# Methods of reduction of information in multidimensional space 

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#### Abstract

The Author replaces hypersurface with hyperplane in the multidimensional space in order to reduce amount of


 data in the transmission of information process.Keywords: multidimansional space, reduction of information

## INTRODUCTION

Gathering amount of information cause the necessity of their transformation and classification There also appears a necessity of elimination of a part of this information, which does not carry essential content and reduces unnecessary dimension in mathematical space New branch of knowledge arises named "feature selection" which by means of mathematical methods removes unnecessary information and simplifies model of data transmission. The problem of reduction of data is important in the process of their creation because excess overload of the link lengthens the transmission time. One of selection data technique is PCA, which reduces unnecessary dimension in geometrical space (Belda, 2012). Method of data reduction proposed by Author in the multidimensional space base on replacing hypersurface with hyperplane that leads to data reduction in sending the information. PCA (https: pl.wikipedia.org.wiki analiza glownych skladowych) method is based on an algorithm which:

1. sets mean and standard deviation matrix
2. sets covariance matrix
3. computes eigenvalue covariance matrix
4. reduces number of variables from eigenvalue covariance matrix, and
5. sets eigenvector and data throws on eigenvectors

My method differs from PCA method because it uses a different form of input data.

## Mathematical description

In this chapter I replace hypersurface with hyperplane in the multidimensional space. Let $M$ be vector in an ndimensional space [1] that means
$M=M\left(x_{1}, x_{2}, \ldots, x_{n}\right)$
Let $U_{1}, U_{2}, \ldots, U_{n}$ be parameters in an $n$ dimensional space [1]. Let us assume that
$x_{1}=U_{1}, x_{2}=U_{2}, \ldots, x_{n-1}=U_{n-1}$
$z=x_{n}=f\left(U_{1}, \ldots, U_{n-1}\right)=f\left(x_{1}, \ldots, x_{n-1}\right)$
where $\boldsymbol{f}\left(x_{1}, \ldots, x_{n-1}\right)$ is hypersurface in n-dimensional space. Let us replace hypersurface with hyperplane. In every $i$ elementary hypercube $d_{1, i}<x_{1}<e_{1, i}$, $\ldots, d_{n-1, i}<x_{n-1}<e_{n-1, i}$ there is a set of hypersurface
and tangent hyperplane. Let us assume in every arbitrary small hypercube is one hyperplane set and a hypersurface tangent to it. We set the vector tangent to a coordinate axis $U_{1}, U_{2}, \ldots, U_{n-1}$. Tangent vectors are signed $M_{U_{1}}, M_{U_{2}}, \ldots, M_{U_{n-1}} \quad$ where

$$
\begin{align*}
& M_{U_{I}}=\left[\frac{\partial x_{1}}{\partial U_{l}}, \ldots \cdot \frac{\partial x_{n}}{\partial U_{1}}\right]  \tag{4}\\
& M_{U_{n-1}}=\left[\frac{\partial x_{1}}{\partial U_{l}}, \ldots \cdot \frac{\partial x_{n}}{\partial U_{\mathrm{n}-1}}\right] \tag{5}
\end{align*}
$$

Taking under consideration connection between $x_{i}$ and $U_{i}$ we receive

$$
\begin{gather*}
M_{U_{1}}=\left[1,0, \ldots, 0, \frac{\partial z}{\partial x_{1}}\right] \\
M_{U_{2}}=\left[0,1, \ldots, 0, \frac{\partial z}{\partial x_{2}}\right]  \tag{6}\\
M_{U_{n-1}}=\left[0,0, \ldots, 1, \frac{\partial z}{\partial x_{n-1}}\right]
\end{gather*}
$$

Vectors $M U_{1, \ldots}, M U_{n-1}$ are linearly independent in n -dimensional space because:

$$
\sum_{i=1}^{n-1} \alpha_{i} M_{U 1}=0 \Rightarrow \alpha_{i}=0, \mathrm{i}=1,2, \ldots, n-1
$$

## Because from

$$
\begin{equation*}
\sum_{i=1}^{n-1} \alpha_{i} M_{U},=\left[\alpha_{1}, \ldots, \alpha_{n-1}, \sum_{i=1}^{n-1} \alpha_{i} \frac{\partial z}{\partial x_{i}}\right]=0 \tag{10}
\end{equation*}
$$

It appears that $\alpha i=0$ for $i=1, \ldots, n-1$ that ends the proof.

Vector ( $\alpha_{1}, \ldots, \alpha_{n}$ ) perpendicular to $M_{U 1}, \ldots, M_{U n-1}$ sets the hyperplane
$\left(x_{1}-x_{1,0}\right) \alpha_{1}+\ldots+\left(x_{n}-x_{n, 0}\right) \alpha_{n}=0$
tangent to hypersurface $z$. Vector ( $\alpha_{1}, \ldots, \alpha_{n}$ ) (perpendicular to vectors tangent to hypersurface) must fulfil equations

$$
\begin{array}{r}
\alpha_{1} 1+\ldots+\alpha_{\mathrm{n}} \frac{\partial \mathrm{z}}{\partial \mathrm{x} 1}=0 \\
\alpha_{1} 0+\ldots+\alpha_{\mathrm{n}} \frac{\partial \mathrm{z}}{\partial \mathrm{x}_{\mathrm{n}-1}}=0
\end{array}
$$

In order to solve equations let us assume that $\alpha_{n}=1$. Then the vector

$$
\begin{equation*}
\left(\alpha_{1}, \ldots, \alpha_{n}\right)=\left(-\frac{\partial z}{\partial \mathrm{x}_{1}}, \ldots,-\frac{\partial \mathbf{z}}{\partial \mathrm{x}_{\mathrm{n}-1}}, 1\right) \tag{14}
\end{equation*}
$$

## Experimental Research

Experimental research was carried out for a 4domensional space. Examined hypersurface is expressed by the formula.

$$
\begin{equation*}
z=f\left(x_{1}, \ldots, x_{3}\right)=x_{1}^{2}+x_{2}^{2}+x^{2} \tag{15}
\end{equation*}
$$

Derivative $z$ after the variables $x_{i}$ is
$\partial z$
$\underline{Z}=2 x_{i}$
$\partial x_{1}$
Thus the vector

$$
\begin{equation*}
\left(\alpha_{1}, \alpha_{2}, \alpha_{3}, \alpha_{4}\right)=\left(-2 x_{1},-2 x_{2},-2 x_{3}, 1\right) \tag{17}
\end{equation*}
$$

Sets hyperplane
$\left(x_{1}-x_{1,0}\right) \alpha_{1}+\ldots\left(x_{4}-x_{4,0}\right) \alpha 4=0$
Let us divide segment [0, 1] to 2 parts. We receive 8 hypercubes. Then $x_{i, 0}=0,250 r 0,75$ and $z=x_{4}$. We receive 8 parts approximating a paraboloid. For $0 \leq x_{i} \leq$ $0,5 z_{0}=x_{4,0}=3 * 0,25^{2}=\frac{3}{10}$ we have the hyperplane

$$
\begin{equation*}
\left(x_{1}-0,25\right)(-2+0,25)+\left(x_{2}-0,25\right)(-2+0,25)+\left(x_{3}-0,25\right)(-2 * 0,25)+\left(z-z_{0}\right)=0 \tag{19}
\end{equation*}
$$

## Convergence and computational complexity

Approximation error of the continuous function will aspire to arbitrarily small value by decreasing the dimension hypercube fields. It appears from that variability of continuous function around the hyperplane can be decreased to the arbitrarily small value by decreasing the dimension field. It saves the amount of sending the data by using proposed algorithm. Let us assume that field [0, 1] is divided by 10 parts for 3-dimensional function. We have $10^{3}$ cubes so we need $7 \times 1000=7000$ numbers. Without the algorithm, when we assume the field divided into 100 parts, we have $100^{3}=1000000$ numbers.

## CONCLUSION

This paper has the purpose to replace the function of many variables with a hyperplane in an n-dimensional space. Performance of this operation enables data reduction and leads to simplification of a multivariable
model of function. Methods of sending the data used now include escessive amount of information that makes the data transmission difficult. Using proposed algorithm simplifies the whole operation and reduces the cost of signal transports. Methods proposed by the Author are simpler than PCA methods. Instead of deleting variables measure data are replaced with hyperplane which contains the most important information data. Technique of data input and output is different. Input data are points in multidimensional space in PCA methods. Input data are an $n$ variable function in my method. In the PCA method we have data in the form of points in reduction of dimension. In my method we have a function based on decreased number of points.

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