

***Left-Leaning
Red-Black Trees***

***Robert Sedgwick
Princeton University***

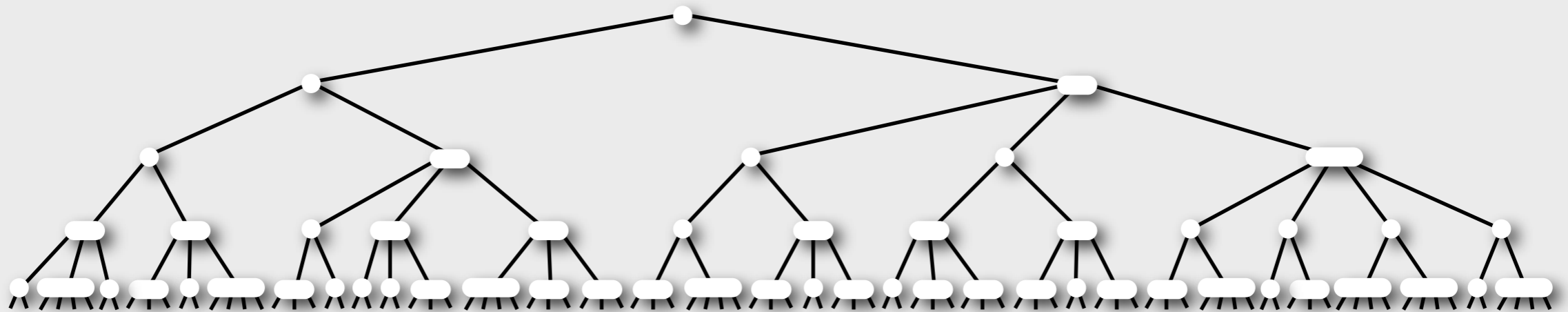
Introduction

2-3-4 Trees

Red-Black Trees

Left-Leaning RB Trees

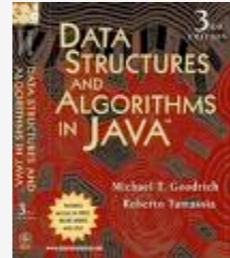
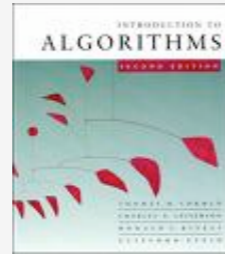
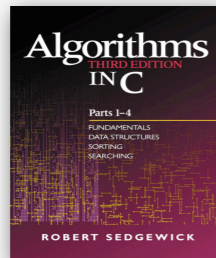
Deletion



Red-black trees

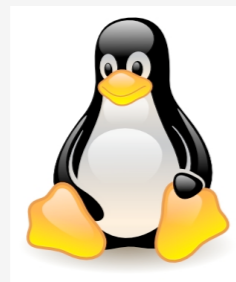
are now found throughout our computational infrastructure

Textbooks on algorithms



...

Library **search function** in many programming environments



...

Popular culture (stay tuned)

Worth revisiting?

Red-black trees

are now found throughout our computational infrastructure

Typical:

```
> ya thanks,  
> i got the idea  
> but is there some other place on the web where only the algorithms  
> used by STL is  
> explained. (that is the underlying data structures etc. ) without  
> explicit reference to the code (as it is pretty confusing if I try to  
> read through).  
>  
> thanks[/color]
```

The standard does not specify which algorithms the STL must use. Implementers are free to choose which ever algorithm or data structure that fulfils the functional and efficiency requirements of the standard.

There are some common choices however. For instance every implementation of map, multimap, set and multiset that I have ever seen uses a structure called a red black tree. Typing 'red black tree algorithm' in google produces a number of likely looking links.

john

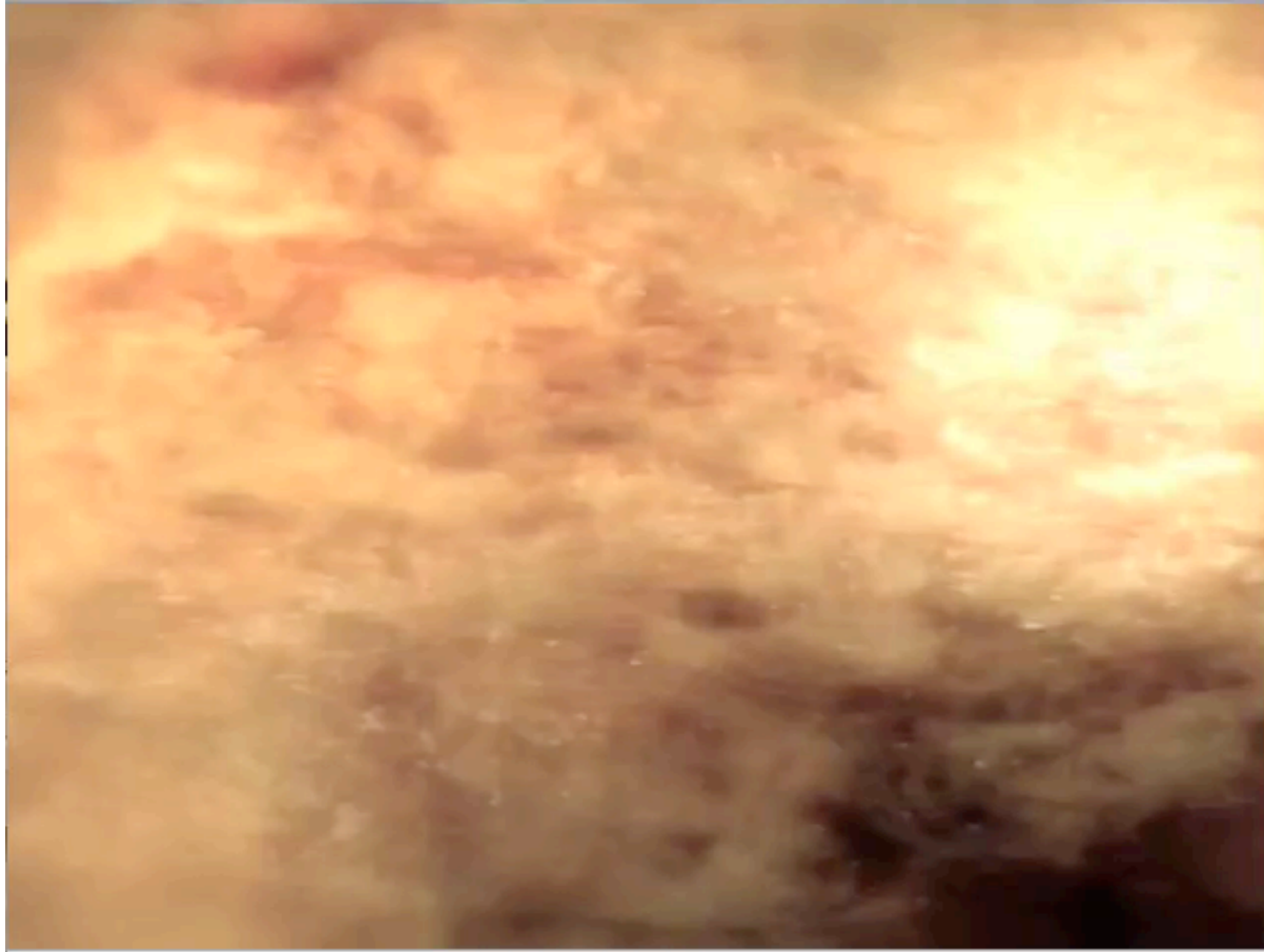
Digression:

Red-black trees are found in popular culture??

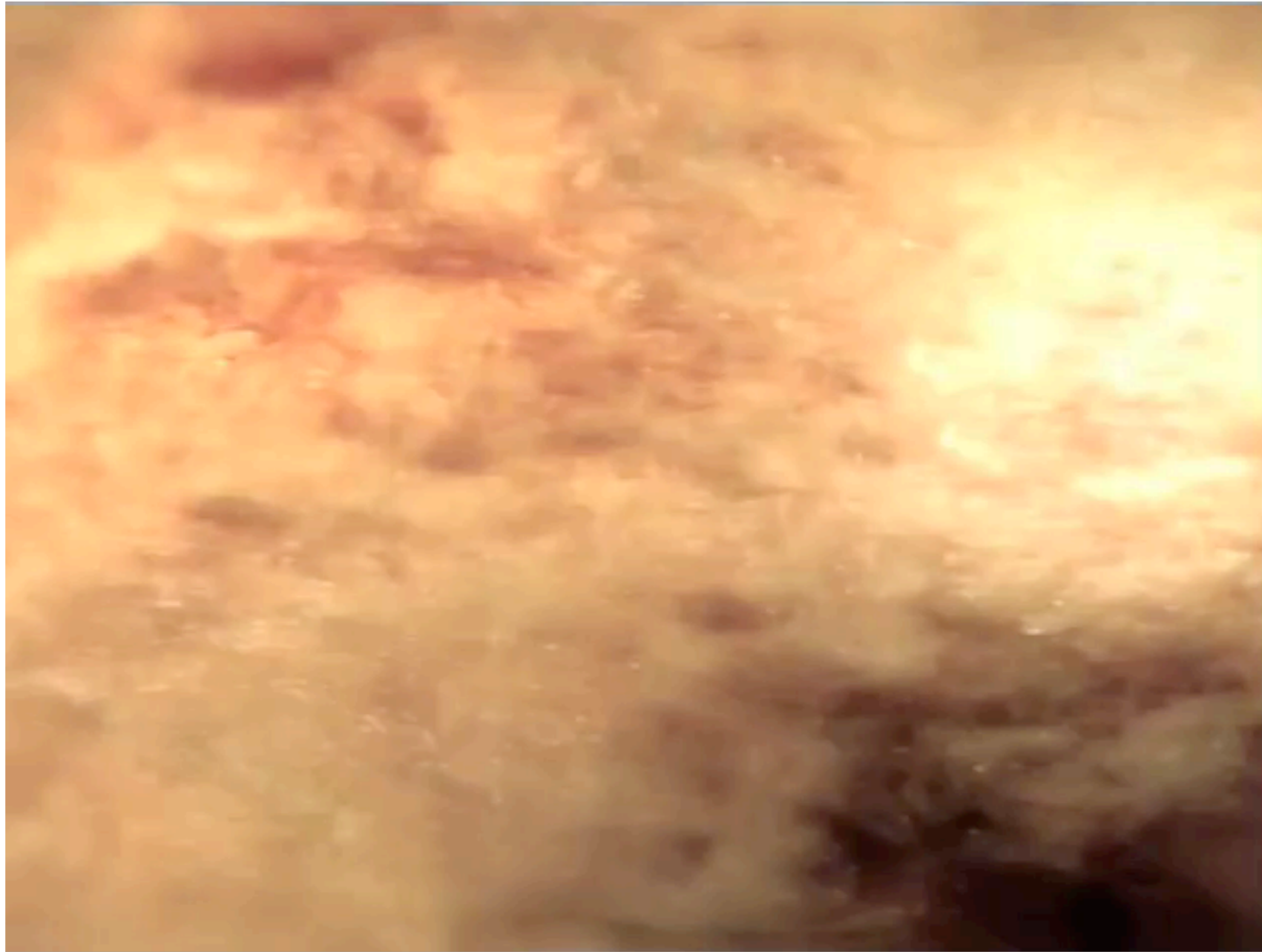
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Mystery: black door?



Mystery: red door?



An explanation ?



Red-black trees (Guibas-Sedgwick, 1978)

- reduce code complexity
- minimize or eliminate space overhead
- unify balanced tree algorithms
- single top-down pass (for concurrent algorithms)
- find version amenable to average-case analysis

Current implementations

- maintenance
- migration
- space not so important (??)
- guaranteed performance
- support full suite of operations

Worth revisiting ?

Red-black trees (Guibas-Sedgwick, 1978)

- reduce code complexity
- minimize or eliminate space overhead
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Current implementations

- maintenance
- migration
- space not so important (??)
- guaranteed performance
- support full suite of operations

Worth revisiting ? **YES. Code complexity is out of hand.**

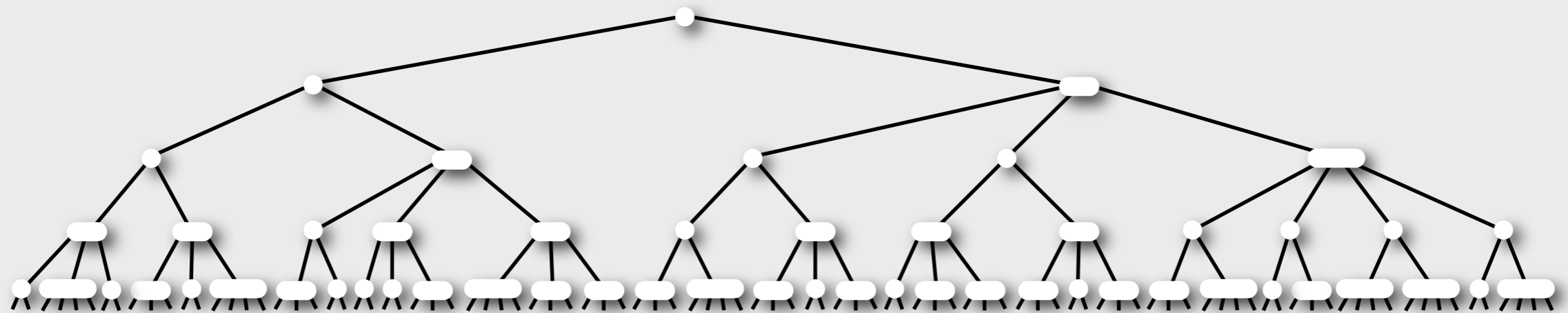
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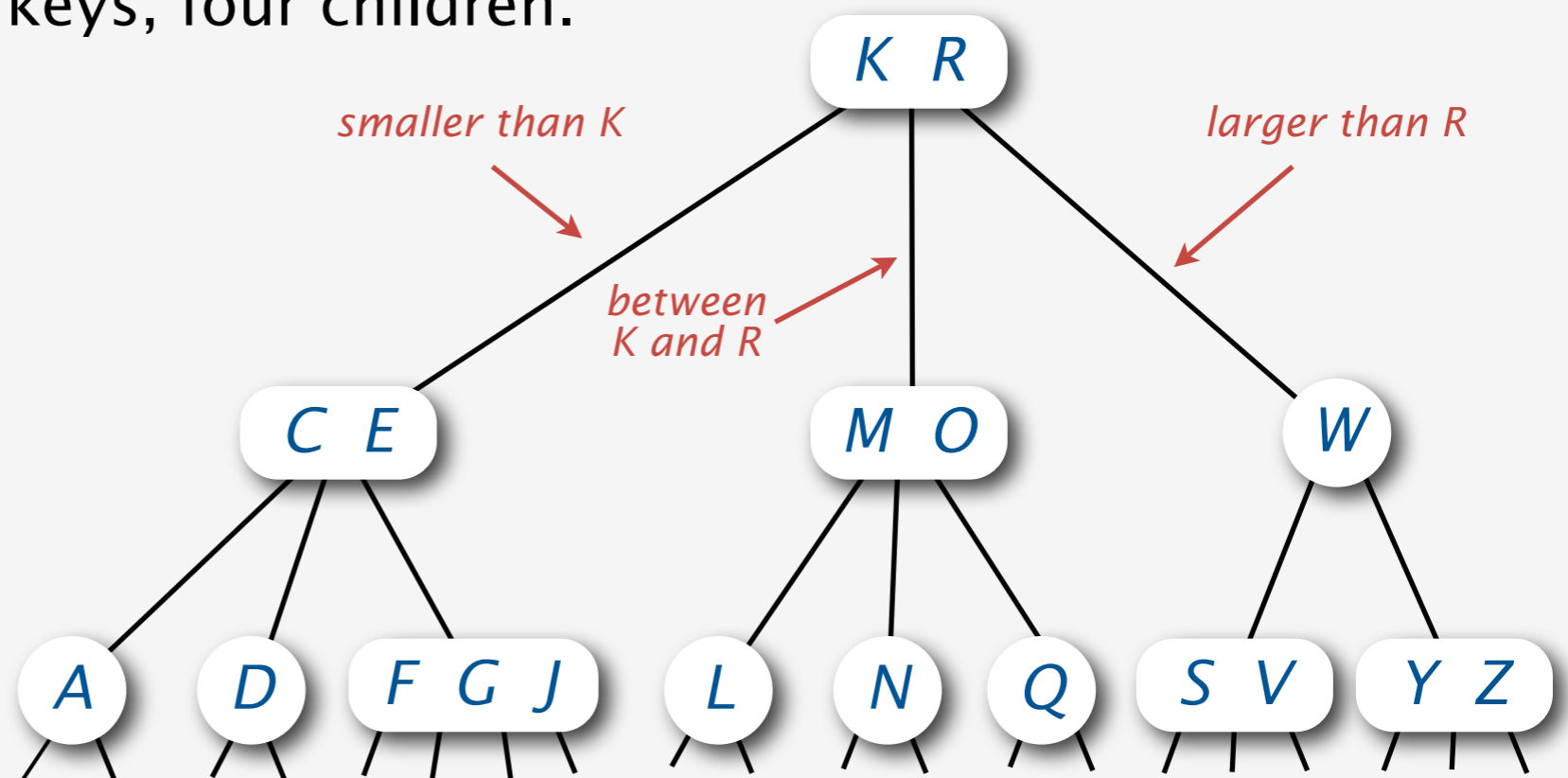
2-3-4 Tree

Generalize BST node to allow multiple keys.
Keep tree in perfect balance.

Perfect balance. Every path from root to leaf has same length.

Allow 1, 2, or 3 keys per node.

- 2-node: one key, two children.
- 3-node: two keys, three children.
- 4-node: three keys, four children.



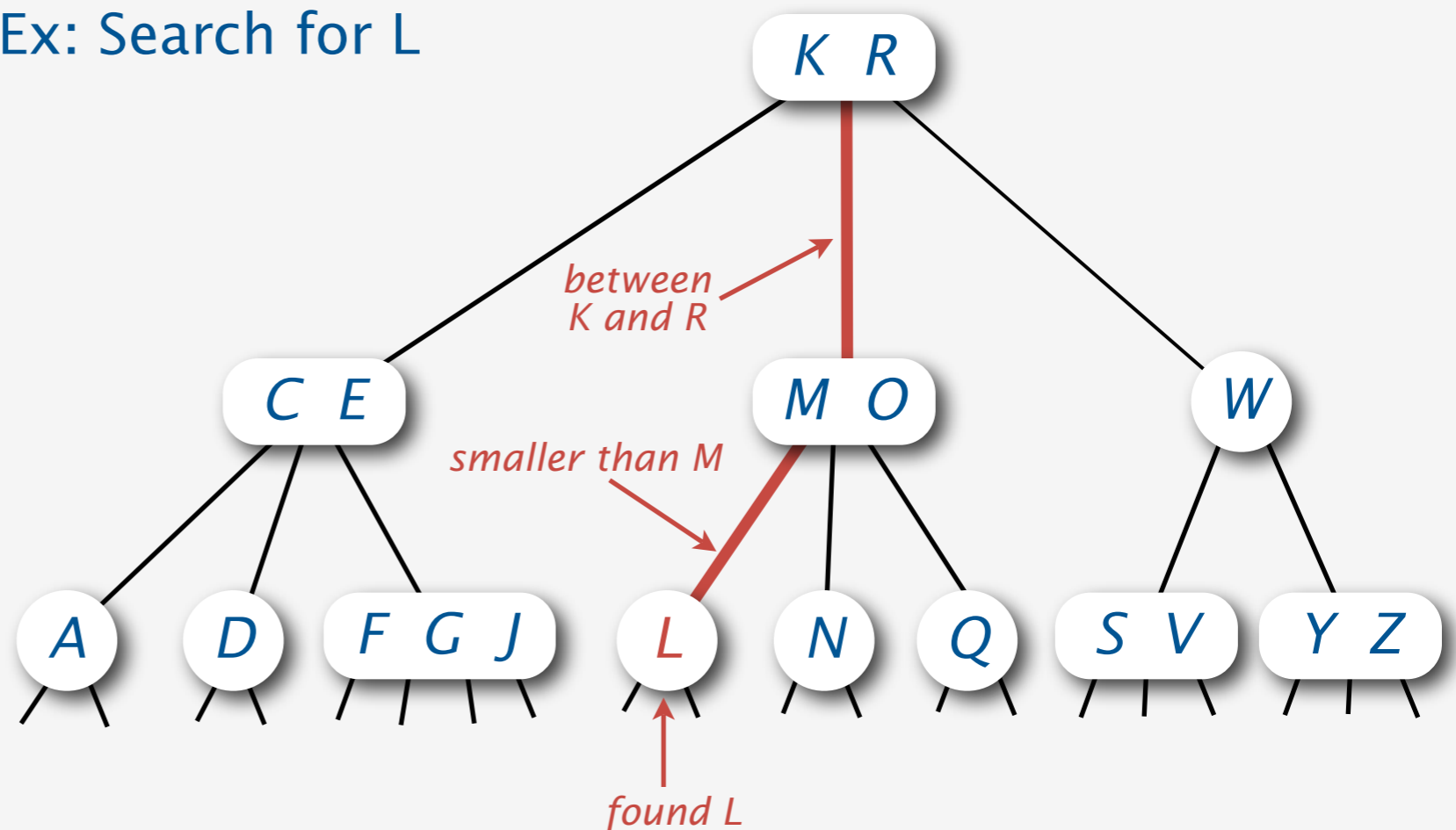
Search in a 2-3-4 Tree

Compare node keys against search key to guide search.

Search.

- Compare search key against keys in node.
- Find interval containing search key.
- Follow associated link (recursively).

Ex: Search for L

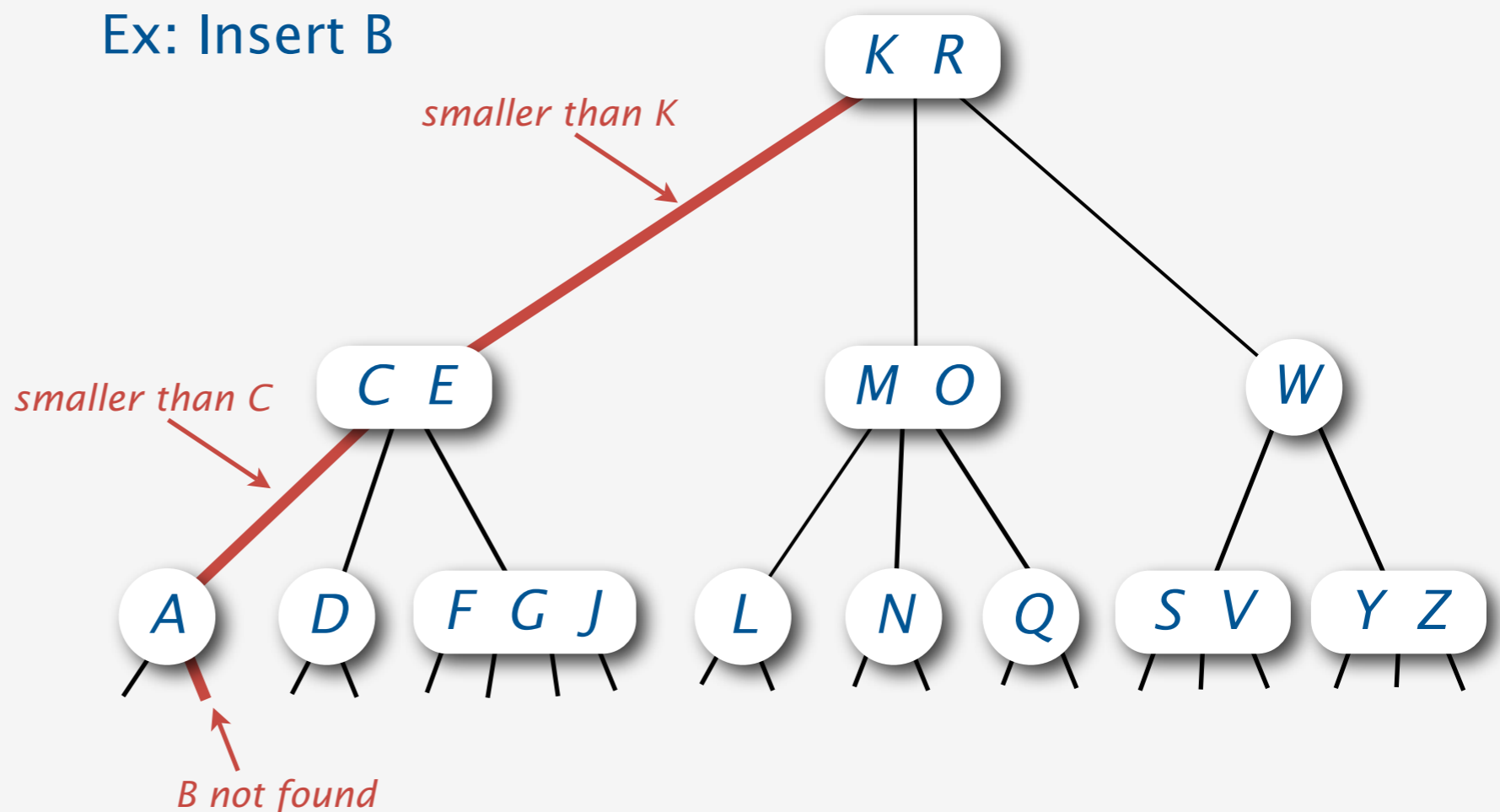


Insertion in a 2-3-4 Tree

Add new keys at the bottom of the tree.

Insert.

- Search to bottom for key.



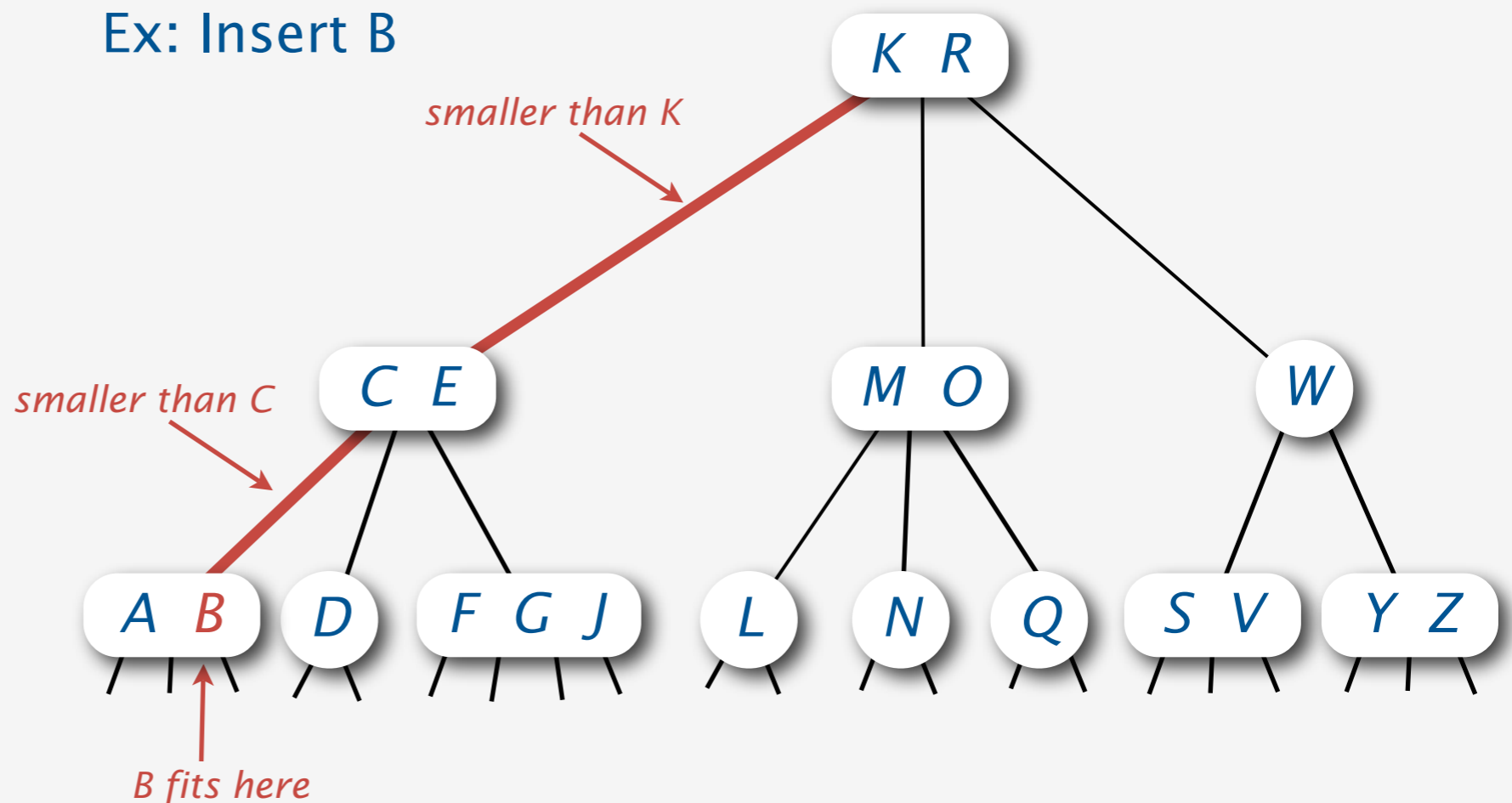
Insertion in a 2-3-4 Tree

Add new keys at the bottom of the tree.

Insert.

- Search to bottom for key.
- 2-node at bottom: convert to a 3-node.

Ex: Insert B



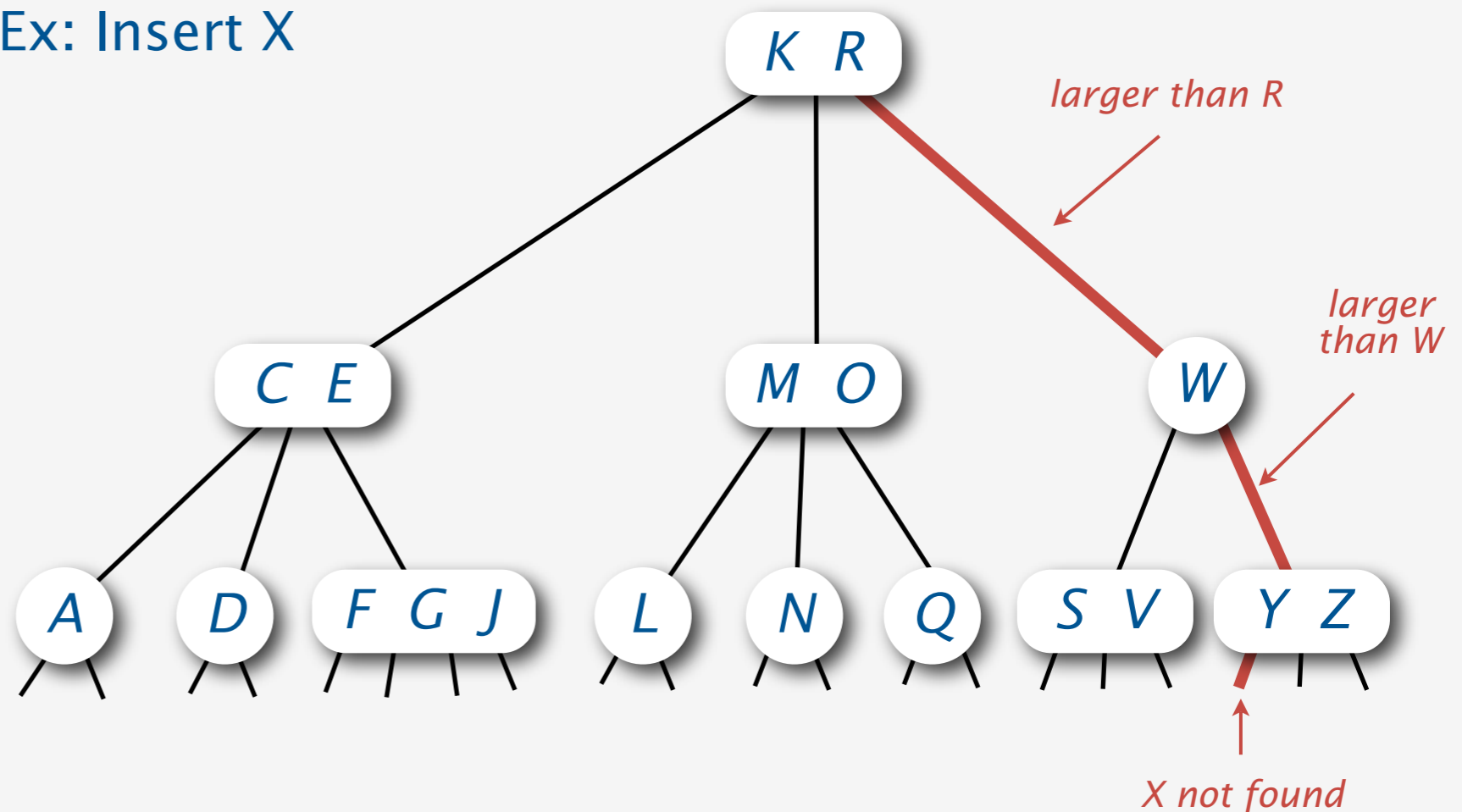
Insertion in a 2-3-4 Tree

Add new keys at the bottom of the tree.

Insert.

- Search to bottom for key.

Ex: Insert X



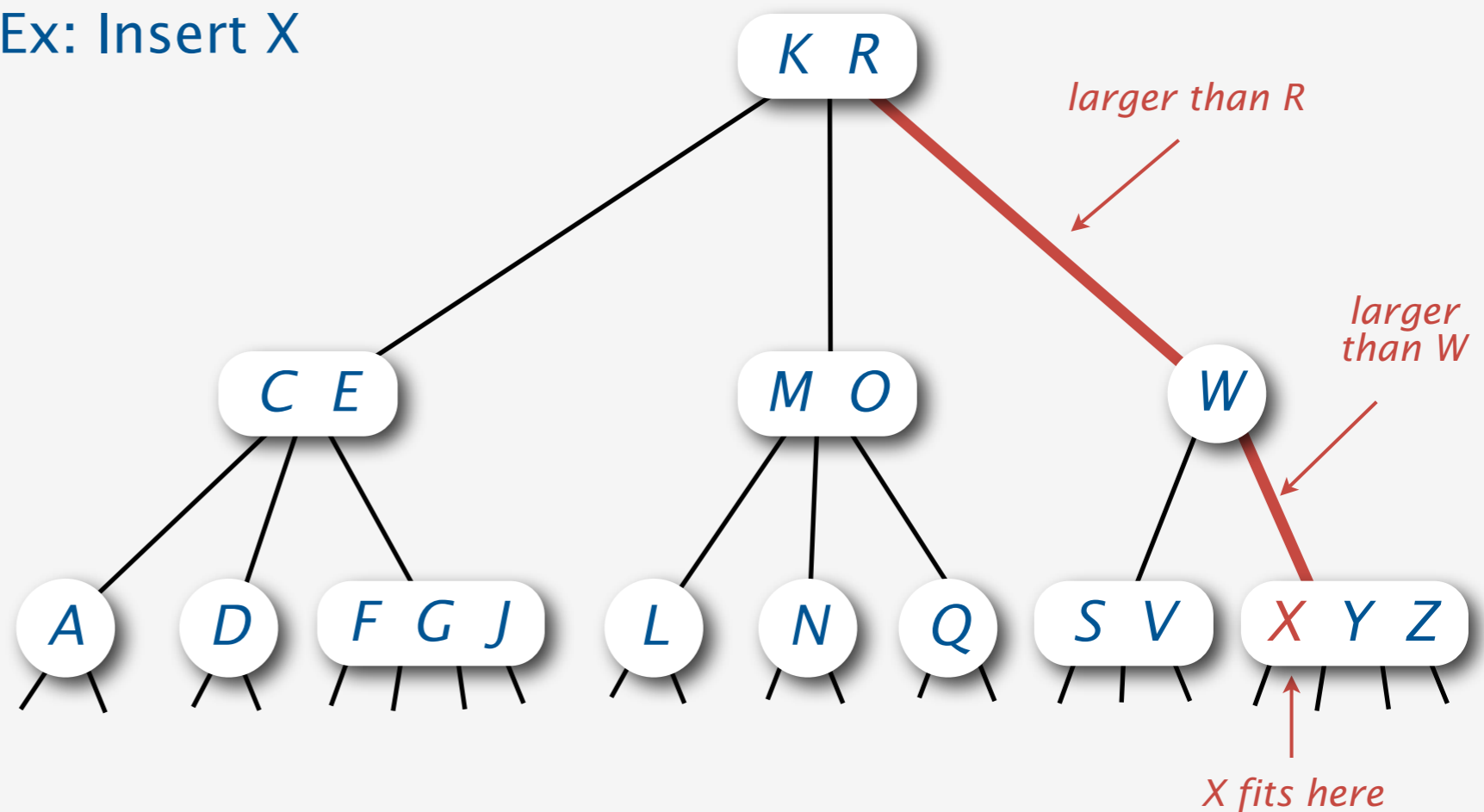
Insertion in a 2-3-4 Tree

Add new keys at the bottom of the tree.

Insert.

- Search to bottom for key.
- 3-node at bottom: convert to a 4-node.

Ex: Insert X



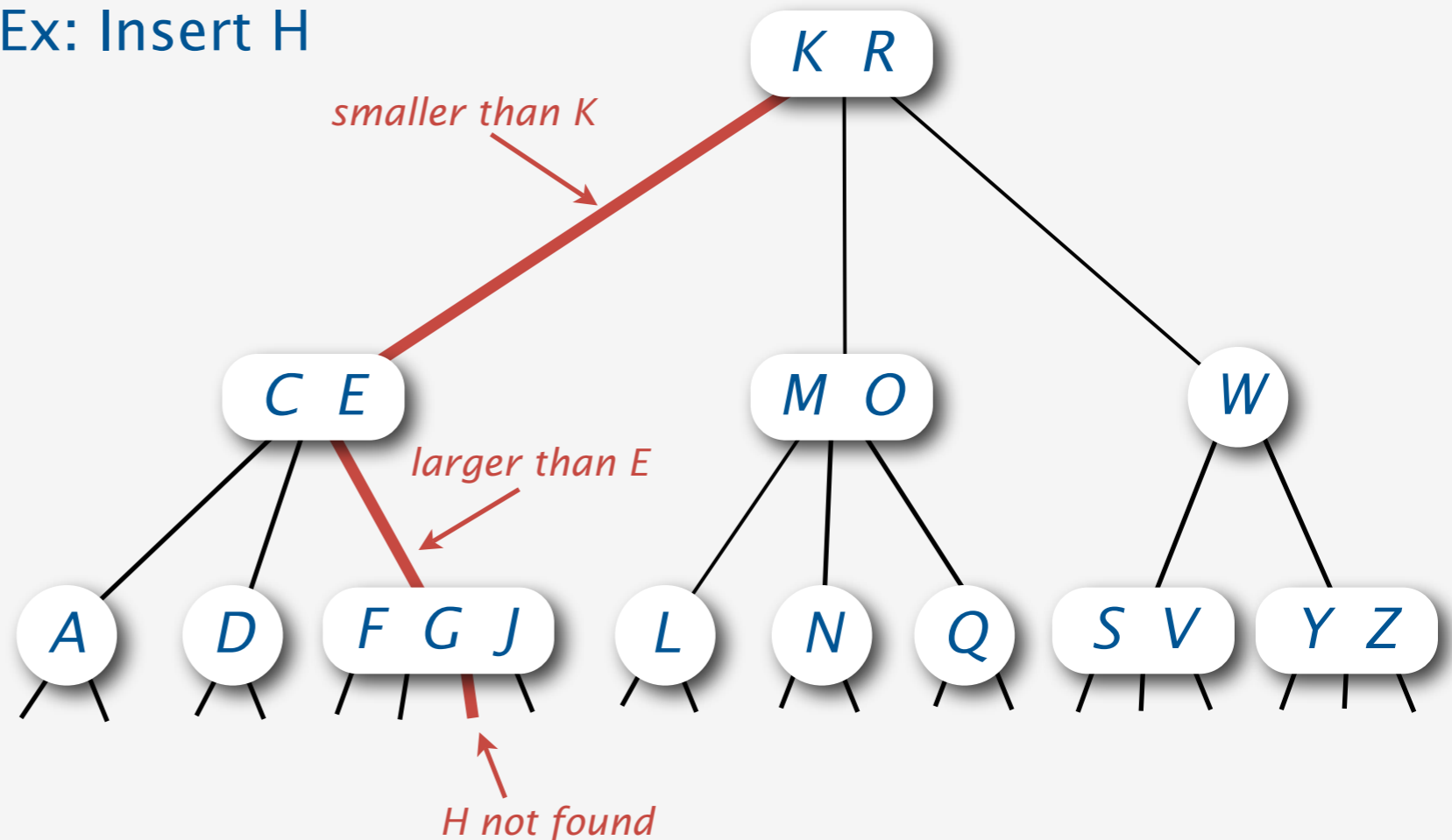
Insertion in a 2-3-4 Tree

Add new keys at the bottom of the tree.

Insert.

- Search to bottom for key.

Ex: Insert H



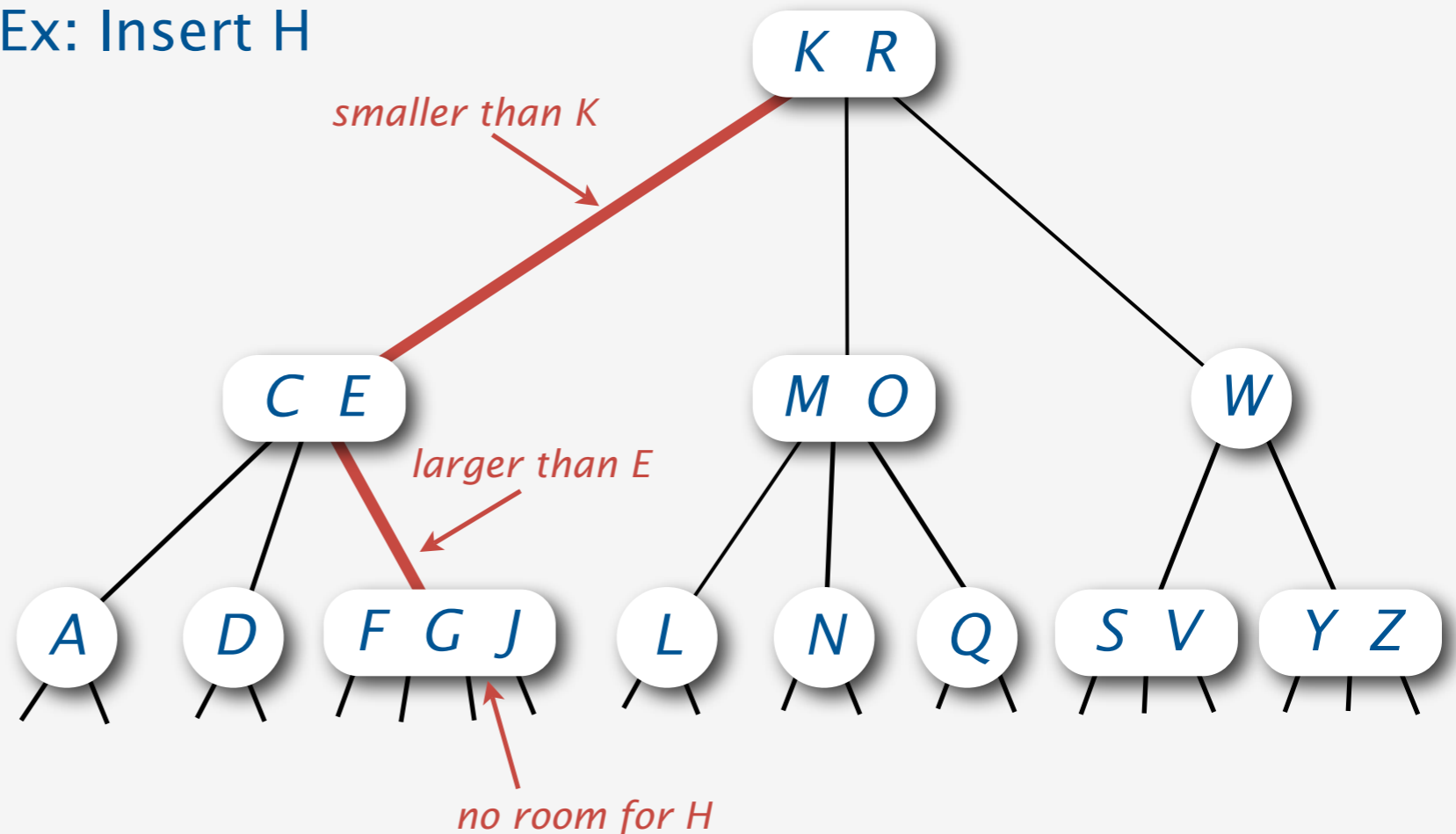
Insertion in a 2-3-4 Tree

Add new keys at the bottom of the tree.

Insert.

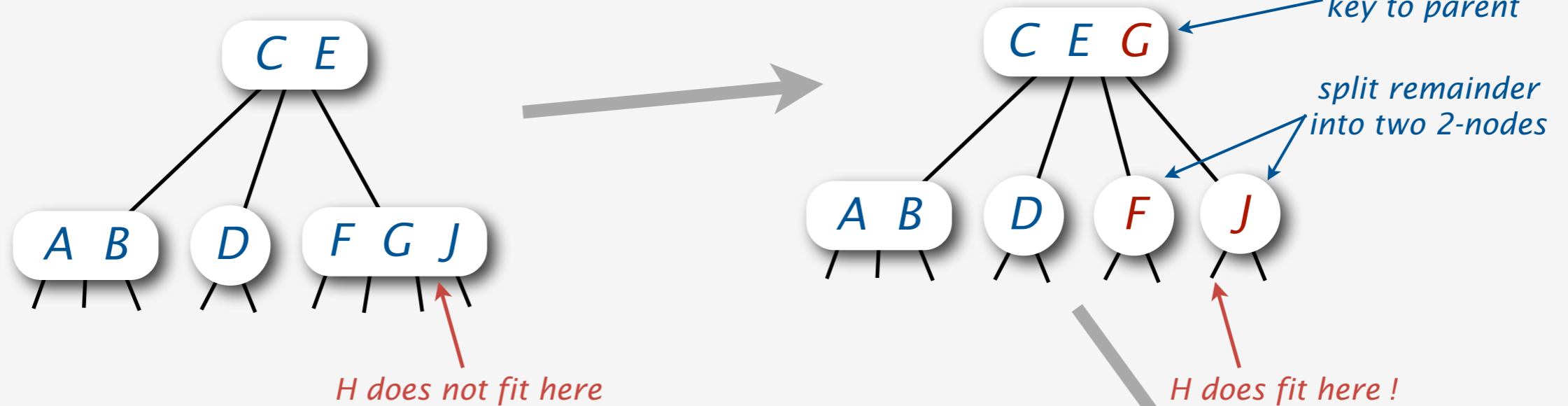
- Search to bottom for key.
- 2-node at bottom: convert to a 3-node.
- 3-node at bottom: convert to a 4-node.
- 4-node at bottom: no room for new key.

Ex: Insert H



Splitting 4-nodes in a 2-3-4 tree

is an effective way to make room for insertions



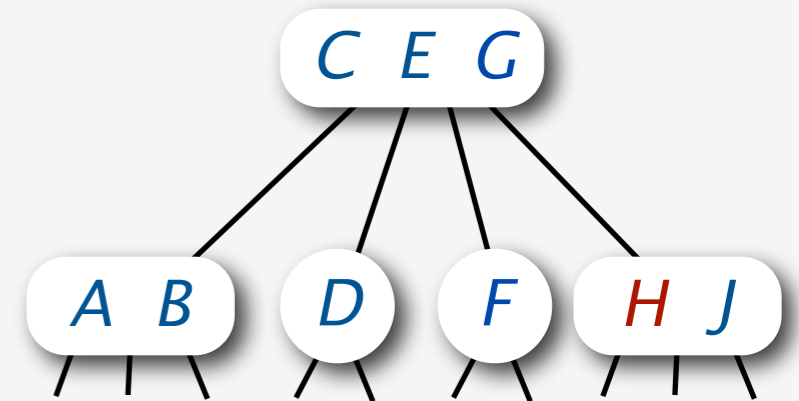
Problem: Doesn't work if parent is a 4-node

Bottom-up solution (Bayer, 1972)

- Use same method to split parent
- Continue up the tree while necessary

Top-down solution (Guibas-Sedgwick, 1978)

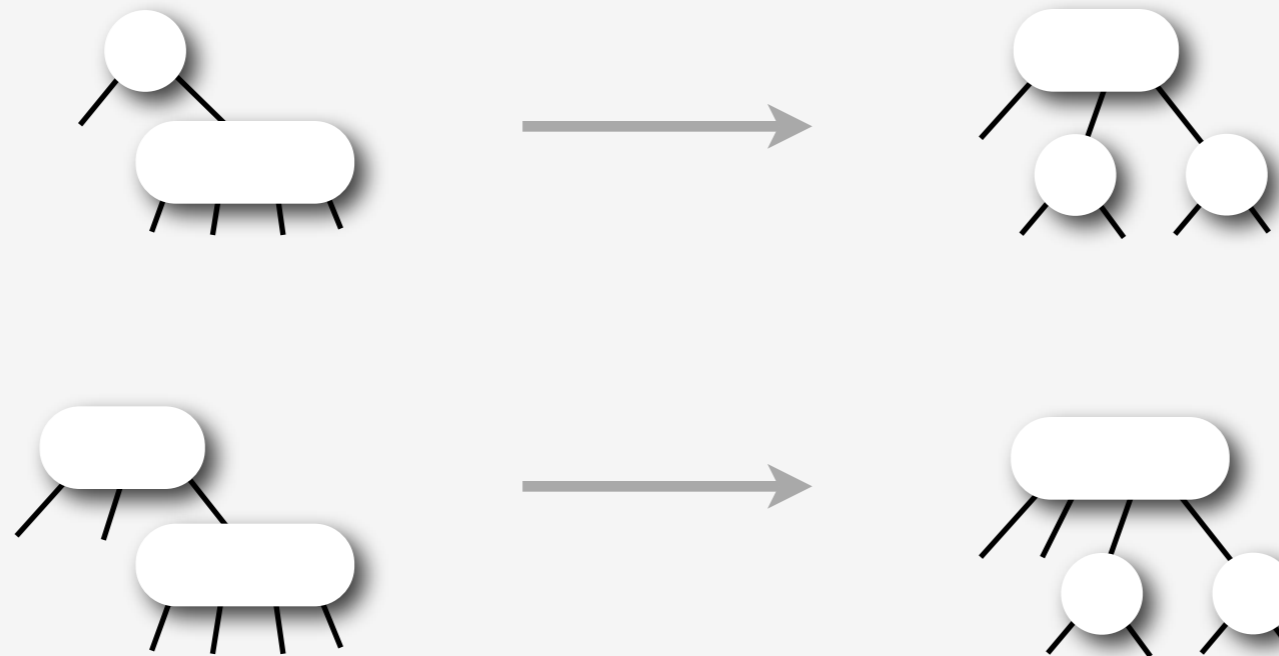
- Split 4-nodes on the way **down**
- Insert at bottom



Splitting 4-nodes on the way down

ensures that the “current” node is not a 4-node

Transformations to split 4-nodes:



*local transformations
that work **anywhere** in the tree*

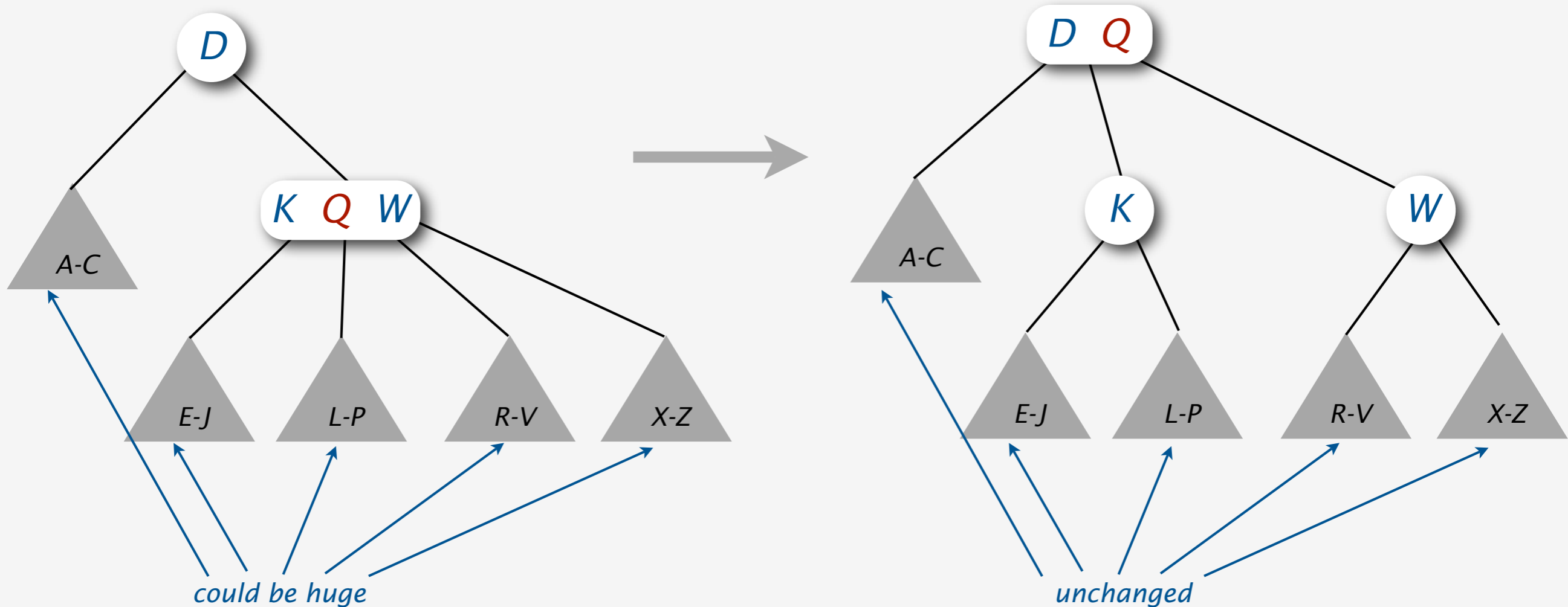
Invariant: “Current” node is not a 4-node

Consequences:

- 4-node below a 4-node case never happens
- Bottom node reached is always a 2-node or a 3-node

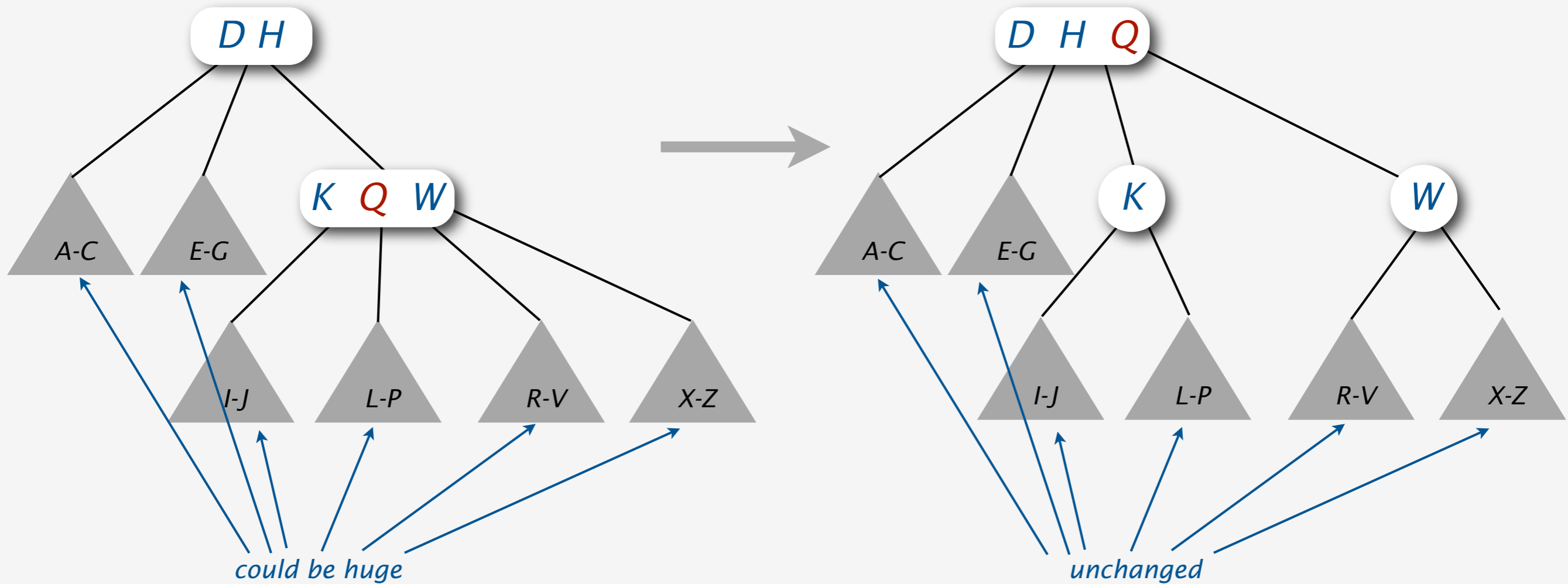
Splitting a 4-node below a 2-node

is a **local** transformation that works anywhere in the tree



Splitting a 4-node below a 3-node

is a **local** transformation that works anywhere in the tree



Growth of a 2-3-4 tree

happens **upwards** from the bottom

insert A



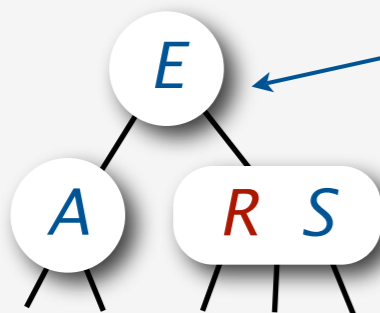
insert S



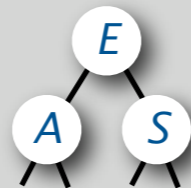
insert E



insert R



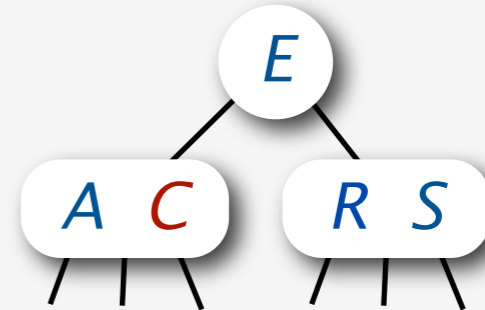
split 4-node to



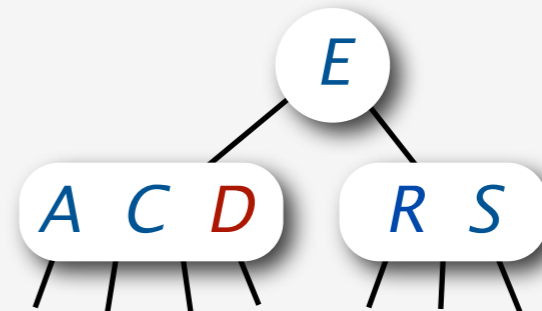
and then insert

tree grows
up one level

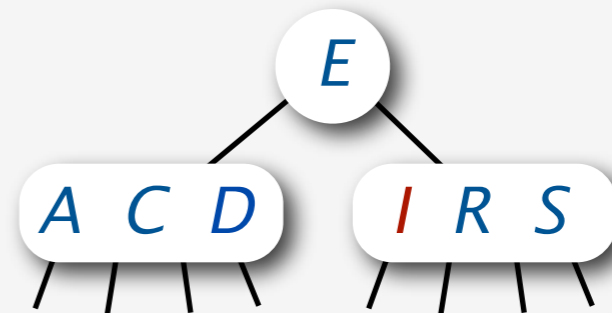
insert C



insert D

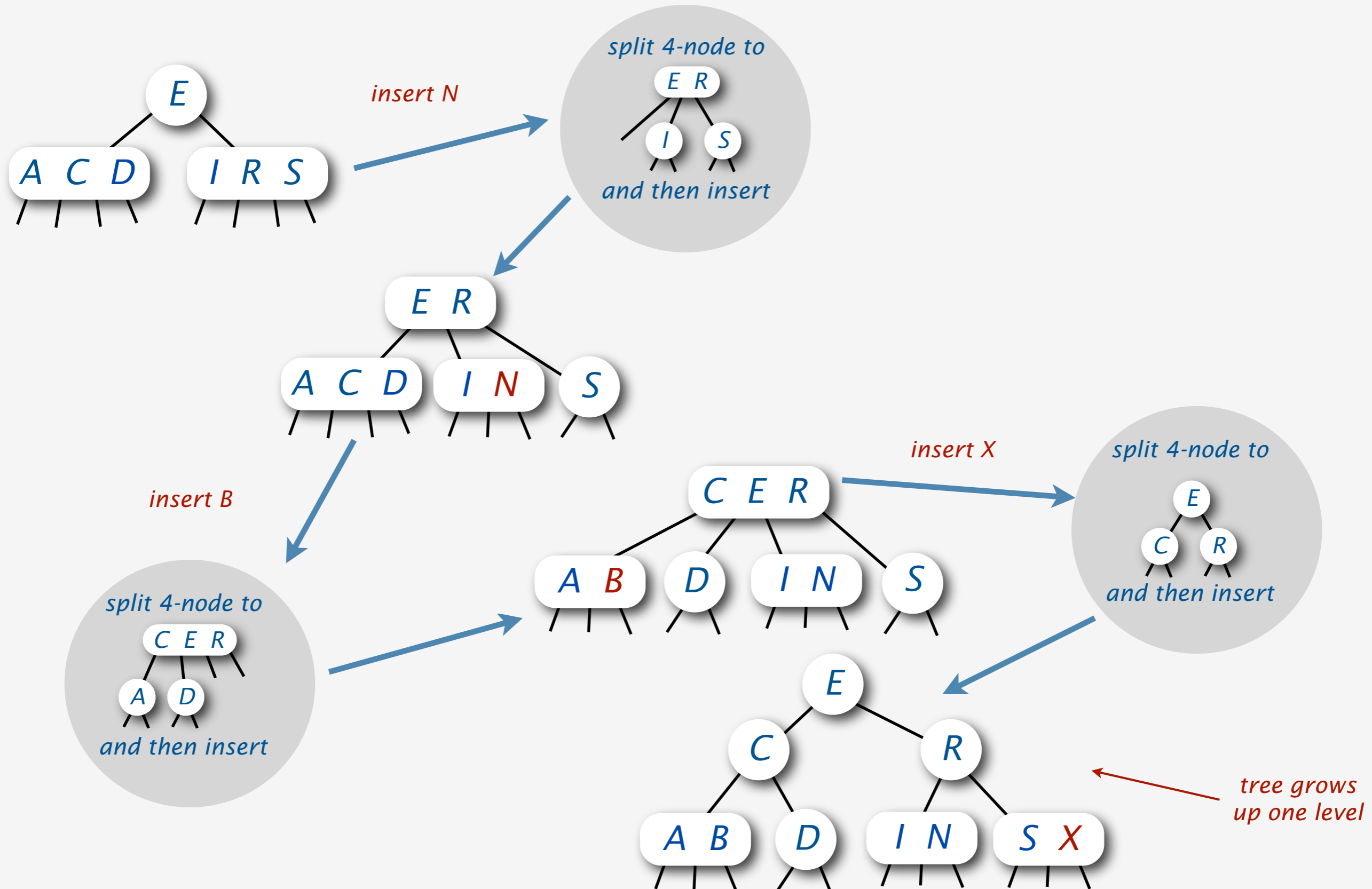


insert I



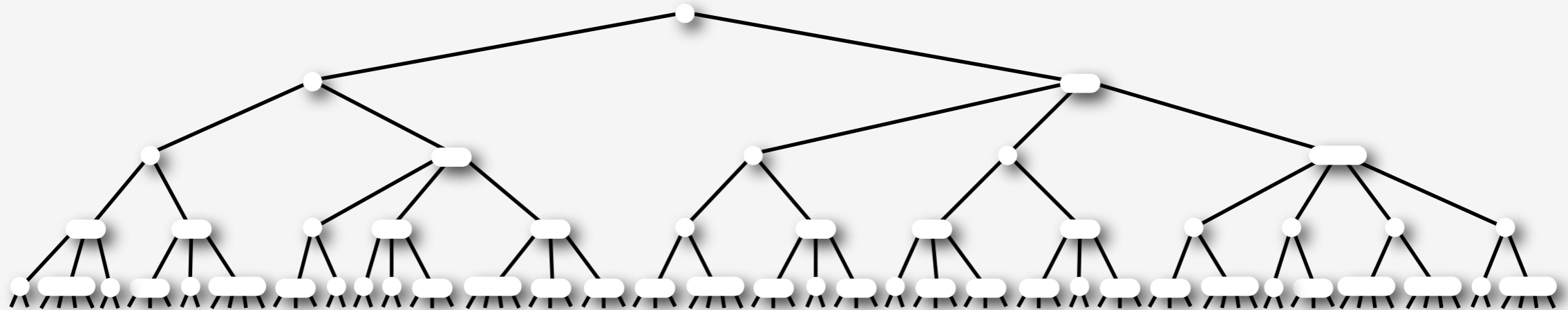
Growth of a 2-3-4 tree (continued)

happens **upwards** from the bottom



Balance in 2-3-4 trees

Key property: All paths from root to leaf are the same length



Tree height.

- Worst case: $\lg N$ [all 2-nodes]
- Best case: $\log_4 N = 1/2 \lg N$ [all 4-nodes]
- Between 10 and 20 for 1 million nodes.
- Between 15 and 30 for 1 billion nodes.

Guaranteed logarithmic performance for both search and insert.

Direct implementation of 2-3-4 trees

is complicated because of code complexity.

Maintaining multiple node types is cumbersome.

- Representation?
- Need multiple compares to move down in tree.
- Large number of cases for splitting.
- Need to convert 2-node to 3-node and 3-node to 4-node.

```
private void insert(Key key, Val val) fantasy
{ code
    Node x = root;
    while (x.getChild(key) != null)
    {
        x = x.getChild(key);
        if (x.is4Node()) x.split();
    }
    if (x.is2Node()) x.make3Node(key, val);
    else if (x.is3Node()) x.make4Node(key, val);
    return x;
}
```

Bottom line: Could do it, but stay tuned for an easier way.

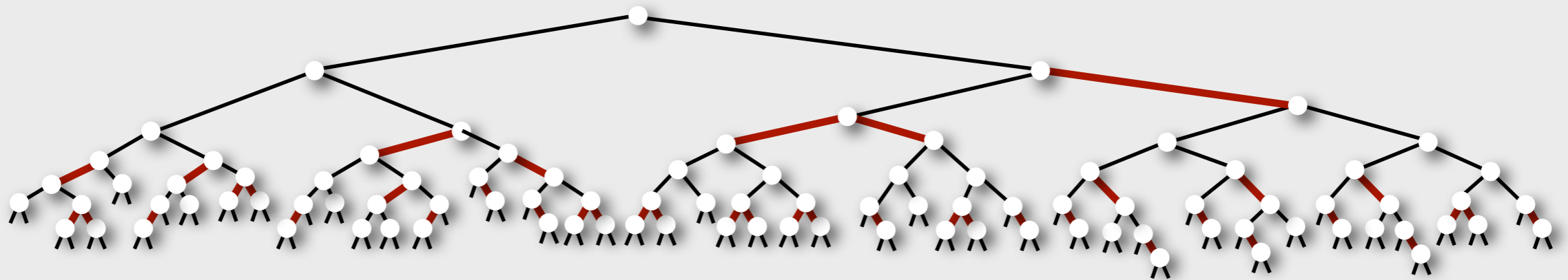
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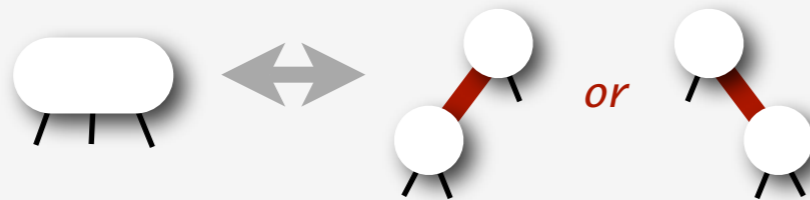
Deletion



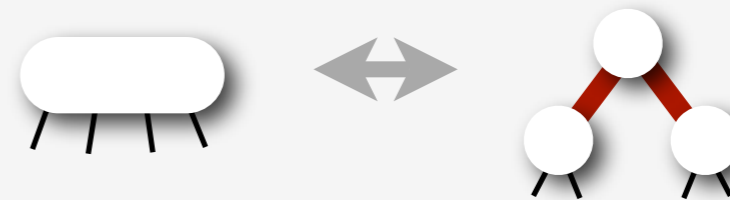
Red-black trees (Guibas-Sedgwick, 1978)

1. Represent 2-3-4 tree as a BST.
2. Use "internal" edges for 3- and 4- nodes.

3-node

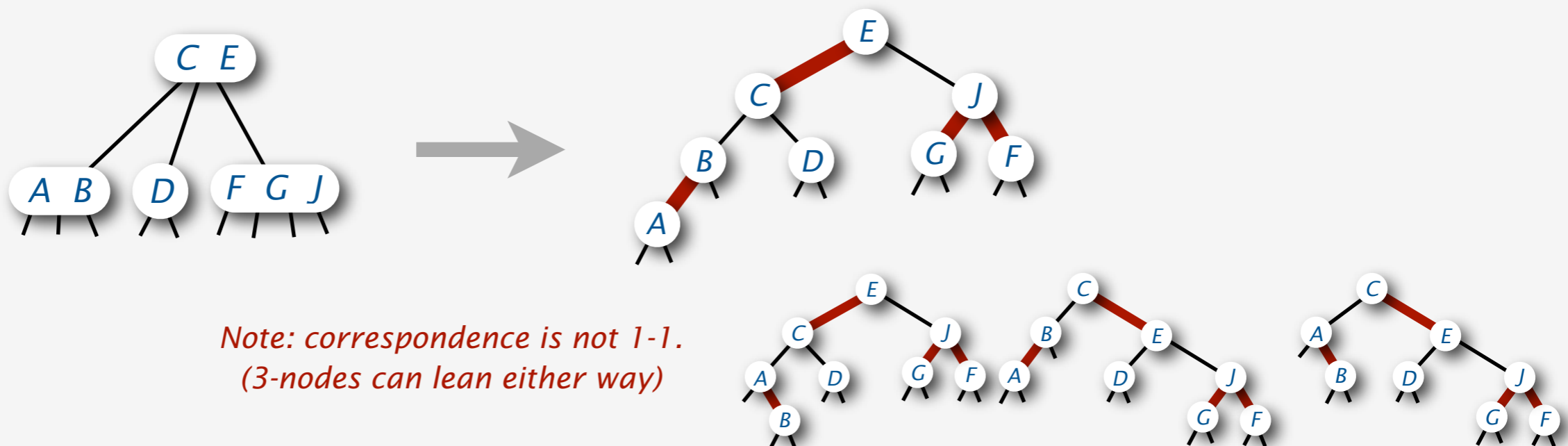


4-node



Key Properties

- elementary BST search works
- easy to maintain a correspondence with 2-3-4 trees (and several other types of balanced trees)



Many variants studied (details omitted.)

NEW VARIANT (this talk): Left-leaning red-black trees

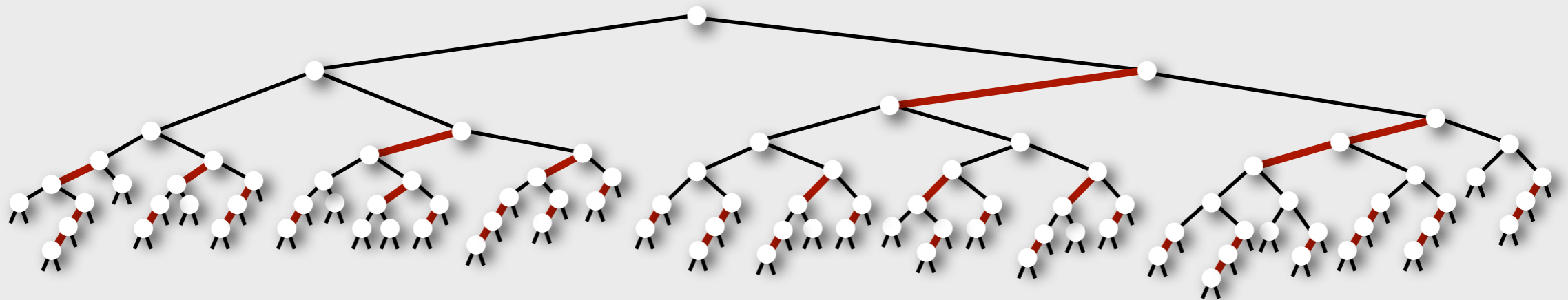
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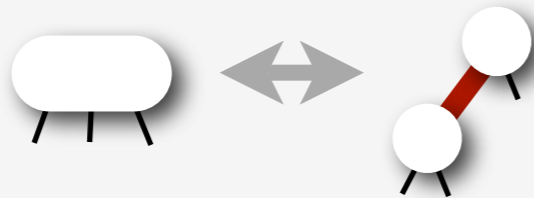
Deletion



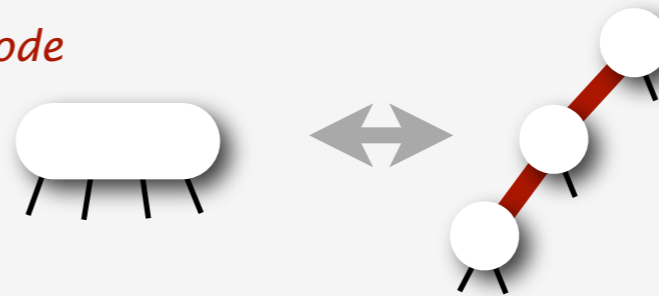
Left-leaning red-black trees

1. Represent 2-3-4 tree as a BST.
2. Use "internal" **left-leaning** edges for 3- and 4- nodes.

3-node

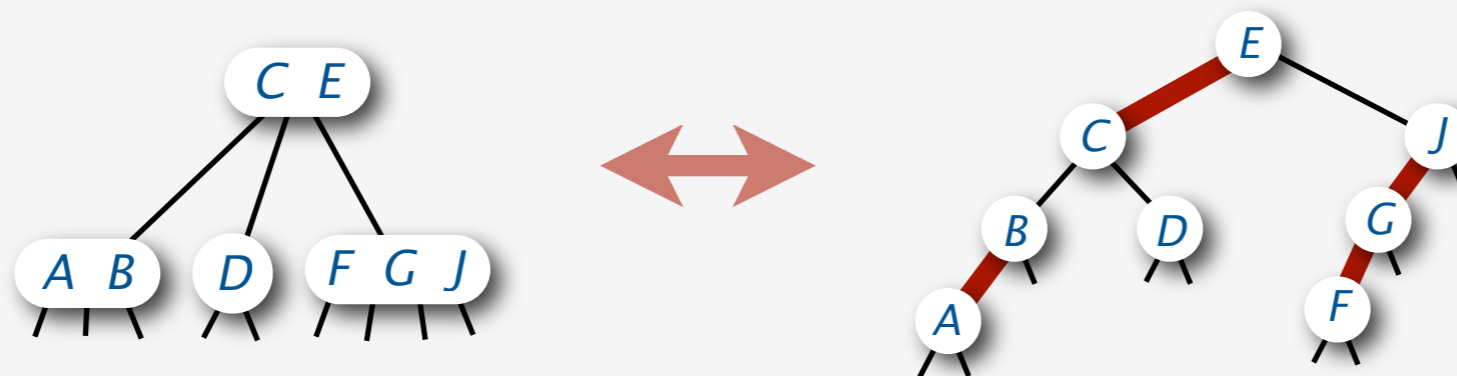


4-node



Key Properties

- elementary BST search works
- easy-to-maintain **1-1** correspondence with 2-3-4 trees



Left-leaning red-black trees

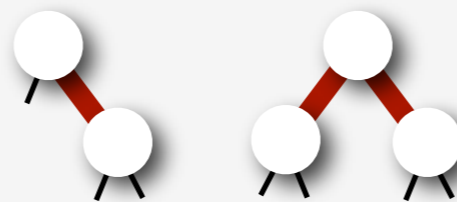
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3-node

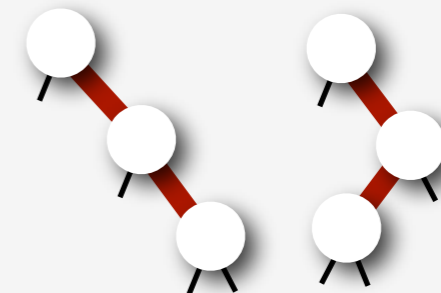


Disallowed

- right-leaning edges

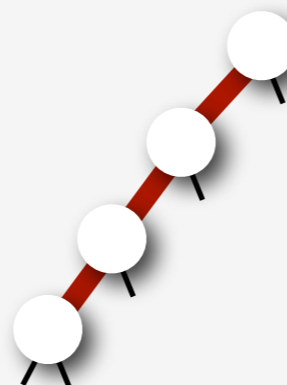


*standard red-black trees
allow these two*



*single-rotation trees
allow these two*

- three reds in a row



Java data structure for red-black trees

adds **one bit for color** to elementary BST data structure

```
public class BST<Key extends Comparable<Key>, Value>
{
    private static final boolean RED    = true;
    private static final boolean BLACK = false;
    private Node root;

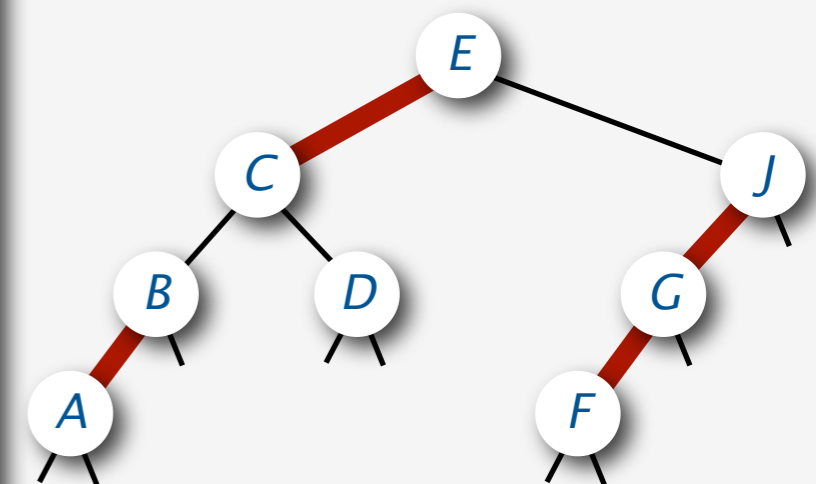
    private class Node
    {
        Key key;
        Value val;
        Node left, right;
        boolean color;
        Node(Key key, Value val, boolean color)
        {
            this.key    = key;
            this.val    = val;
            this.color  = color;
        }
    }

    public Value get(Key key)
    // Search method.

    public void put(Key key, Value val)
    // Insert method.
}
```

constants

color of incoming link



helper method to test node color

```
private boolean isRed(Node x)
{
    if (x == null) return false;
    return (x.color == RED);
}
```

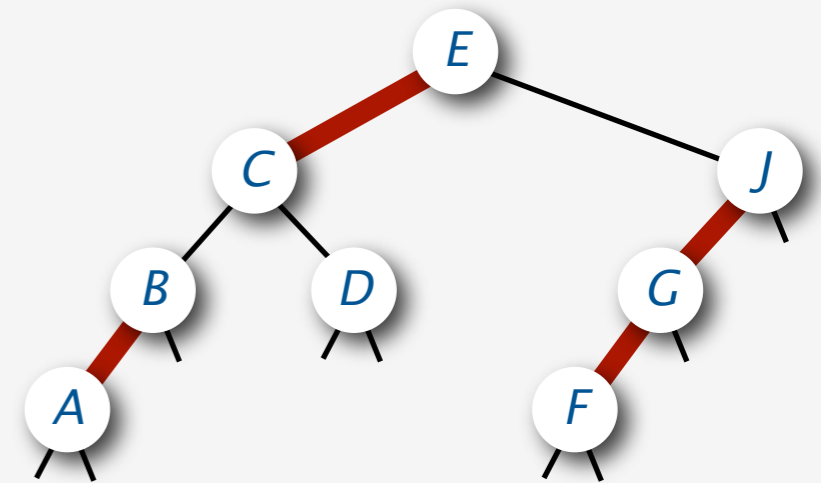
Search implementation for red-black trees

is **the same** as for elementary BSTs

(but typically runs faster because of better balance in the tree).

BST (and LLRB tree) search implementation

```
public Value get(Key key)
{
    Node x = root;
    while (x != null)
    {
        int cmp = key.compareTo(x.key);
        if (cmp == 0) return x.val;
        else if (cmp < 0) x = x.left;
        else if (cmp > 0) x = x.right;
    }
    return null;
}
```



Note: Other BST methods also work

- order statistics
- iteration

Ex: Find the minimum key

```
public Key min()
{
    Node x = root;
    while (x != null) x = x.left;
    if (x == null) return null;
    else return x.key;
}
```

Insert implementation for LLRB trees

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is best expressed in a **recursive** implementation

Recursive insert() implementation for elementary BSTs

```
private Node insert(Node h, Key key, Value val)
{
    if (h == null)
        return new Node(key, val);

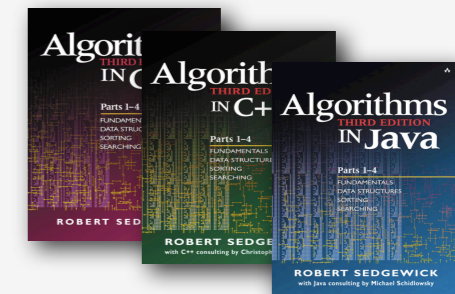
    int cmp = key.compareTo(h.key);
    if (cmp == 0) h.val = val; ← associative model (no duplicate keys)
    else if (cmp < 0)
        h.left = insert(h.left, key, val);
    else
        h.right = insert(h.right, key, val);

    return h;
}
```

Nonrecursive



Recursive



Note: effectively travels down the tree and then up the tree.

- simplifies correctness proof
- simplifies code for balanced BST implementations
- could remove recursion to get single-pass algorithm

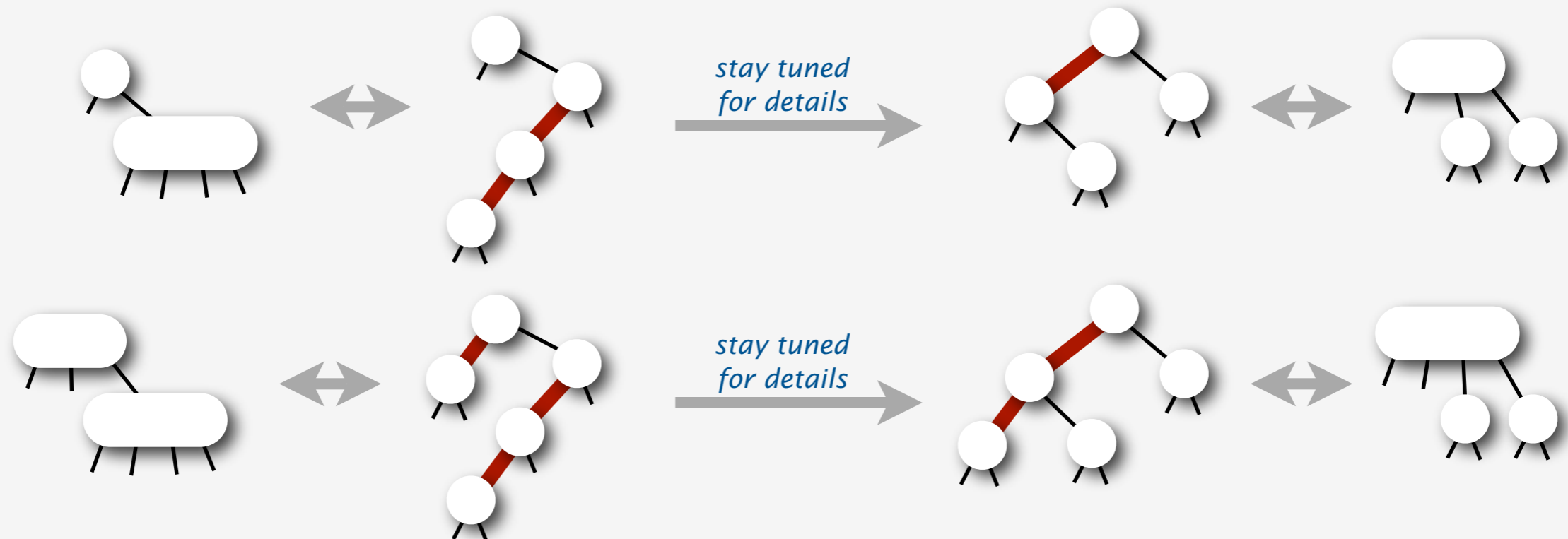
Insert implementation for LLRB trees

follows directly from 1-1 correspondence with 2-3-4 trees

1. If key found on recursive search, reset value, as usual.
2. If key not found, insert at the bottom.



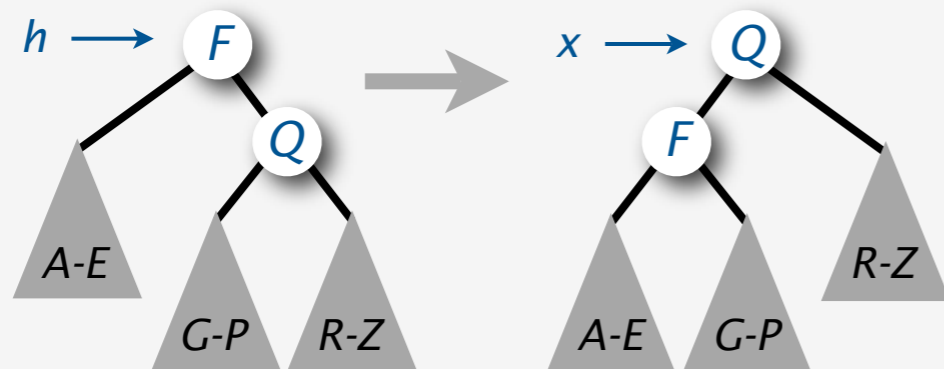
3. Split 4-nodes on the way down



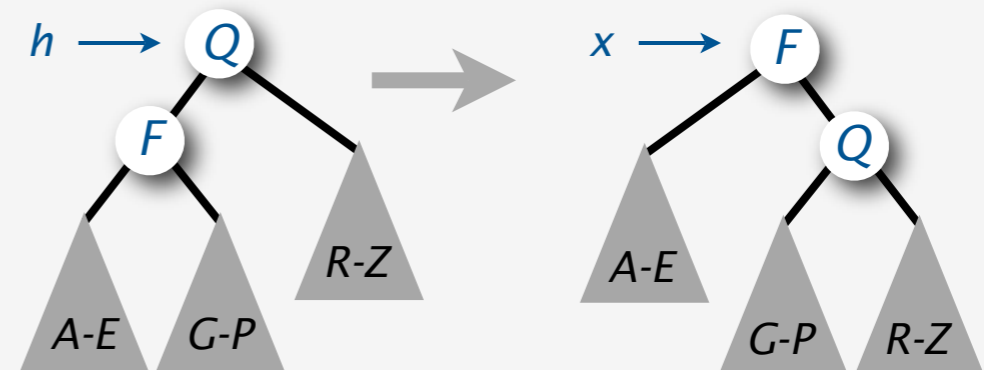
Balanced tree code

is based on local transformations known as **rotations**

```
private Node rotL(Node h)
{
    Node x = h.right;
    h.right = x.left;
    x.left = h;
    return x;
}
```



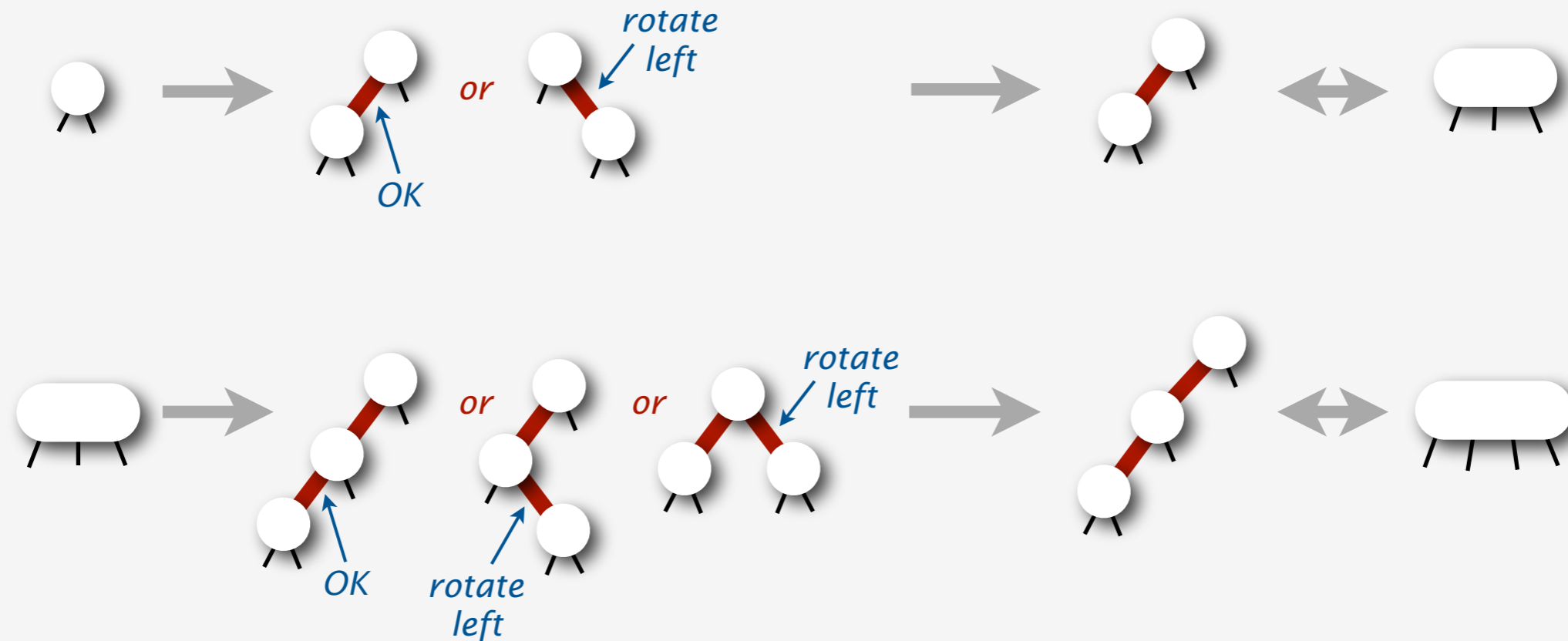
```
private Node rotR(Node h)
{
    Node x = h.left;
    h.left = x.right;
    x.right = h;
    return x;
}
```



Insert a new node at the bottom in a LLRB tree

follows directly from 1-1 correspondence with 2-3-4 trees

1. Add new node as usual, with **red** link to glue it to node above
2. **Rotate left if necessary** to make link lean left

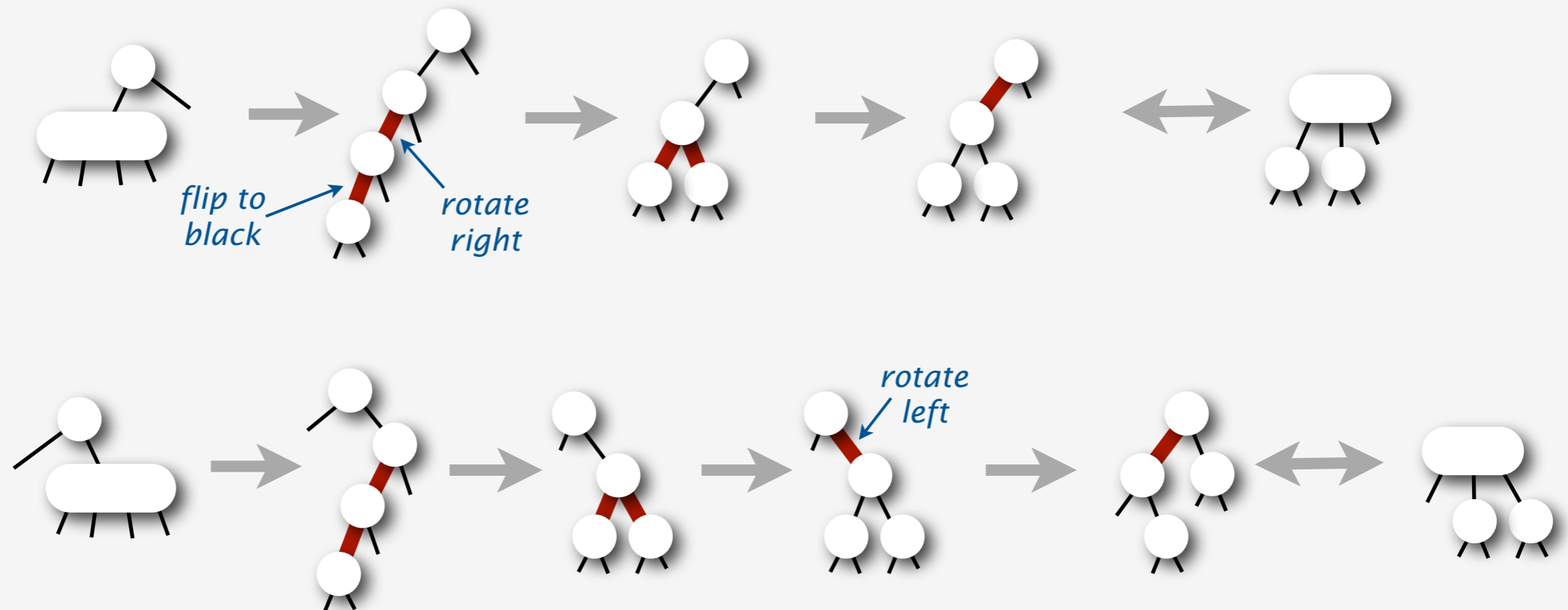


Splitting a 4-node in a LLRB tree

follows directly from 1-1 correspondence with 2-3-4 trees

1. Rotate **right** to balance the 4-node
2. Flip colors to pass **red** link up one level
3. **Rotate left if necessary** to make link lean left

Parent is a 2-node: two cases

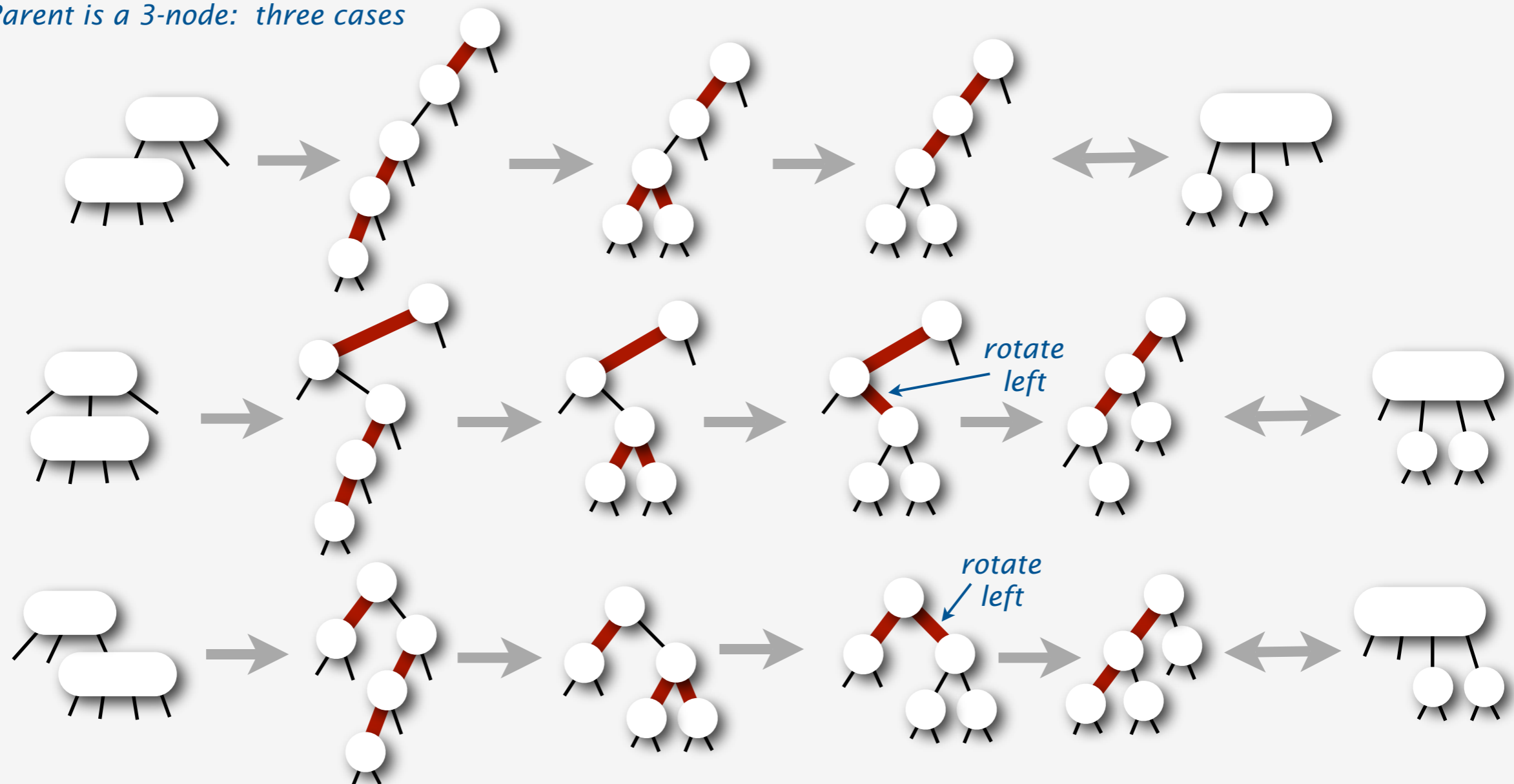


Splitting a 4-node in a LLRB tree

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Parent is a 3-node: three cases

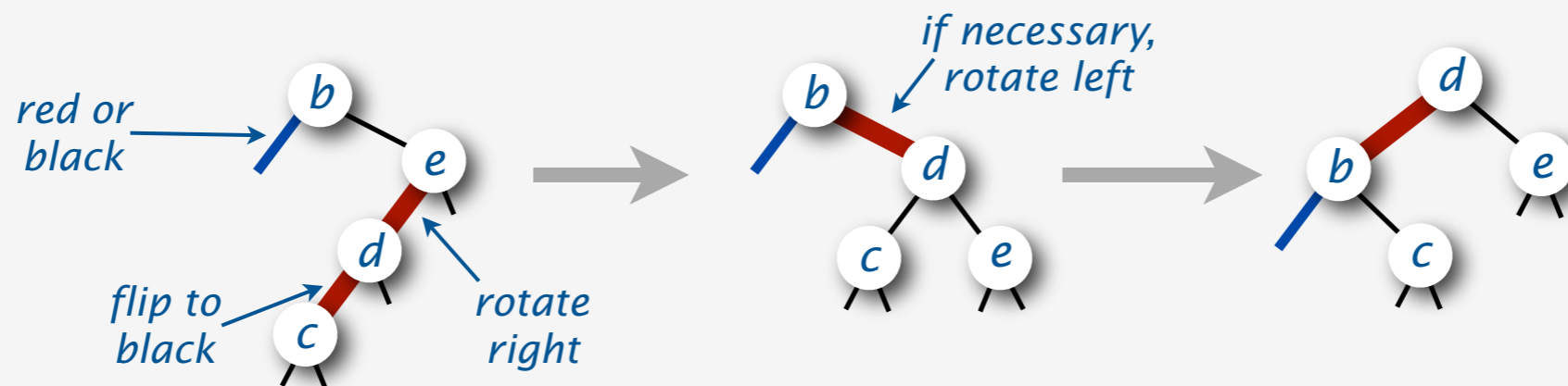


Splitting a 4-node in a LLRB tree

follows directly from 1-1 correspondence with 2-3-4 trees

1. Rotate **right** to balance the 4-node
2. Flip colors to pass **red** link up one level
3. **Rotate left if necessary** to make link lean left

Key point: The transformations are all **the same**.

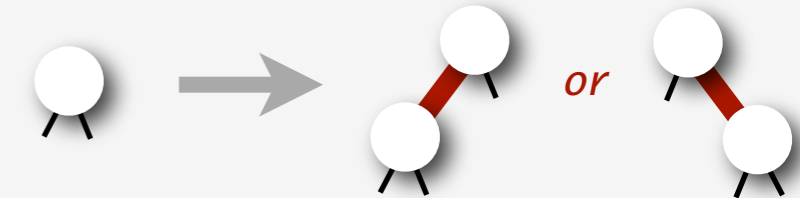


Inserting and splitting nodes in LLRB trees

are easier when left rotates are done on the way **up** the tree.

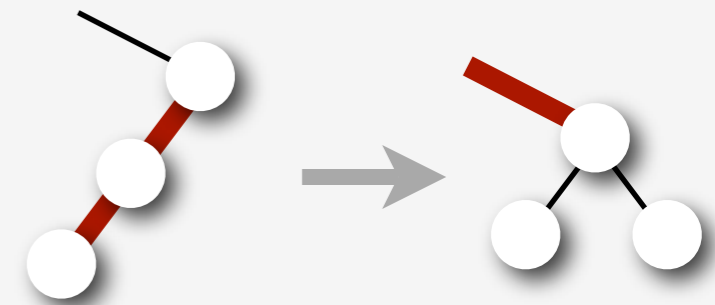
Search as usual

- if key found reset value, as usual
- if key not found insert a new red node at the bottom
[might be right-leaning red link]



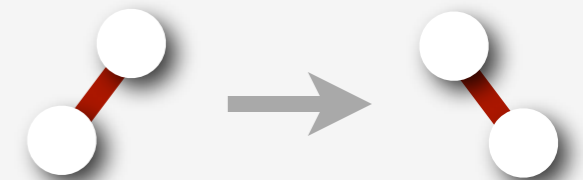
Split 4-nodes on the way down the tree.

- right-rotate and flip color
- might leave right-leaning link higher up in the tree



NEW TRICK: enforce left-leaning condition on the way up the tree.

- left-rotate any right-leaning link on search path
- trivial with recursion (do it after recursive calls)
- no other right-leaning links elsewhere



Insert code for LLRB trees

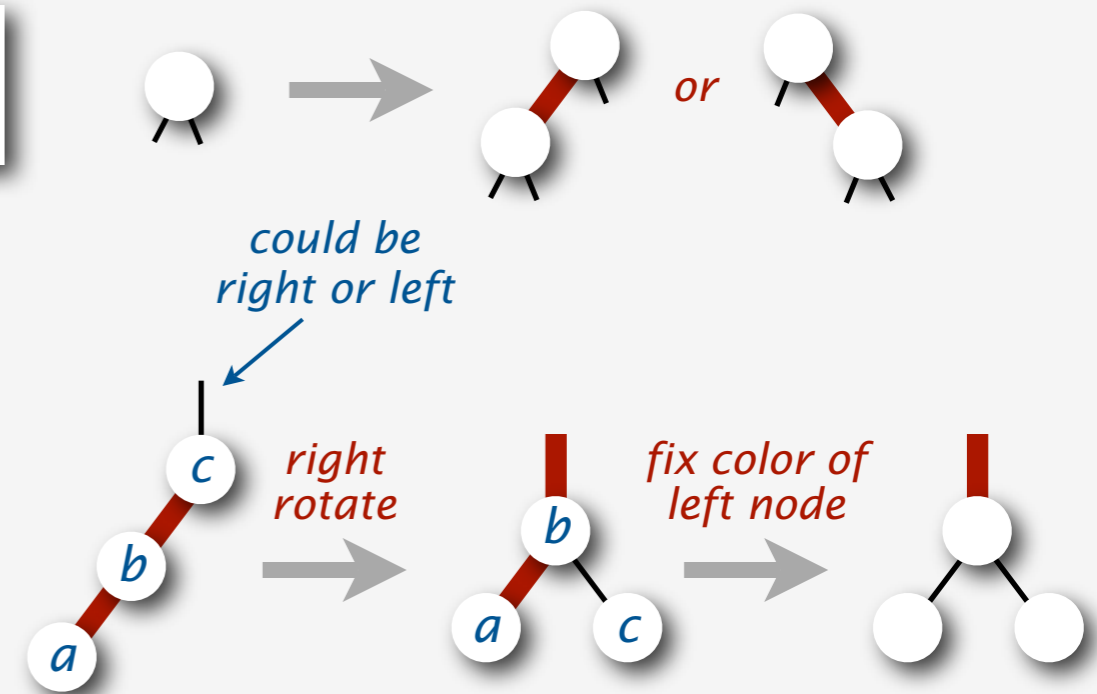
is based on three simple operations.

1. Insert a new node at the bottom.

```
if (h == null)
    return new Node(key, value, RED);
```

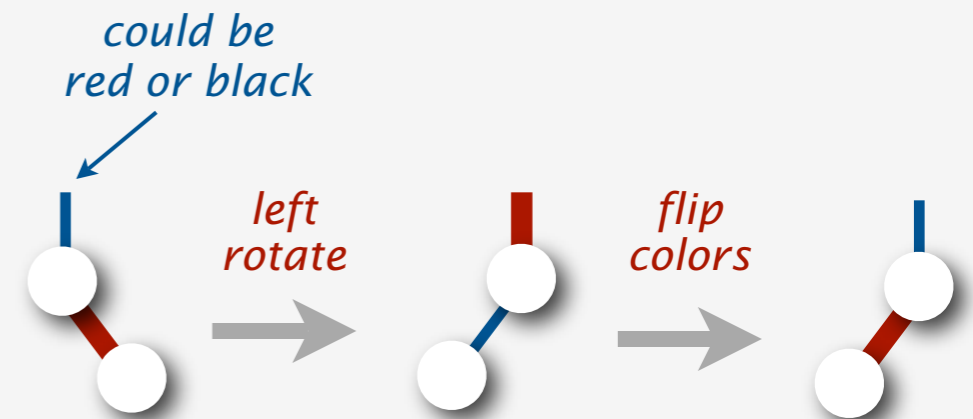
2. Split a 4-node.

```
private Node splitFourNode(Node h)
{
    x = rotR(h);
    x.left.color = BLACK;
    return x;
}
```



3. Enforce left-leaning condition.

```
private Node leanLeft(Node h)
{
    x = rotL(h);
    x.color = x.left.color;
    x.left.color = RED;
    return x;
}
```



Insert implementation for LLRB trees

is a few lines of code added to elementary BST insert

```
private Node insert(Node h, Key key, Value val)
{
    if (h == null)
        return new Node(key, val, RED);

    if (isRed(h.left))
        if (isRed(h.left.left))
            h = splitFourNode(h);

    int cmp = key.compareTo(h.key);
    if (cmp == 0) h.val = val;
    else if (cmp < 0)
        h.left = insert(h.left, key, val);
    else
        h.right = insert(h.right, key, val);

    if (isRed(h.right))
        h = leanLeft(h);

    return h;
}
```

← insert at the bottom

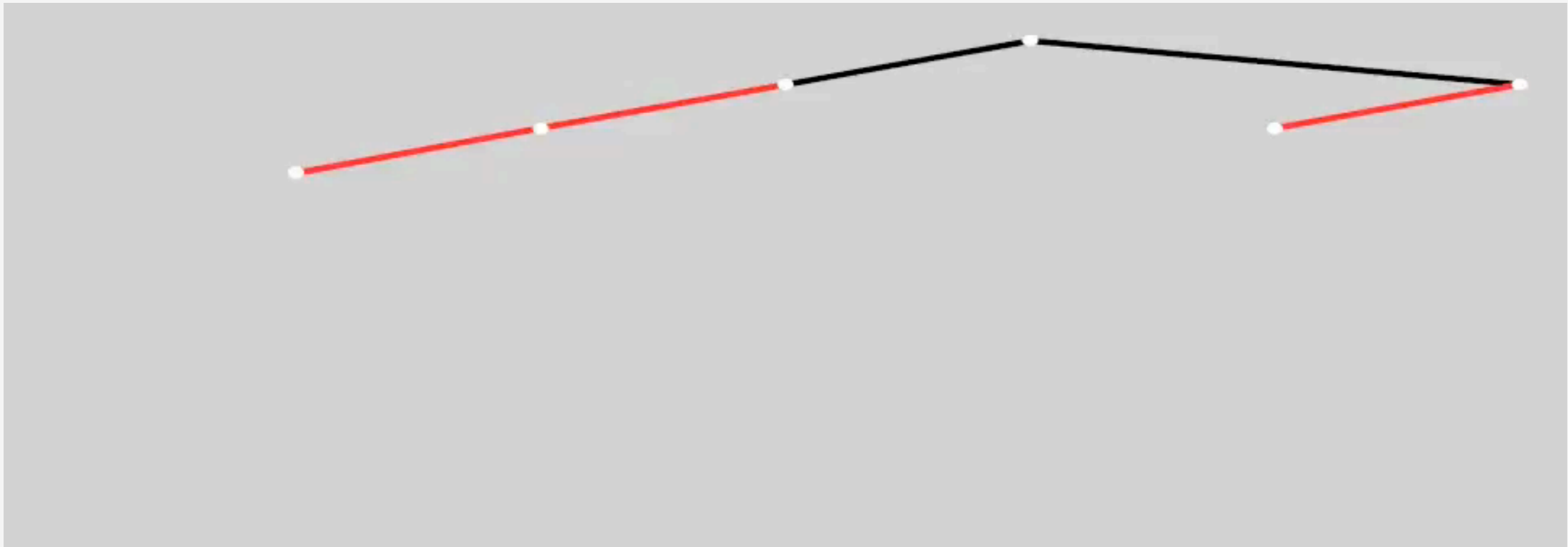
← split 4-nodes on the way down

← standard BST insert code

← fix right-leaning reds on the way up

LLRB insert movie

- Introduction*
- 2-3-4 Trees*
- Red-Black Trees*
- Left-Leaning RB Trees*
- Deletion*



Why revisit red-black trees?

Take your pick:

```
private Node insert(Node x, Key key, Value val, boolean sw)
{
    if (x == null)
        return new Node(key, value, RED);
    int cmp = key.compareTo(x.key);

    if (isRed(x.left) && isRed(x.right))
    {
        x.color = RED;
        x.left.color = BLACK;
        x.right.color = BLACK;
    }
    if (cmp == 0) x.val = val;
    else if (cmp < 0)
    {
        x.left = insert(x.left, key, val, false);
        if (isRed(x) && isRed(x.left) && sw)
            x = rotR(x);
        if (isRed(x.left) && isRed(x.left.left))
        {
            x = rotR(x);
            x.color = BLACK; x.right.color = RED;
        }
    }
    else // if (cmp > 0)
    {
        x.right = insert(x.right, key, val, true);
        if (isRed(h) && isRed(x.right) && !sw)
            x = rotL(x);
        if (isRed(h.right) && isRed(h.right.right))
        {
            x = rotL(x);
            x.color = BLACK; x.left.color = RED;
        }
    }
    return x;
}
```



```
private Node insert(Node h, Key key, Value val)
{
    int cmp = key.compareTo(h.key);
    if (h == null)
        return new Node(key, val, RED);
    if (isRed(h.left))
        if (isRed(h.left.left))
        {
            h = rotR(h);
            h.left.color = BLACK;
        }
    if (cmp == 0) x.val = val;
    else if (cmp < 0)
        h.left = insert(h.left, key, val);
    else
        h.right = insert(h.right, key, val);
    if (isRed(h.right))
    {
        h = rotL(h);
        h.color = h.left.color;
        h.left.color = RED;
    }
    return h;
}
```

**Left-Leaning
Red-Black Trees**

Robert Sedgwick
Princeton University

↑
straightforward

←
*very
tricky*

Why revisit red-black trees?

- Introduction
- 2-3-4 Trees
- Red-Black Trees
- Left-Leaning RB Trees
- Deletion

Take your pick:

TreeMap.java

Adapted from
CLR by
experienced
professional
programmers
(2004)



150

wrong scale!

Why left-leaning trees?

Take your pick:

```
private Node insert(Node x, Key key, Value val, boolean sw)
{
    if (x == null)
        return new Node(key, value, RED);
    int cmp = key.compareTo(x.key);
    if (isRed(x.left) && isRed(x.right))
    {
        x.color = RED;
        x.left.color = BLACK;
        x.right.color = BLACK;
    }
    if (cmp == 0) x.val = val;
    else if (cmp < 0)
    {
        x.left = insert(x.left, key, val, false);
        if (isRed(x) && isRed(x.left) && sw)
            x = rotR(x);
        if (isRed(x.left) && isRed(x.left.left))
        {
            x = rotR(x);
            x.color = BLACK; x.right.color = RED;
        }
    }
    else // if (cmp > 0)
    {
        x.right = insert(x.right, key, val, true);
        if (isRed(h) && isRed(x.right) && !sw)
            x = rotL(x);
        if (isRed(h.right) && isRed(h.right.right))
        {
            x = rotL(x);
            x.color = BLACK; x.left.color = RED;
        }
    }
    return x;
}
```



```
private Node insert(Node h, Key key, Value val)
{
    int cmp = key.compareTo(h.key);
    if (h == null)
        return new Node(key, val, RED);
    if (isRed(h.left))
        if (isRed(h.left.left))
        {
            h = rotR(h);
            h.left.color = BLACK;
        }
    if (cmp == 0) x.val = val;
    else if (cmp < 0)
        h.left = insert(h.left, key, val);
    else
        h.right = insert(h.right, key, val);
    if (isRed(h.right))
    {
        h = rotL(h);
        h.color = h.left.color;
        h.left.color = RED;
    }
    return h;
}
```

Left-Leaning
Red-Black Trees
Robert Sedgwick
Princeton University

straightforward

very
tricky



40

Left-Leaning
Red-Black Trees
Robert Sedgwick
Princeton University

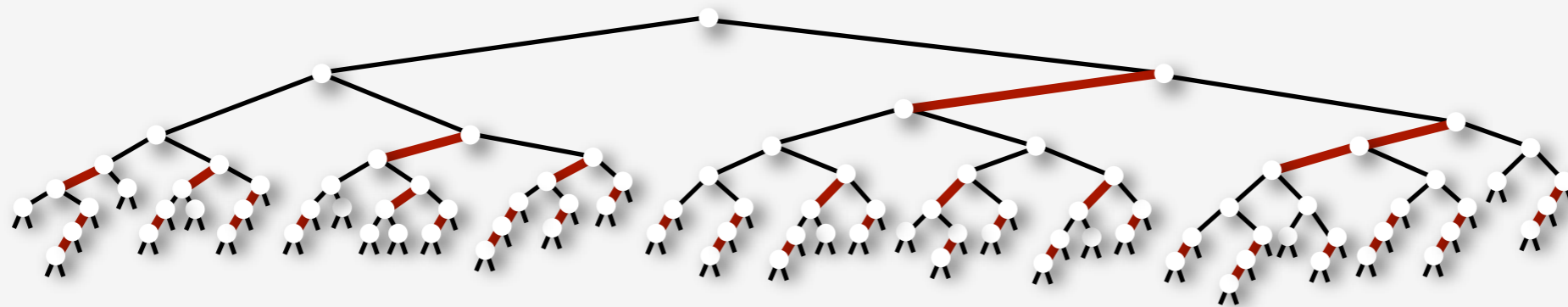
30

← lines of code for insert
(lower is better!)

Why revisit red-black trees?

LLRB implementation is **far simpler** than previous attempts.

- left-leaning restriction reduces number of cases
- recursion gives two (easy) chances to fix each node
- short inner loop more than compensates for slight increase in height



Improves widely used algorithms

- AVL, 2-3, and 2-3-4 trees
- red-black trees

Same ideas simplify implementation of other operations

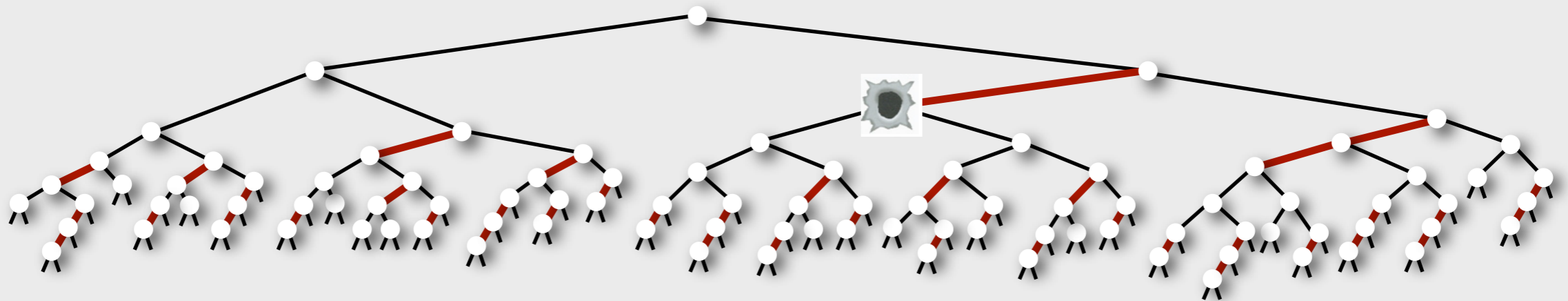
- delete min, max
- arbitrary delete

2008

1978

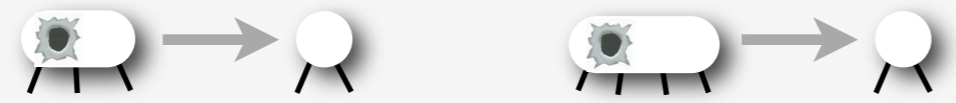
1972

Introduction
2-3-4 Trees
Red-Black Trees
Left-Leaning RB Trees
Deletion

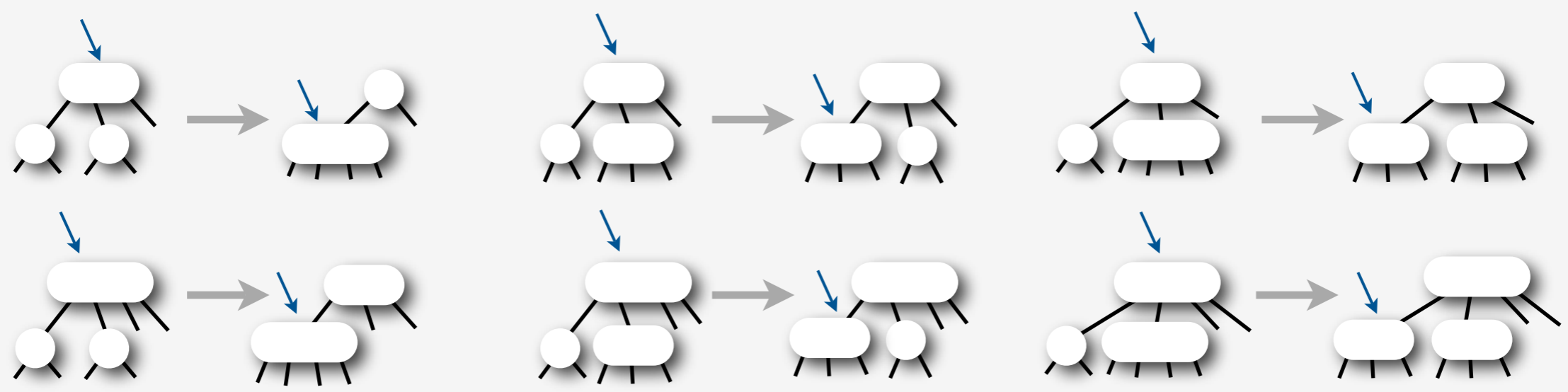


Warmup 1: delete the minimum

1. Search down the left spine of the tree.
2. If search ends in a 3-node or 4-node: just remove it.



3. Removing a 2-node would destroy balance
 - transform tree on the way down the search path
 - Invariant: current node is not a 2-node



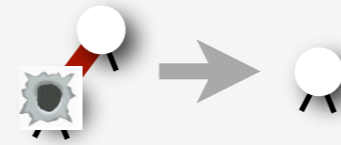
Note: LLRB representation reduces number of cases (as for insert)

Warmup 1: delete the minimum

Carry a red link **down** the left spine of the tree.

Invariant: either **h** or **h.left** is **RED**

Implication: deletion easy at bottom

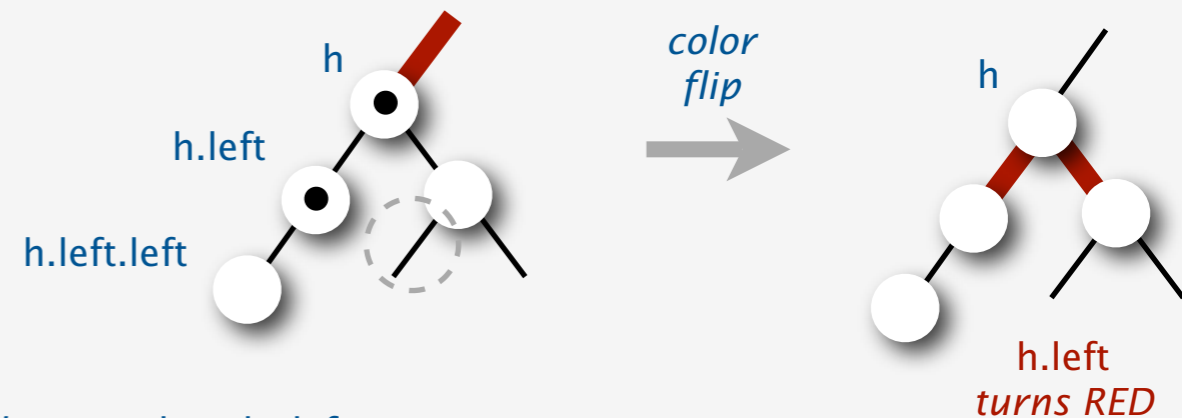


Need to adjust tree only when **h.left** and **h.left.left** are both **BLACK**

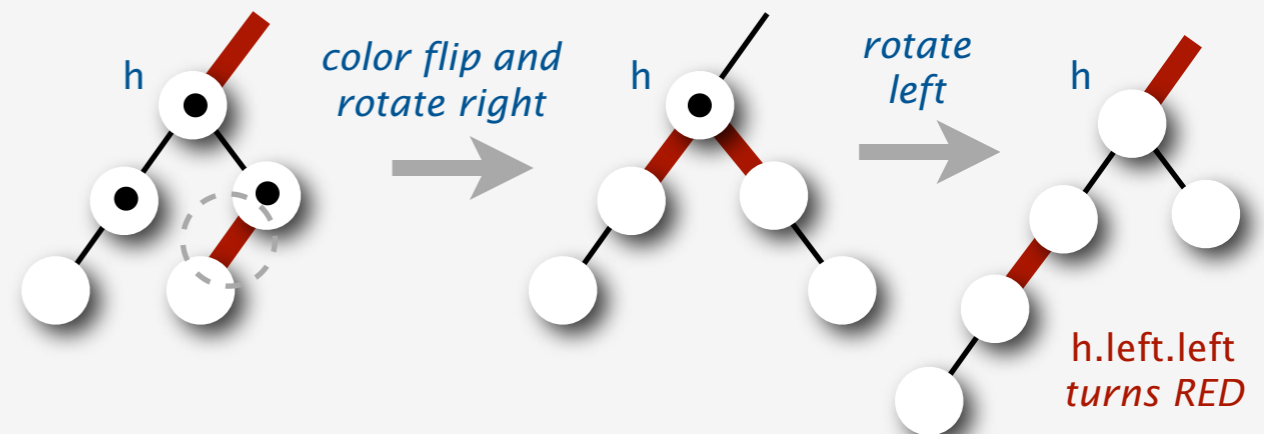
Two cases, depending on color of **h.right.left**

```
private Node moveRedLeft(Node h)
{
    h.color = BLACK;
    h.left.color = RED;
    if (isRed(h.right.left))
    {
        h.right = rotR(h.right);
        h = rotL(h);
    }
    else h.right.color = RED;
    return h;
}
```

Easy case: **h.right.left** is **BLACK**



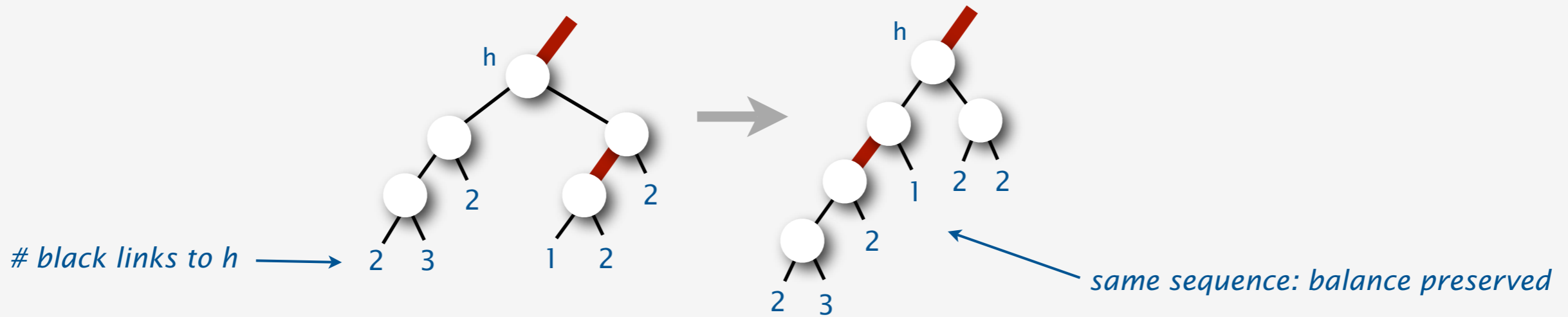
Harder case: **h.right.left** is **RED**



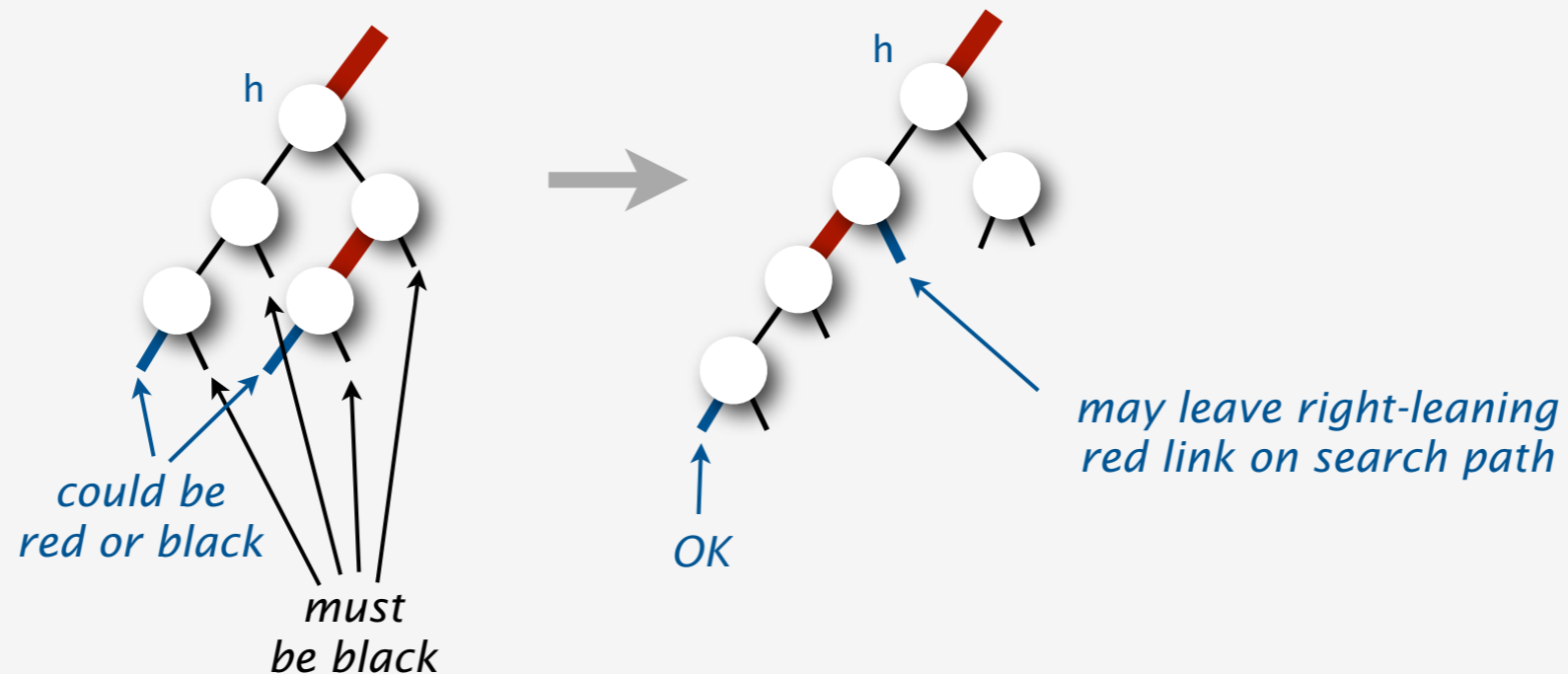
Leaving right red links on the search path

simplifies the code, complicates the proof.

1. Does each transformation preserve balance?



2. Does each transformation preserve correspondence with 2-3-4 trees?



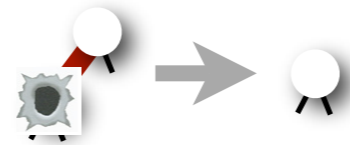
deleteMin() implementation for LLRB trees

is otherwise **a few lines of code**

```
public void deleteMin()  
{  
    root = deleteMin(root);  
    root.color = BLACK;  
}
```

```
private Node deleteMin(Node h)  
{
```

```
    if (h.left == null)  
        return null;
```



*remove node on bottom level
(h must be RED by invariant)*

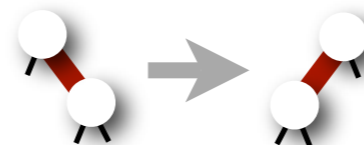
```
    if (!isRed(h.left) && !isRed(h.left.left))  
        h = moveRedLeft(h);
```

push red link down if necessary

```
    h.left = deleteMin(h.left);
```

move down one level

```
    if (isRed(h.right))  
        h = leanLeft(h);
```



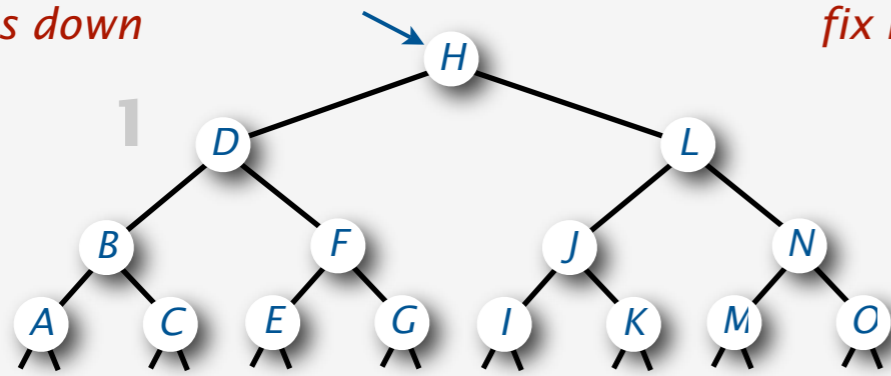
*fix right-leaning red links
on the way up the tree*

```
    return h;
```

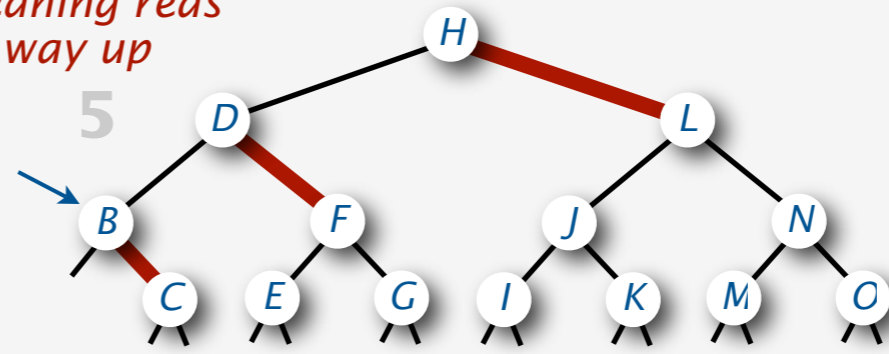
```
}
```

deleteMin() example

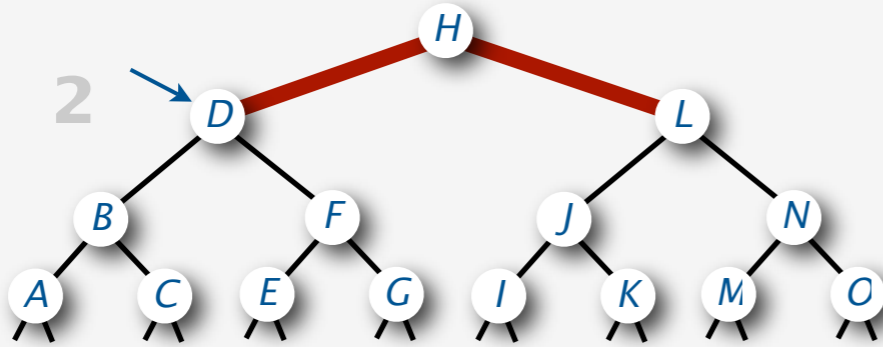
push reds down



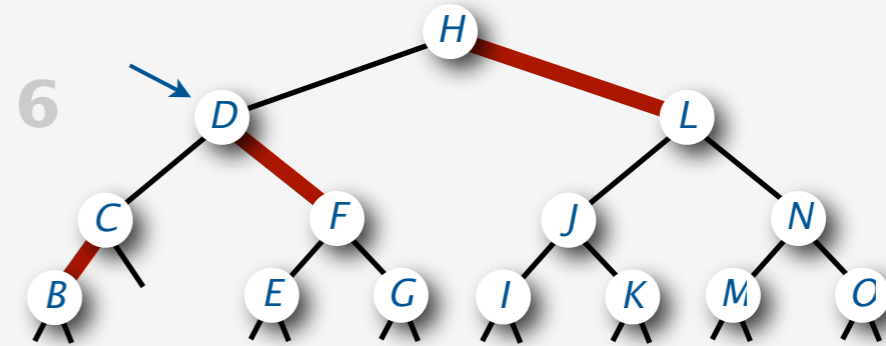
fix right-leaning reds on the way up



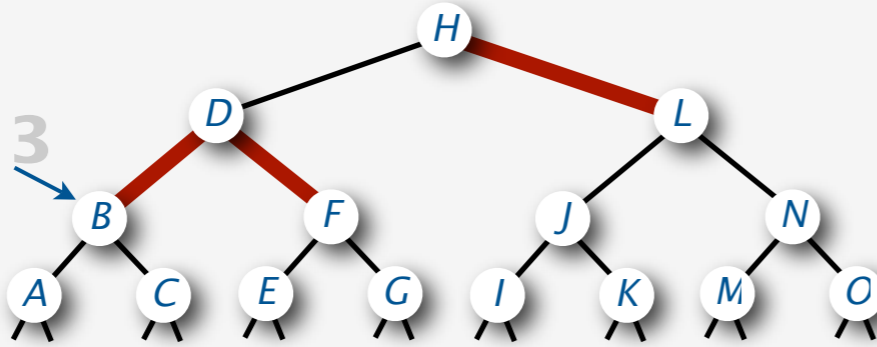
2



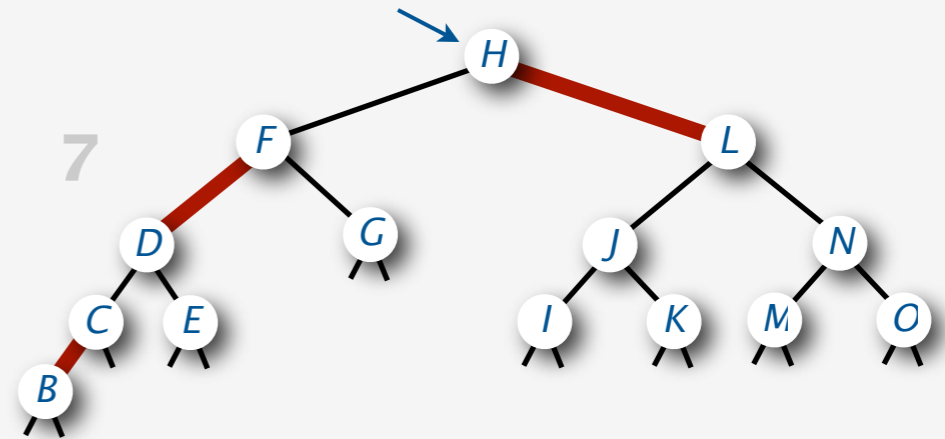
6



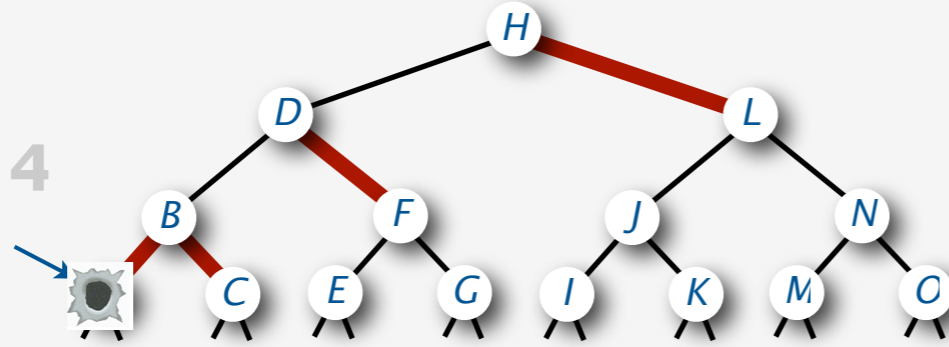
3



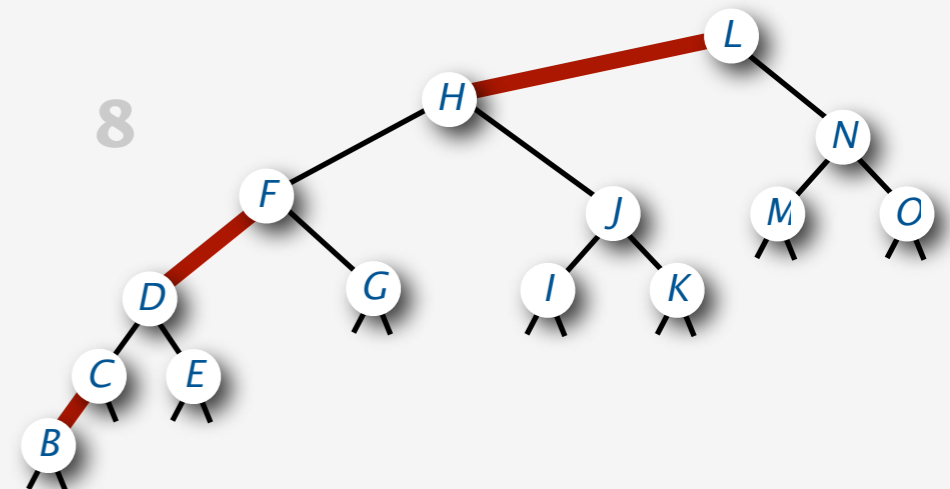
7



4

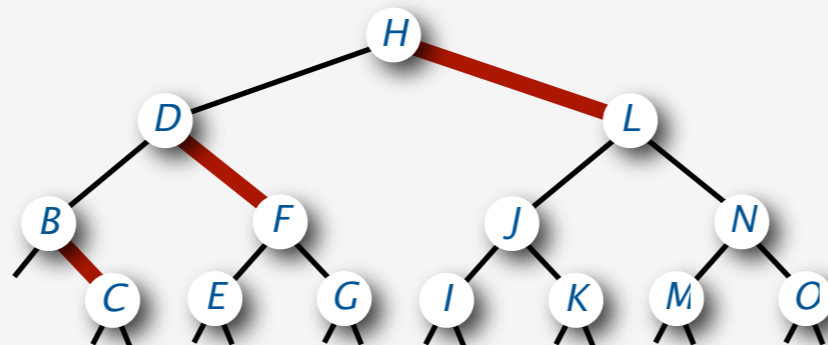


8



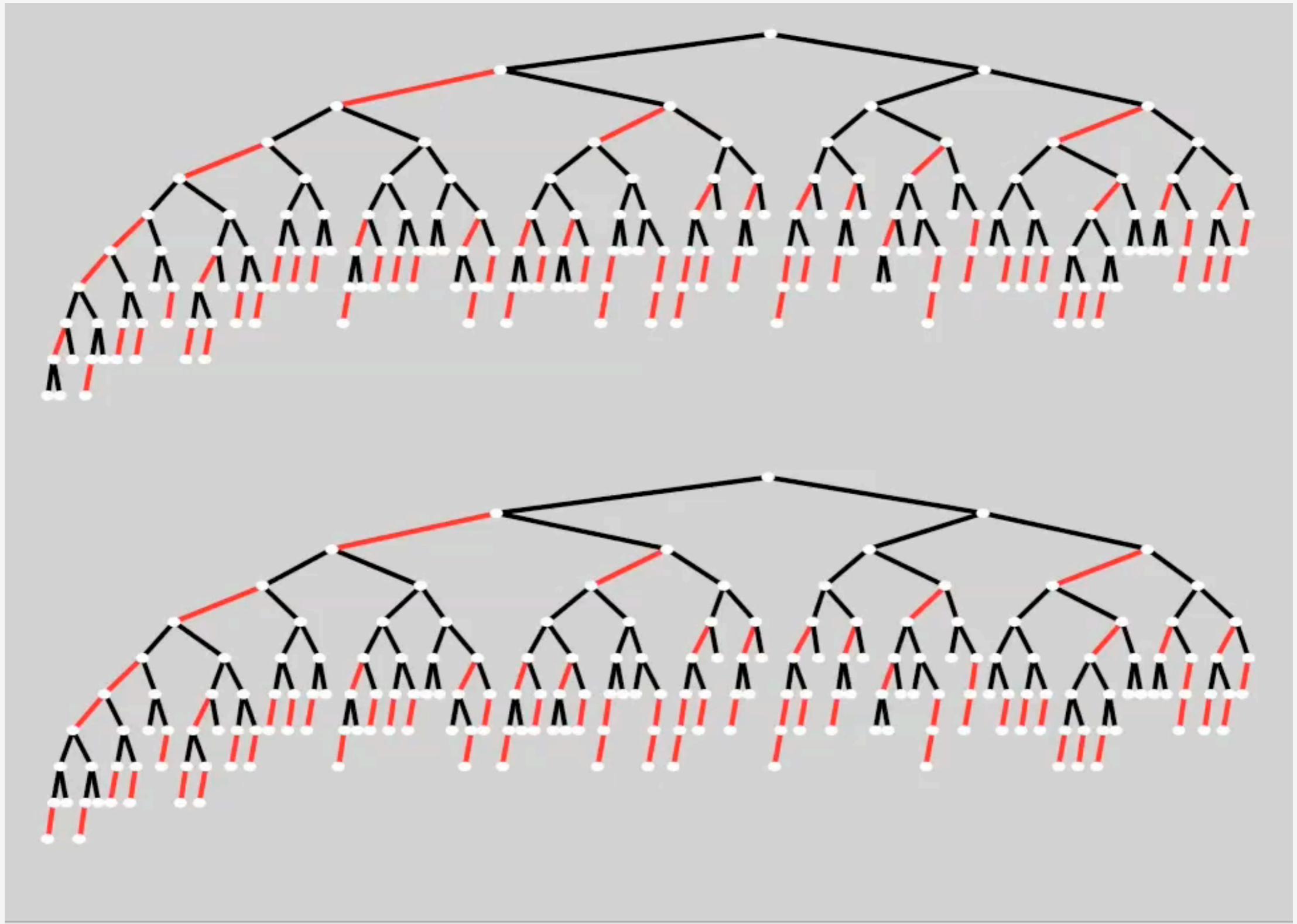
remove minimum

5



LLRB deleteMin() movie

- Introduction
- 2-3-4 Trees
- Red-Black Trees
- Left-Leaning RB Trees
- Deletion



Warmup 2: delete the maximum

is similar, but slightly different (since trees lean left).

```
private Node deleteMax(Node h)
{
  if (h.right == null)
  {
    if (h.left != null)
      h.left.color = BLACK;
    return h.left;
  }

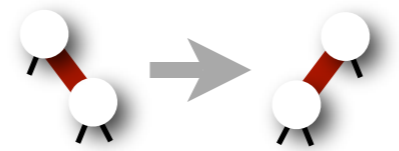
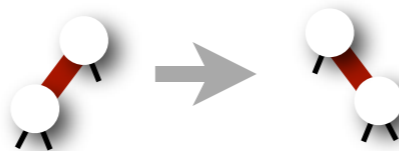
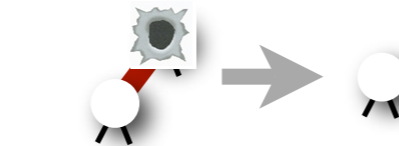
  if (isRed(h.left))
    h = leanRight(h);

  if (!isRed(h.right)
      && !isRed(h.right.left))
    h = moveRedRight(h);

  h.right = deleteMax(h.right);

  if (isRed(h.right))
    h = leanLeft(h);

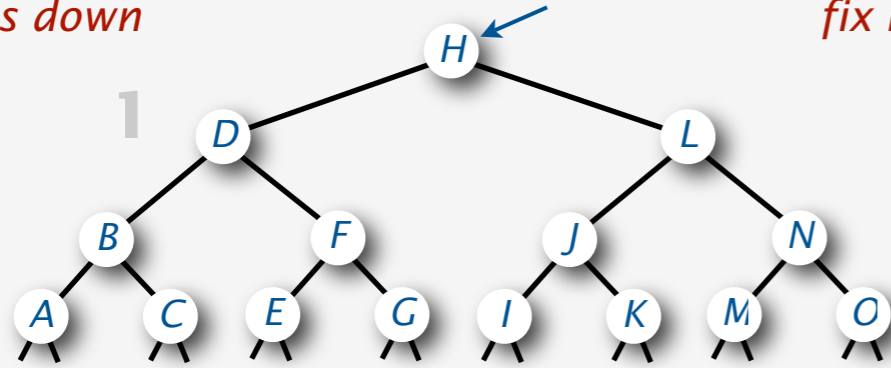
  return h;
}
```



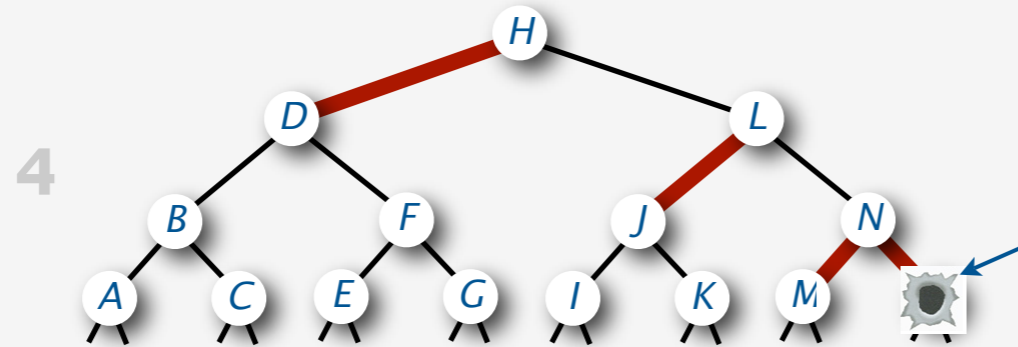
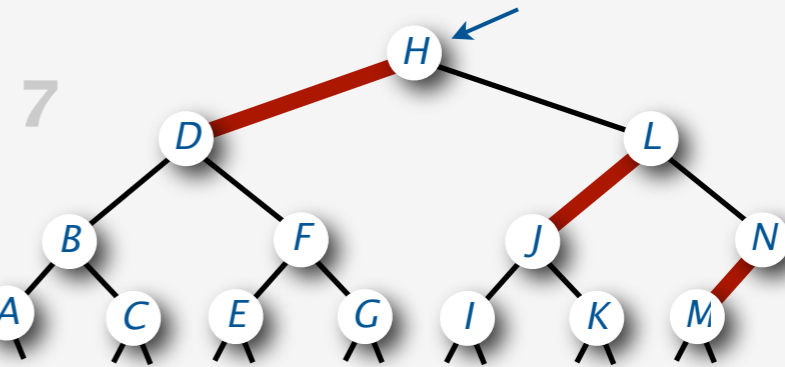
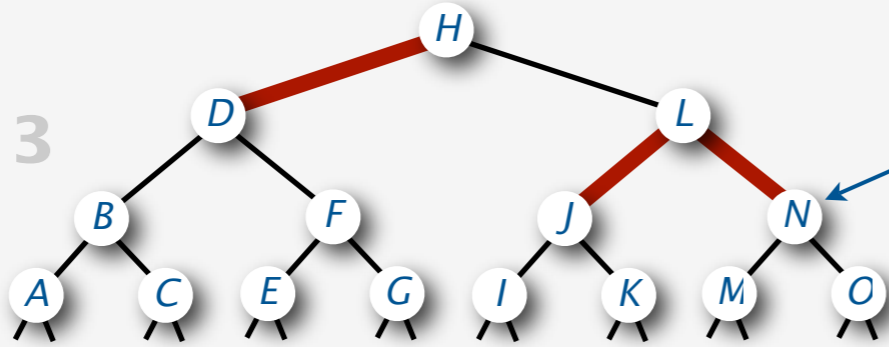
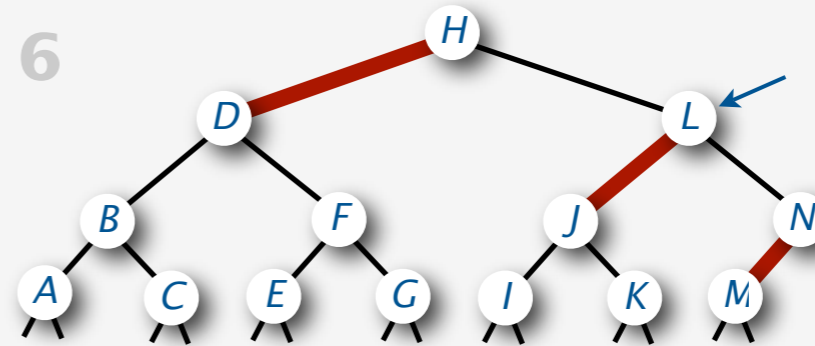
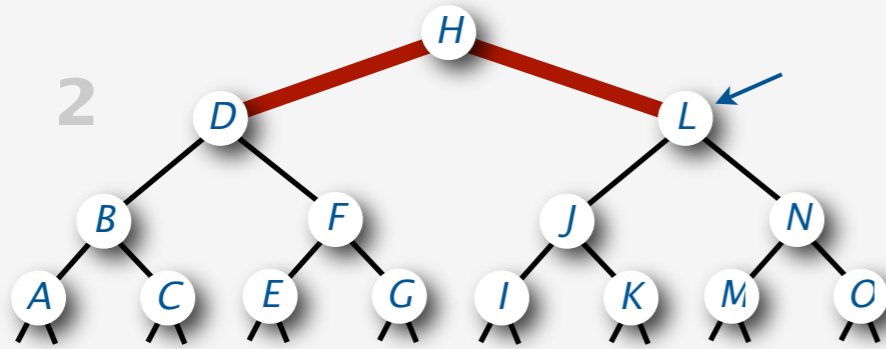
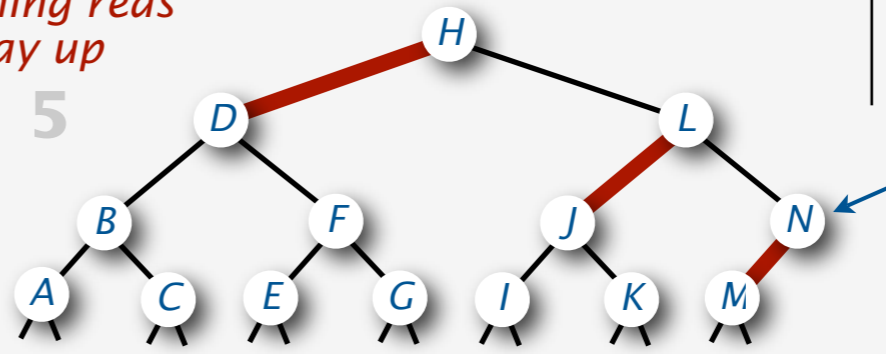
```
private Node moveRedRight(Node h)
{
  h.color = BLACK;
  h.right.color = RED;
  if (isRed(h.left.left))
  {
    h = rotR(h);
    h.color = RED;
    h.left.color = BLACK;
  }
  else h.left.color = RED;
  return h;
}
```


deleteMax() example

push reds down

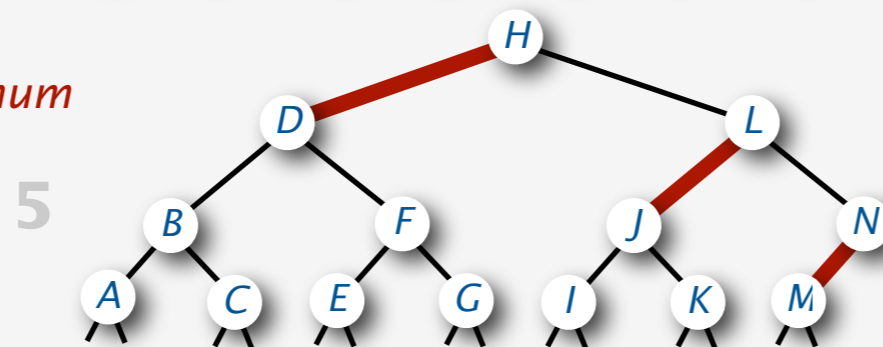


fix right-leaning reds on the way up



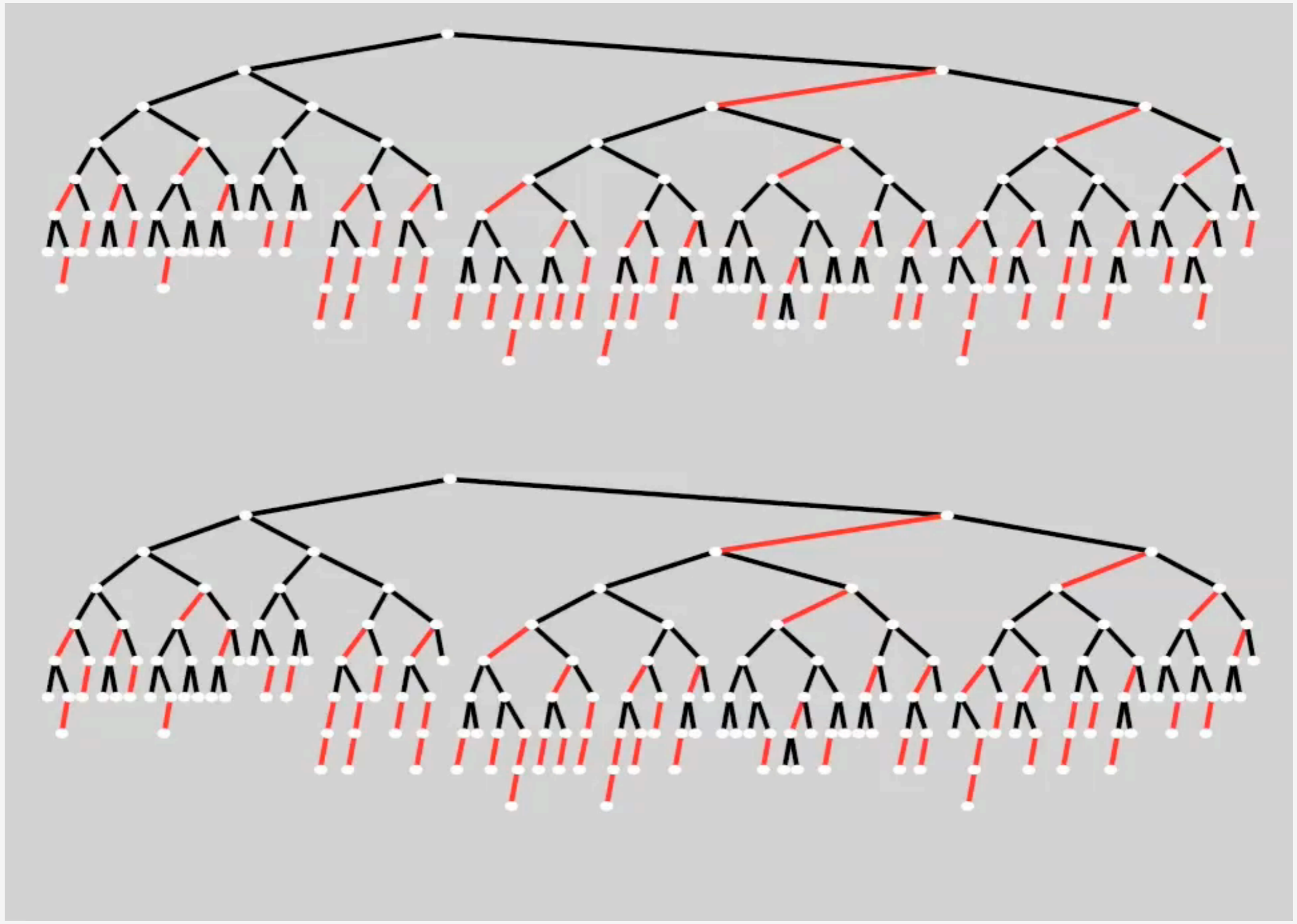
(nothing to fix!)

remove maximum



LLRB deleteMax() movie

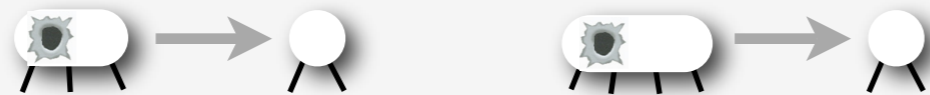
- Introduction
- 2-3-4 Trees
- Red-Black Trees
- Left-Leaning RB Trees
- Deletion



Deleting an arbitrary node

involves the same general strategy.

1. Search down the left spine of the tree.
2. If search ends in a 3-node or 4-node: just remove it.



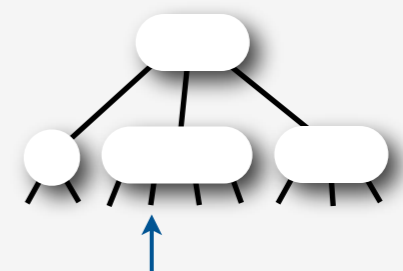
3. Removing a 2-node would destroy balance
 - transform tree on the way down the search path
 - Invariant: current node is not a 2-node

Difficulty:

- Far too many cases!
- LLRB representation **dramatically** reduces the number of cases.

Q: How many possible search paths in **two** levels ?

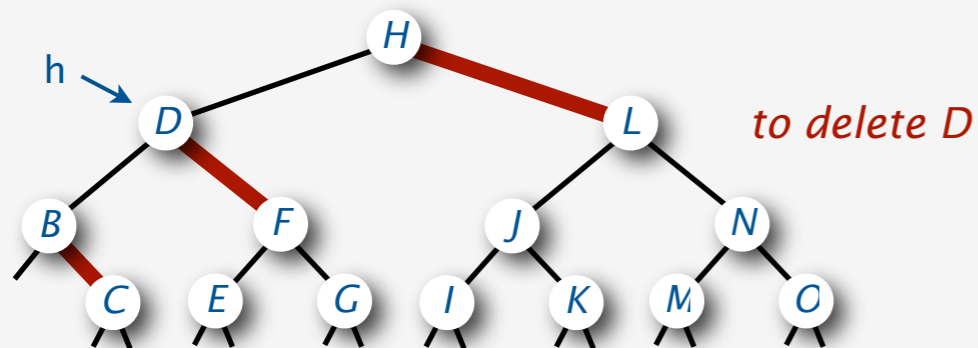
A: $9 * 6 + 27 * 9 + 81 * 12 = 1269$ (!!)



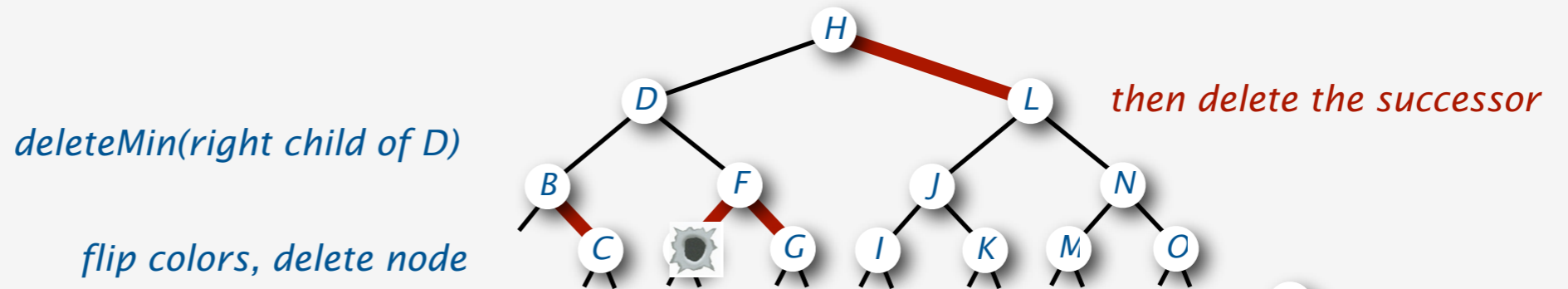
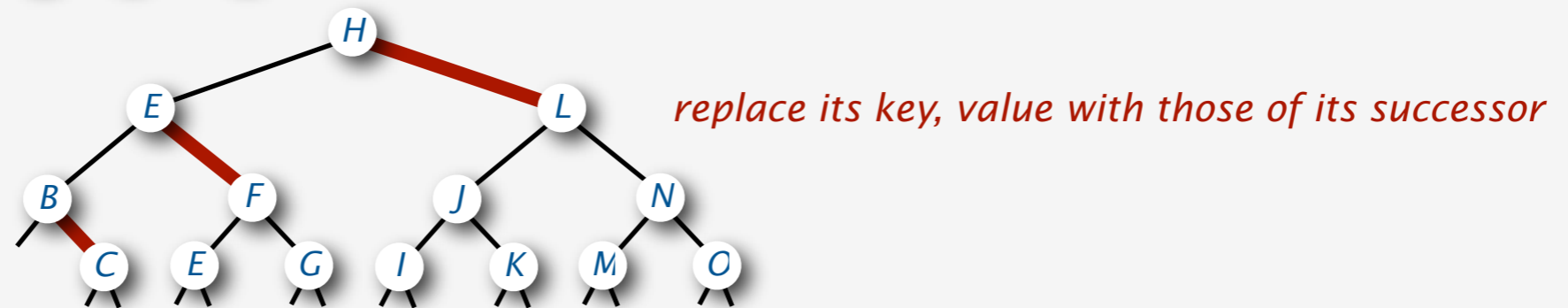
Deleting an arbitrary node

reduces to deleteMin()

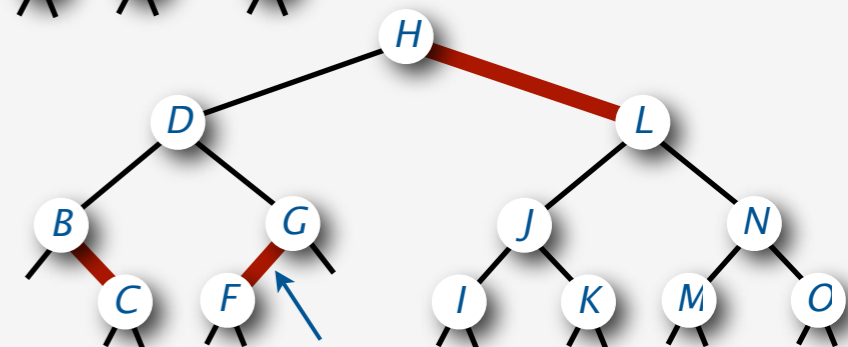
A standard trick:



```
h.key = min(h.right);  
h.value = get(h.right, h.key);  
h.right = deleteMin(h.right);
```



fix right-leaning red link

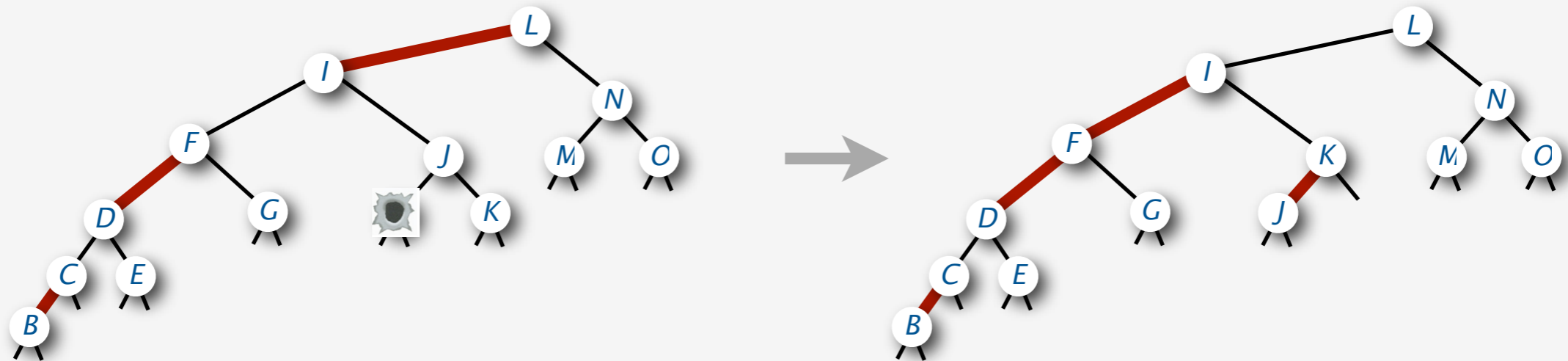


Deleting an arbitrary node at the bottom

can be implemented with the **same** helper methods used for `deleteMin()` and `deleteMax()`.

Invariant: **h** or one of its children is **RED**

- search path goes left: use `moveRedLeft()`.
- search path goes right: use `moveRedRight()`.
- delete node at bottom
- fix right-leaning reds on the way up



A few loose ends remain . . . et voilà! (see next page)

delete() implementation for LLRB trees

Introduction
2-3-4 Trees
Red-Black Trees
Left-Leaning RB Trees
Deletion

```
private Node delete(Node h, Key key)
{
    int cmp = key.compareTo(h.key);
    if (cmp < 0)
    {
        if (!isRed(h.left) && !isRed(h.left.left))
            h = moveRedLeft(h);
        h.left = delete(h.left, key);
    }
    else
    {
        if (isRed(h.left)) h = leanRight(h);

        if (cmp == 0 && (h.right == null))
            return null;

        if (!isRed(h.right) && !isRed(h.right.left))
            h = moveRedRight(h);

        if (cmp == 0)
        {
            h.key = min(h.right);
            h.value = get(h.right, h.key);
            h.right = deleteMin(h.right);
        }
        else h.right = delete(h.right, key);
    }
    if (isRed(h.right)) h = leanLeft(h);

    return h;
}
```

LEFT

push red right if necessary

move down (left)

RIGHT or EQUAL

rotate to push red right

*EQUAL (at bottom)
delete node*

push red right if necessary

EQUAL (not at bottom)

*replace current node with
successor key, value*

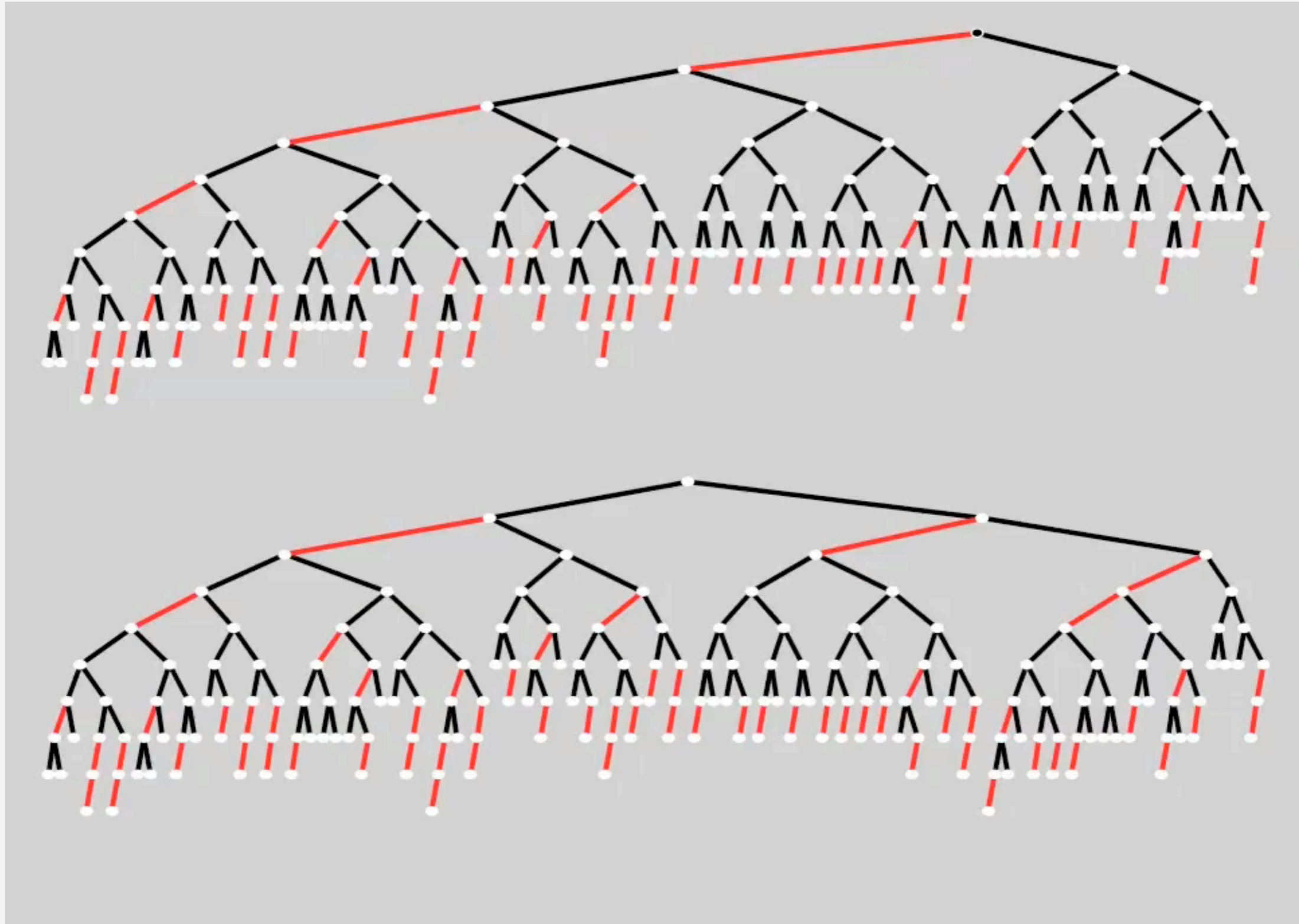
delete successor

move down (right)

*Fix right-leaning red links
on the way up the tree*

LLRB delete() movie

- Introduction*
- 2-3-4 Trees*
- Red-Black Trees*
- Left-Leaning RB Trees*
- Deletion*

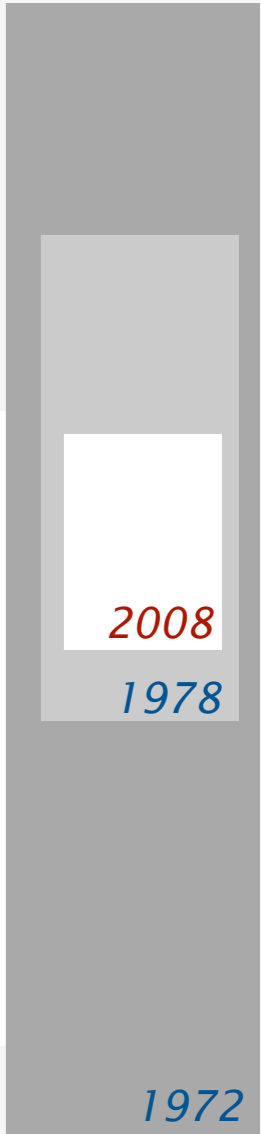


Red-black-tree implementations in widespread use:

- are based on pseudocode with “case bloat”
- use parent pointers (!)
- 400+ lines of code for core algorithms

Left-leaning red-black trees

- you just saw all the code
- single pass (remove recursion if concurrency matters)
- <80 lines of code for core algorithms
- less code implies faster insert, delete
- less code implies easier maintenance and migration



insert

delete

helper



insert

delete

helper

← *accomplishes the same result with less than 1/4 the code*