

### YOUNG'S THEOREM

A very important and useful result in the calculus of functions of several variables is the following.

**Theorem:** Let  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  be twice continuously differentiable on its domain of definition,  $\mathbb{X} \subset \mathbb{R}^n$ . Then on the interior of its domain, the  $n \times n$  matrix of second-order partial derivatives is symmetric,

$$\frac{\partial^2 f}{\partial x_i \partial x_j} = \frac{\partial^2 f}{\partial x_j \partial x_i}, \quad \forall i, j = 1, \dots, n.$$

**Proof:** By holding the  $x_k$ 's fixed for all  $k \neq i, j$  with  $i$  and  $j$  arbitrary, we can reduce the problem to the simple case of a function of two variables. Therefore, let  $y = x_i$ ,  $z = x_j$ , and  $g(y, z) \equiv f(x_1, \dots, x_{i-1}, y, x_{i+1}, \dots, x_{j-1}, z, x_{j+1}, \dots, x_n)$ . Note that continuity of the first- and second-order partial derivatives of  $f$  is equivalent to continuity of the first- and second-order partial derivatives of  $g$ . Now consider the quantity

$$(1) \quad h(\Delta y, \Delta z) \equiv [g(y + \Delta y, z + \Delta z) - g(y, z + \Delta z)] - [g(y + \Delta y, z) - g(y, z)].$$

There are three aspects of the function  $h(\Delta y, \Delta z)$  that are important. First, we can interchange the middle two terms of  $h(\Delta y, \Delta z)$  without affecting its value to get

$$(1') \quad h(\Delta y, \Delta z) \equiv [g(y + \Delta y, z + \Delta z) - g(y + \Delta y, z)] - [g(y, z + \Delta z) - g(y, z)].$$

Second, referring to the right-hand-side of (1), it is clear that for any  $\Delta z$ ,  $h(0, \Delta z) \equiv 0$ .

Similarly, referring to the right-hand-side of (1'), it is also clear that for any  $\Delta y$ ,  $h(\Delta y, 0) \equiv 0$ . This means that the graph of  $h(\Delta y, \Delta z)$  as a function of  $\Delta y$  (for fixed  $\Delta z$ )

begins at the origin, has base equal to  $\Delta y$  and height equal to  $h(\Delta y, \Delta z)$ , while the graph of  $h(\Delta y, \Delta z)$  as a function of  $\Delta z$  (for fixed  $\Delta y$ ) begins at the origin, has base equal to  $\Delta z$  and height equal to  $h(\Delta y, \Delta z)$ . Third, by the composite function theorem, the partial derivatives of  $h(\Delta y, \Delta z)$  with respect to  $\Delta y$  and  $\Delta z$  are

$$(2) \quad \frac{\partial h(\Delta y, \Delta z)}{\partial \Delta y} = \left[ \frac{\partial g(y + \Delta y, z + \Delta z)}{\partial y} - \frac{\partial g(y + \Delta y, z)}{\partial y} \right],$$

$$(2') \quad \frac{\partial h(\Delta y, \Delta z)}{\partial \Delta z} = \left[ \frac{\partial g(y + \Delta y, z + \Delta z)}{\partial z} - \frac{\partial g(y, z + \Delta z)}{\partial z} \right].$$

Finally, from (2) and (2'), the second-order cross-partial derivatives of  $h(\Delta y, \Delta z)$  are

$$(3) \quad \frac{\partial^2 h(\Delta y, \Delta z)}{\partial \Delta y \partial \Delta z} = \frac{\partial^2 g(y + \Delta y, z + \Delta z)}{\partial y \partial z},$$

$$(3') \quad \frac{\partial^2 h(\Delta y, \Delta z)}{\partial \Delta z \partial \Delta y} = \frac{\partial^2 g(y + \Delta y, z + \Delta z)}{\partial z \partial y}.$$

Therefore, by the mean value theorem, for any given  $\Delta z$  there is a  $c \in [0, \Delta y]$  such that

$$(4) \quad h(\Delta y, \Delta z) = \frac{\partial h(c, \Delta z)}{\partial \Delta y} \cdot \Delta y = \left[ \frac{\partial g(y + c, z + \Delta z)}{\partial y} - \frac{\partial g(y + c, z)}{\partial y} \right] \cdot \Delta y.$$

Note that by the hypotheses of the theorem, the terms in square brackets on the right-hand-side of (4) are continuously differentiable and therefore satisfy the conditions required for a second application of the mean value theorem. Therefore, there is a  $d \in [0, \Delta z]$  such that

$$(5) \quad h(\Delta y, \Delta z) = \frac{\partial^2 g(y + c, z + d)}{\partial y \partial z} \cdot \Delta y \cdot \Delta z.$$

Next, note that the definition of  $h(\Delta y, \Delta z)$  in (1) is “symmetrical” in  $y, z$  and in  $\Delta y, \Delta z$ , a fact that lead us to the equivalent expression for  $h(\Delta y, \Delta z)$  given in (1’). Therefore, using exactly the same arguments as above, but in the reverse sequence for  $\Delta y$  and  $\Delta z$  and applied to (1’) rather than (1), we obtain

$$(6) \quad h(\Delta y, \Delta z) = \frac{\partial^2 g(y + \tilde{c}, z + \tilde{d})}{\partial z \partial y} \cdot \Delta y \cdot \Delta z$$

for some  $\tilde{c} \in [0, \Delta y]$  and some  $\tilde{d} \in [0, \Delta z]$ . Equating the two expressions (5) and (6) for  $h(\Delta y, \Delta z)$  and canceling  $\Delta y$  and  $\Delta z$  implies

$$(7) \quad \frac{\partial^2 g(y + c, z + d)}{\partial y \partial z} = \frac{\partial^2 g(y + \tilde{c}, z + \tilde{d})}{\partial z \partial y}.$$

As  $\Delta y \rightarrow 0$  we have  $c \rightarrow 0$  (since  $0 \leq |c| \leq |\Delta y|$ ) so that  $y + c \rightarrow y \equiv x_i$ , while as  $\Delta z \rightarrow 0$  we have  $d \rightarrow 0$  (since  $0 \leq |d| \leq |\Delta z|$ ) and  $z + d \rightarrow z \equiv x_j$ . Similarly, as  $\Delta y \rightarrow 0$  we have  $\tilde{c} \rightarrow 0$  and  $y + \tilde{c} \rightarrow y \equiv x_i$ , while as  $\Delta z \rightarrow 0$  we have  $\tilde{d} \rightarrow 0$  and  $z + \tilde{d} \rightarrow z \equiv x_j$ . Continuity of both sides of (7) then implies that

$$(8) \quad \frac{\partial^2 f}{\partial x_i \partial x_j} = \frac{\partial^2 g(y, z)}{\partial y \partial z} = \frac{\partial^2 g(y, z)}{\partial z \partial y} = \frac{\partial^2 f}{\partial x_j \partial x_i}. \quad \mathbf{Q.E.D.}$$

