {
      Print(a % 2 == 0);
                                                     t2 = a < t1;
                                                     IfZ _t2 Goto _L1;
      a = a + 1;
                                                     _{t3} = 2;
                                                     _{t4} = a % t3;
                                                     _t5 = 0;
_t6 = _t4 == _t5;
PushParam _t6;
                                                     LCall _PrintBool;
                                                     PopParams 4;
                                                     _{t7} = 1;
                                                      t8 = a + t7;
                                                     a = t8;
                                                     Goto_L0;
                                                 L1:
                                                     EndFunc;
```

# **Using TAC For Other Languages**

The TAC we use is fairly generic. Although we show our examples in the context of Decaf, a TAC generator for any programming language would generate a similar sequence of statements. For example, in the (in)famous dragon book, the following syntax-directed translation is used to generate TAC for a while loop. (Check out pages 469 of Aho, Sethi, and Ullman)

One last idea before we finish. A nice enhancement to a TAC generator is re-using temp variable names. For example, if we have the following expression:

```
E \rightarrow E1 + E2
```

Our usual steps would be to evaluate £1 into £1, evaluate £2 into £2, and then set £3 to their sum. Will £1 and £2 be used anywhere else in the program? How do we know when we can reuse these temp names? Here is a method from Aho/Sethi/Ullman (p. 480) for reusing temp names:

- 1) Keep a count c initialized to 0.
- 2) Whenever a temp name is used as an operand, decrement c by 1
- 3) Whenever a new temp is created, use this new temp and increase c by one.

```
x = a * b + c * d - e * f

(c = 0) T0 = a * b
(c = 1) T1 = c * d (c = 2)
(c = 0) T0 = T0 + T1
(c = 1) T1 = e * f (c = 2)
(c = 0) T0 = T0 - T1

x = T0
```

Note that this algorithm expects that each temporary name will be assigned and used exactly once, which is true in the majority of cases.

## **Bibliography**

- J.P. Bennett, <u>Introduction to Compiling Techniques</u>. Berkshire, England: McGraw-Hill, 1990.
- S. Muchnick, <u>Advanced Compiler Design and Implementation</u>. San Francisco, CA: Morgan Kaufmann, 1997.
- A. Pyster, <u>Compiler Design and Construction</u>. New York, NY: Van Nostrand Reinhold, 1988.