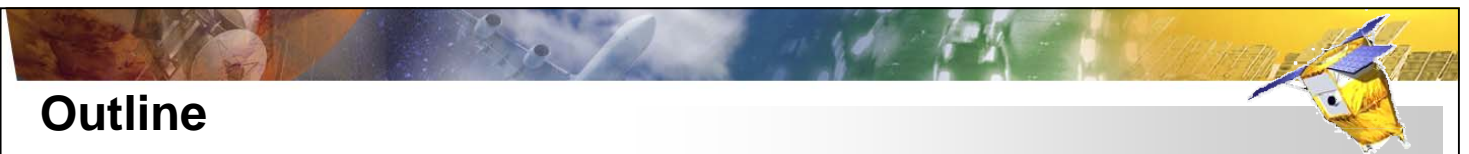


# The Bright Future of High Resolution Satellite-Will Aerial Photogrammetry Become Obsolete

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Institute for Robotics and Mechatronics Department  
Optical Sensorics and Electronics

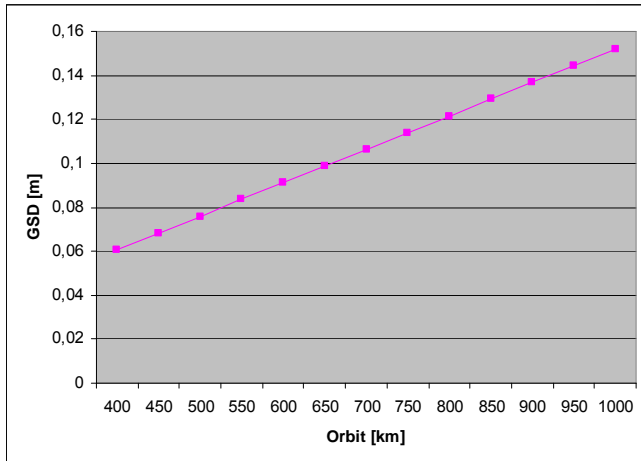


## Outline

- Current optical high end high resolution technology
- High resolution optical satellite EO-Programs
- Commercial space segments
- Data fusion with AIS and radar sensors
- **HiROS High Resolution Optical Satellite System**
- Examples for real time 3D change detection
- Conclusion

# Current optical high end high resolution technology

<b>LAUNCH:</b>	April 24, 1990
	from space shuttle Discovery (STS-31)
<b>DEPLOYMENT:</b>	April 25, 1990
<b>MISSION DURATION:</b>	<b>Up to 20 years</b>
<b>SERVICING MISSION 1:</b>	December 1993
<b>SERVICING MISSION 2:</b>	February 1997
<b>SERVICING MISSION 3A:</b>	December 1999
<b>SERVICING MISSION 3B:</b>	February 2002
<b>SERVICING MISSION 4:</b>	May 2009

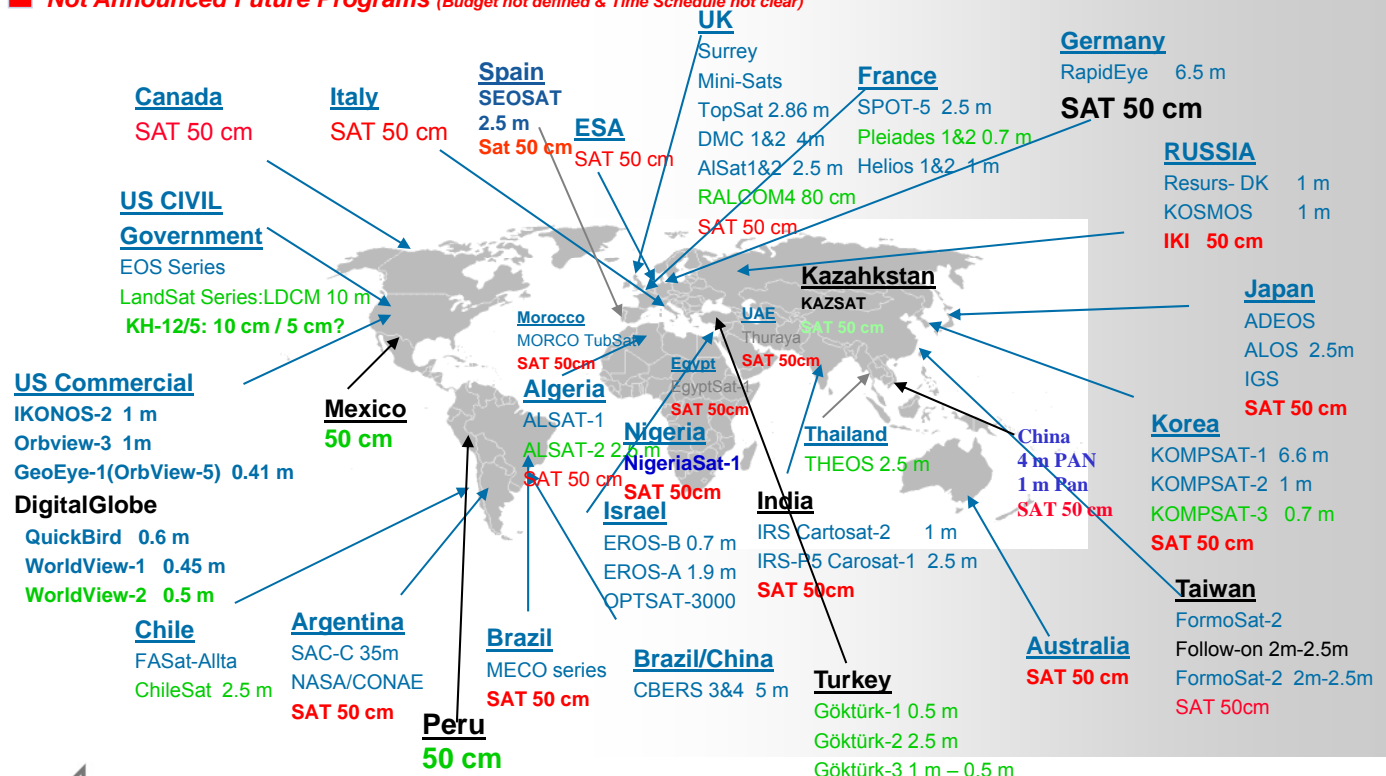


→f: 57.6 m  
 →F#: 24 / PAN  
 →D 2.4 m

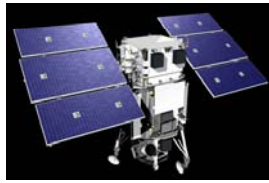
# High resolution optical satellite EO-Programs

≈ 15-20 Satellites 0.5 m GSD

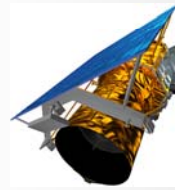
- **Current Status**
- **Announced Future Programs**
- **Not Announced Future Programs** (Budget not defined & Time Schedule not clear)



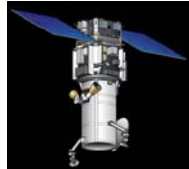
# Commercial or dual use optical space segments



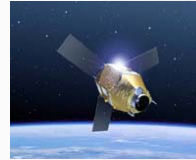
WV1: 0.5 m GSD



Geo Eye 0.41 m GSD



WV2 0.5 m GSD

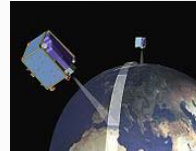


Pleiades 1 m GSD

## Example DLR Proposal



HiROS 0.5 GSD



RapidEye 6.5 m GSD

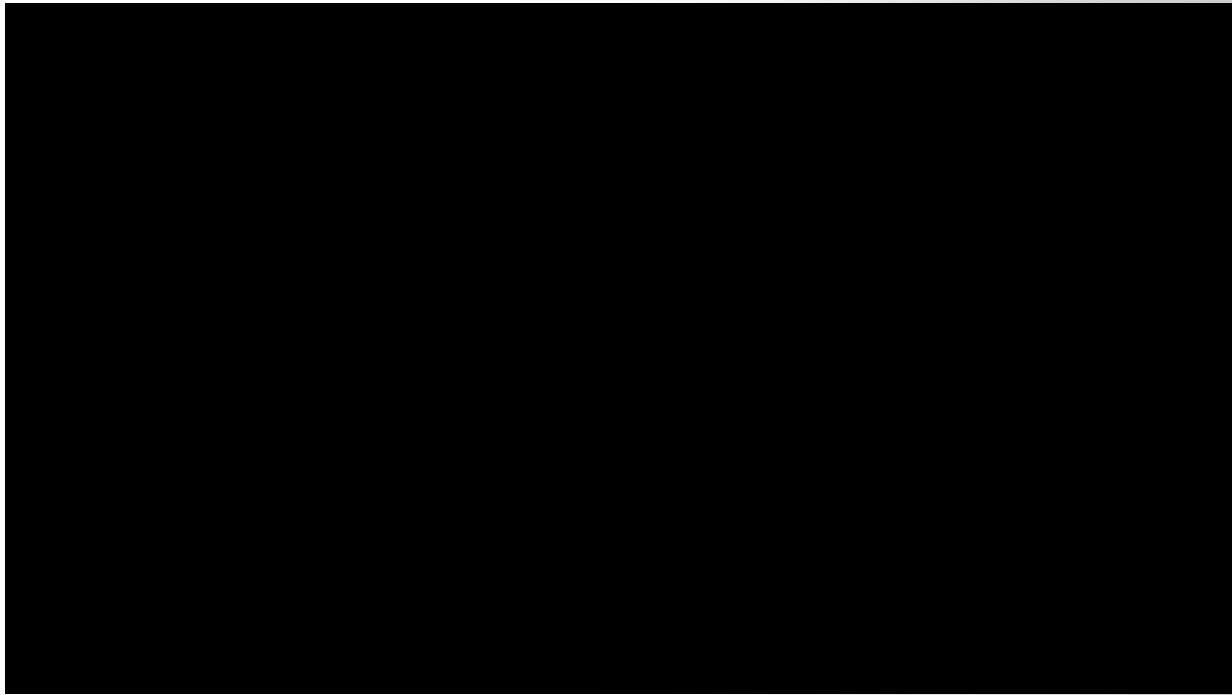
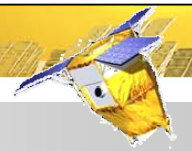
# Example: HiROS design goals

Main key parameter of the optical HiROS payload

- Revisit, actuality and imaging time  
(any area worldwide shall be scanned within 24 h by one of the satellites)
- Size of imaging area (36...60 km x 36...60 km)
- Target recognition (high color resolution, 3D capability)
- Special data products for MIL and security applications
- Data processing time minimization

**➔ 3 Satellite System with 0.5 m GSD PAN ←**

# HiROS a End to End system proposal



Options: (1) Auto Indetif. of Ships, (2) Night Vision IR, (3) Real time Image Access

# HiROS Key Parameter



	HiROS-Std	HiROS-MR	HiROS-HR
Orbit [km]	490...685		
GSD	0.5...0.7		
Aperture [m]	0.75		
VIS Spectral	R,G,B,NIR		
Stereo Views	-30°,-10°,0°, +10°, +30°		
TDI-Direction	bidirectional		
Nr. Pixel PAN	24,000		
Nr. Pixel MS	6,000		
Line Rate [kHz]	14		
MTF	> 12 %		
SNR	> 200*		

(\* at 20 % albedo, (30 ° sun angle, 30 ° view angle), 10:30 Berlin)



# Mission characteristics of HiROS

**Long Life Time:** 5 years

## Resolution:

- PAN 0.5 m GSD
- MS 2 m GSD (Red, Green, Blue, NIR)

**High Revisit Time:** any point on Earth every day

- Polar SSO (490 km, 7063 m/s, LTDN 10:30)
- 3 satellite constellation (120° spacing)
- High duty cycle 10 min per orbit

## High Agility / Operability

- One- Pass Stereo Imaging (along track viewing angle of 0°, +/- 10°, +/- 30°)
- Wide Area Imaging ( five strips of 12 km swath, in flight all directions)
- Multi Point Imaging (Multiple small area coverage in one path)

## High Down Link Capability

- Steerable X – band antenna (600 Mbit/s encrypted)
- Simultaneous downlink & imaging

**Option [I]: IR MIR & TIR: GSD 5 m**

**Option [II]: Automatic Identification of Systems** (Coded telecommunication)

**Option [III]: Ka-Band Uplink to Geo Communication Satellites** (2 min for 12 x 12 qkm after imaging)

# High resolution optical satellite system (Std. HiROS)

## Satellite Characteristics

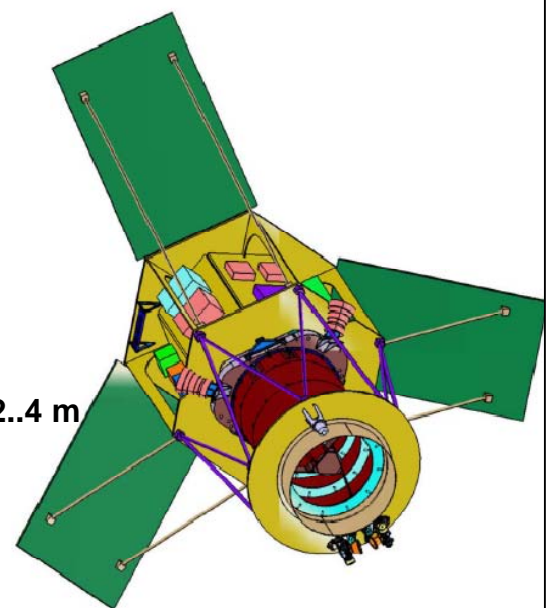
**Mass:** 820 kg (dry mass 750 kg)

**Launcher:** single launch (Rockot, VEGA...)  
multiple launch (Soyuz 2 – 1b)

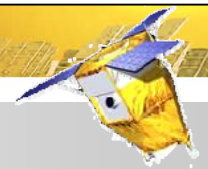
**Power:** 380 W average

## High Pointing Accuracy & Stability:

- Accuracy of orientation w/o ground control points: +/- 2..4 m
- Orientation relative to Nadir +/- 30° pitch / +/- 40° roll
- Stereo Angle along track 0°, +/- 10°, +/- 30°
- Cross track 0° to 90° during one path
- LoS accuracy (Jitter Stability): 0.07 arcs / 4.83 ms
- Co-registration between IR and HR VIS: 1/3 Pixel of IR detector = 0.7 arcs



# HiROS – Instrument performances

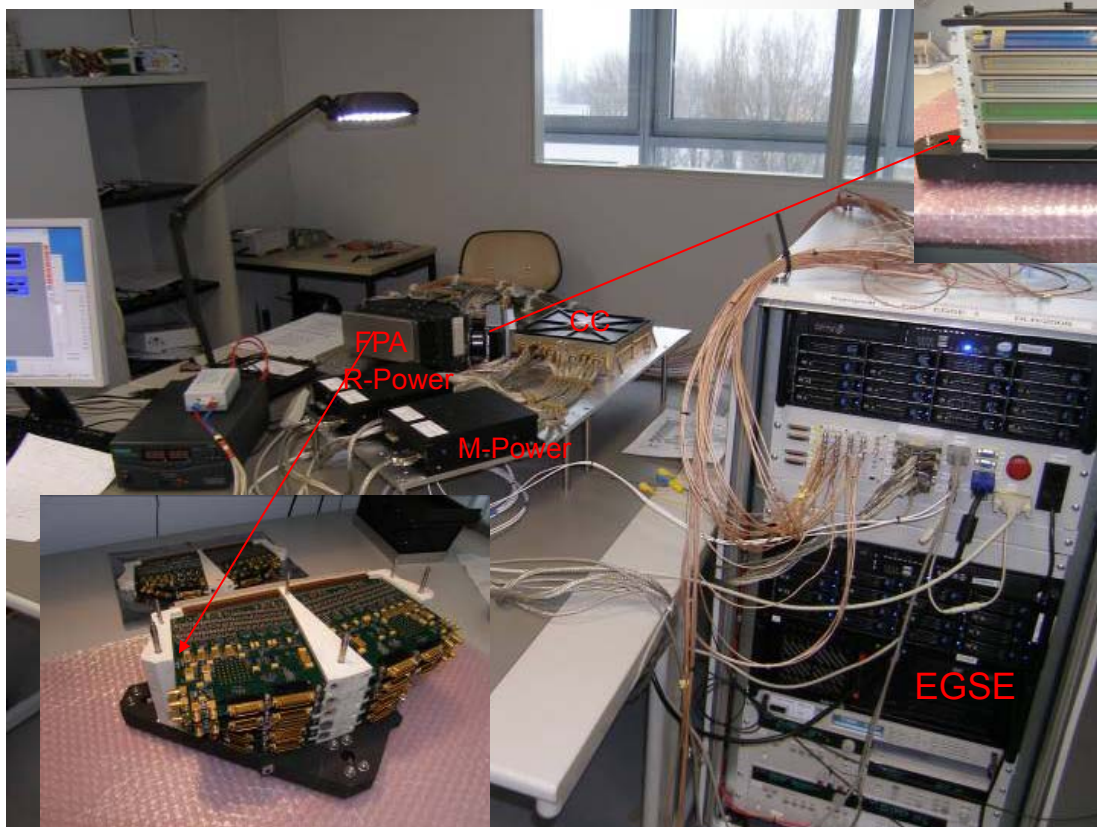


- **Mass:** 190 kg
- **Power:** 110 W
- **Panchromatic Channel:** 0.5 m GSD  
450nm – 900nm
- **Multi spectral Channels:** 2 m GSD  
450 – 520, 520 – 600, 630 – 690, 760 – 900 nm
- **Option IR Channel:**
  - **MIR GSD:** 5 m
  - **TIR GSD:** 5 m
- **Swath Width** > 12 km
- **MTF** > 13 %
- **SNR:** > 200\*
- **Dynamic Range:** > 1:5000 (14 bit ADC)
- **Selectable TDI Stages:** 1, 8, 32, 64
- **Line Rate:** 0.5...14.5 kHz PAN / 0.5...3.6 kHz MS



\* Sun angle 30° view angle 30° albedo 20%, 10:30 Berlin

# Focal plane development

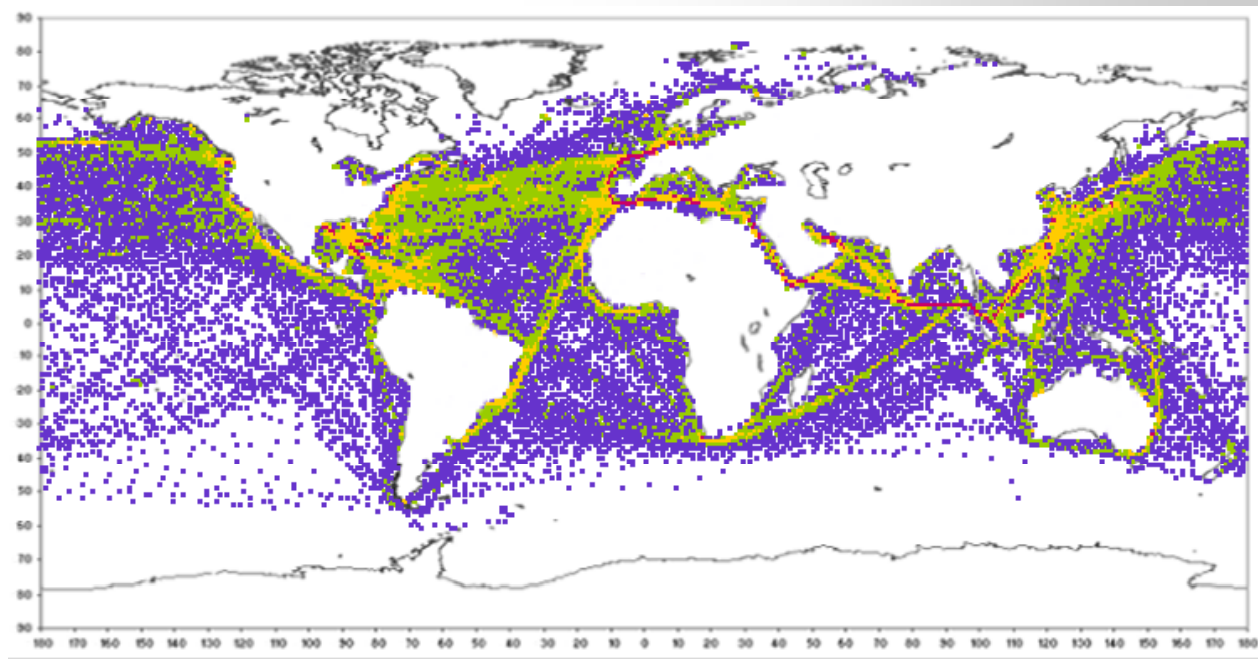


- MTF [CT] : 52 %
- MTF [LT] : 53 %
- rms noise [wc]  
16 LSB (40 °C)
- Channel SNR  
>1024
- Instrument SNR  
200\*
- Line Rate: 14 kHz

\* Sun angle 30° view angle 30° albedo 20%, 10:30 Berlin

# Maritime Surveillance & Reconnaissance

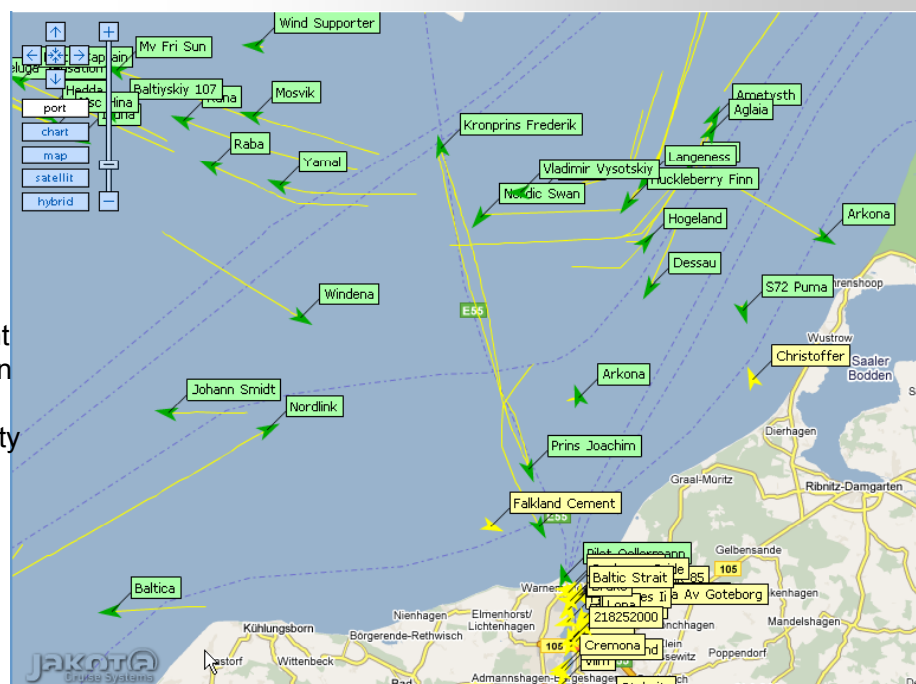
## Automatic Identification System AIS



© AMVER

## Current Status

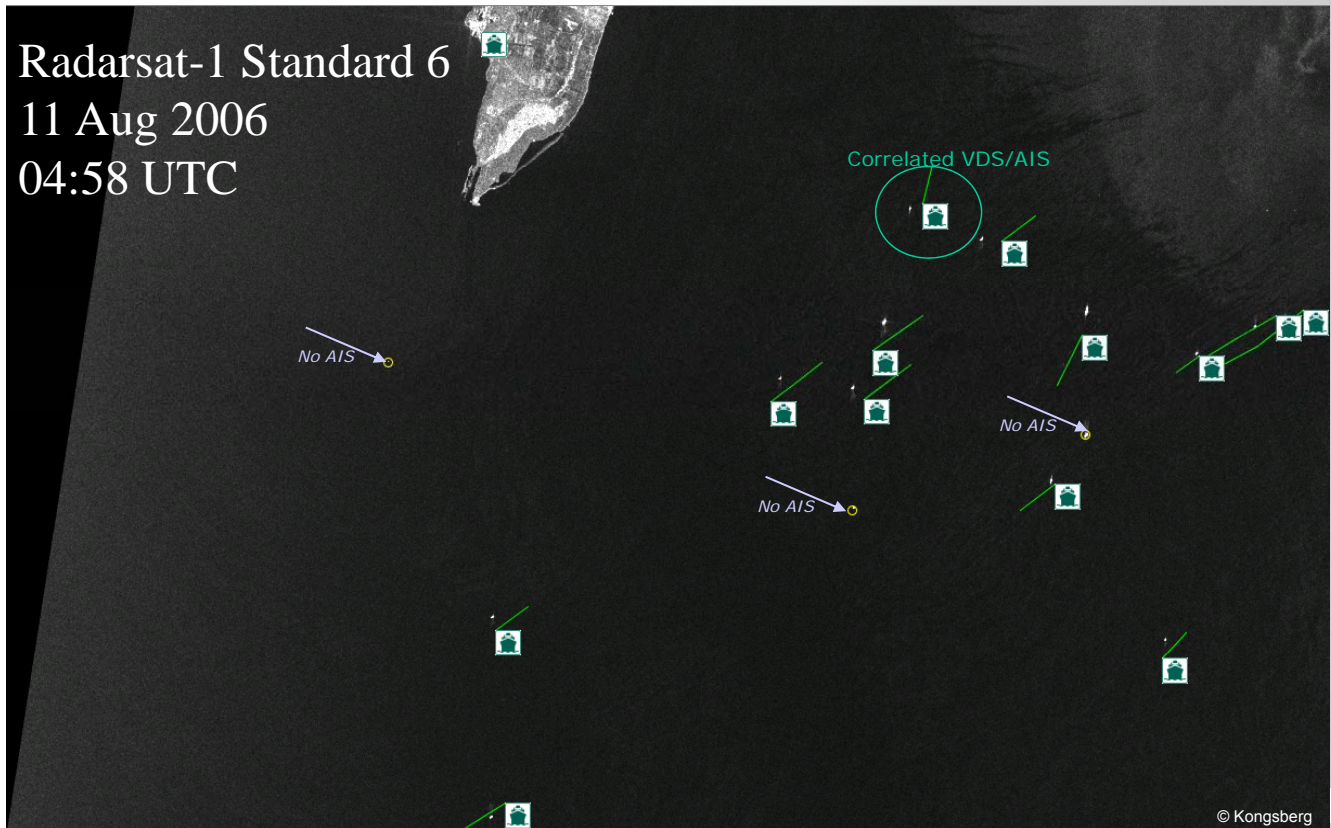
- Ship Monitoring only in coastal zones areas possible
  - no global monitoring available
  - no global traffic coordination possible
- Very limited technical equipment existing to track the ship traffic in open ocean areas to find out position and the vector of velocity (INMARSAT, VMS, ..)



## Example of Data fusion

DLR Study: Needs for on board classification and feature based data fusion

Radarsat-1 Standard 6  
11 Aug 2006  
04:58 UTC



Deutsches Zentrum  
DLR für Luft- und Raumfahrt e.V.  
in der Helmholtz-Gemeinschaft

© Kongsberg

PHOWO 09.09.2009, Page: 15

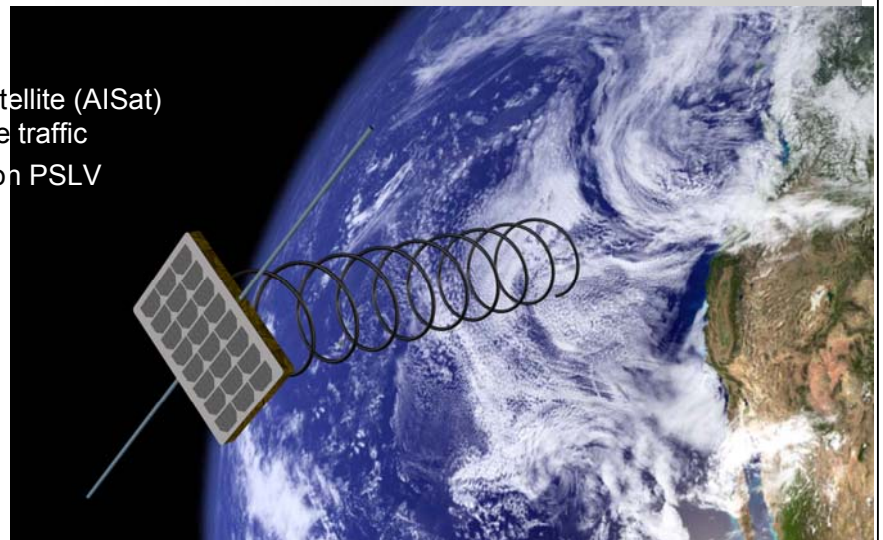
## Optional Payload AIS DLR Micro Sat. Mission

➤ Small Payload with high additional information ships for larger Systems

- Receiver: Mass less 1kg, Dimensions: 170 x 250 x 50 mm
- Antenna: Helix

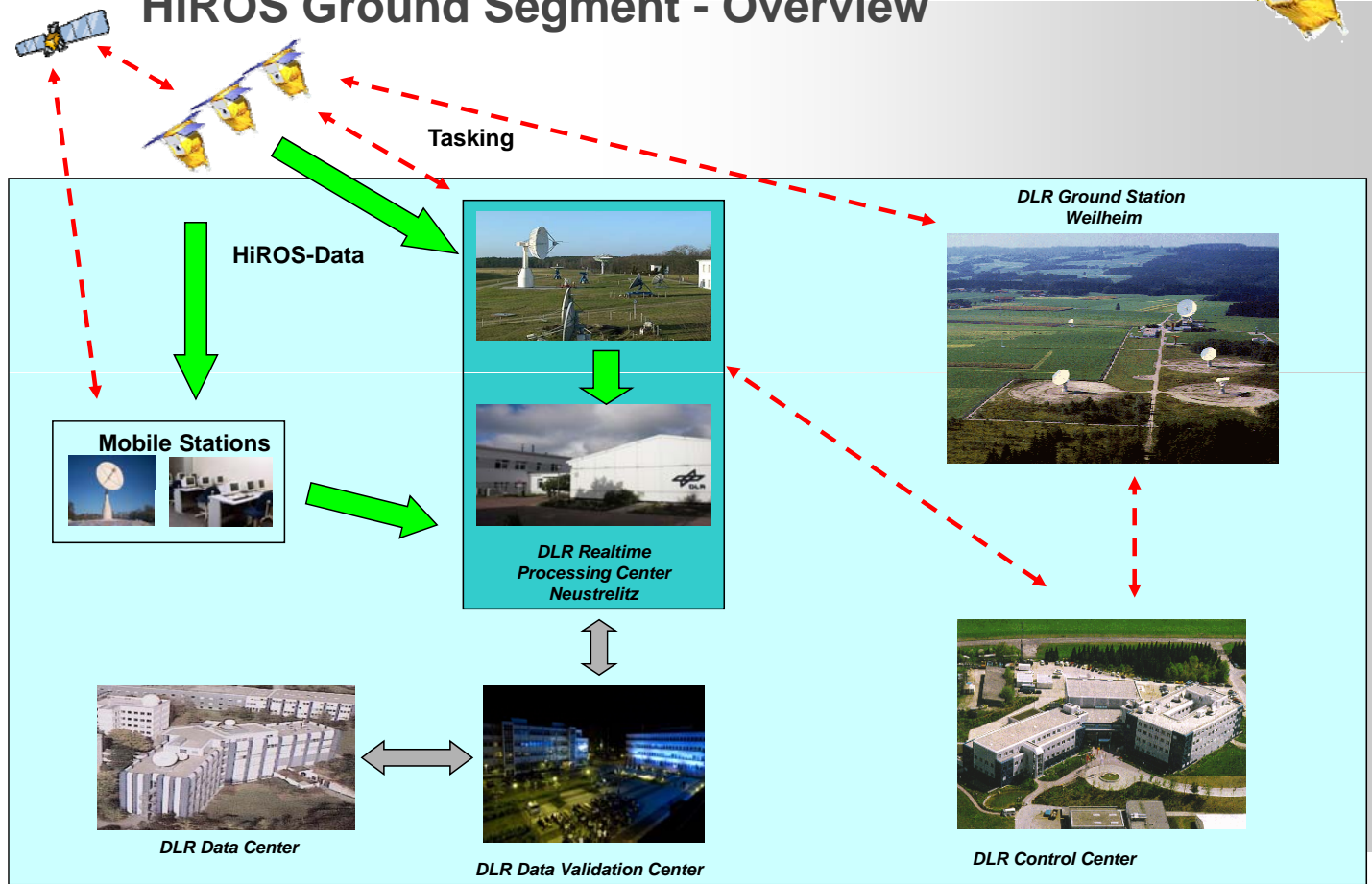
➤ DLR-RY Pre Curser Activities

- Development of a nano satellite (AISat) for global Monitoring of sea traffic
- Planed Launch **1Q/ 2010** on PSLV

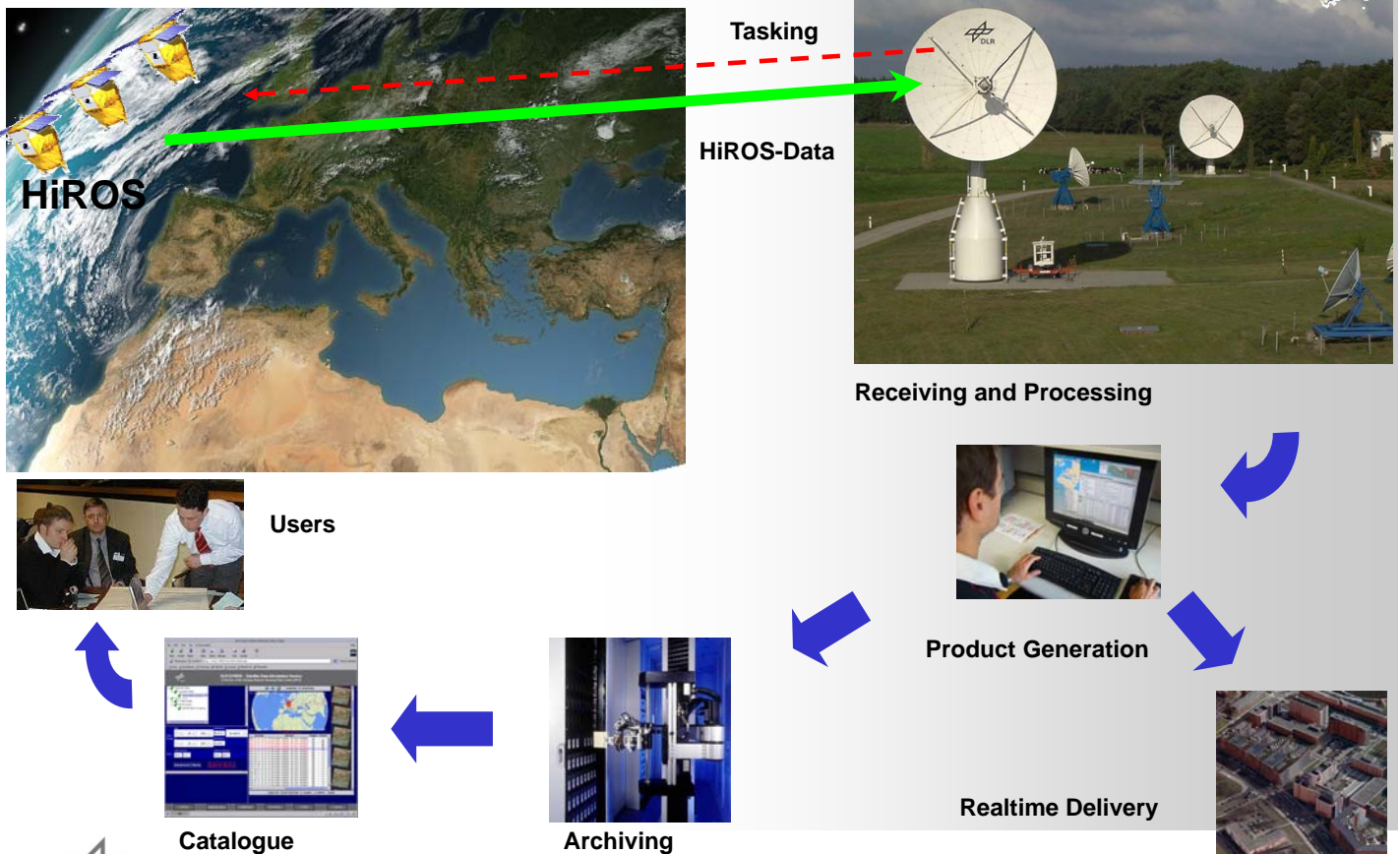




# HiROS Ground Segment - Overview



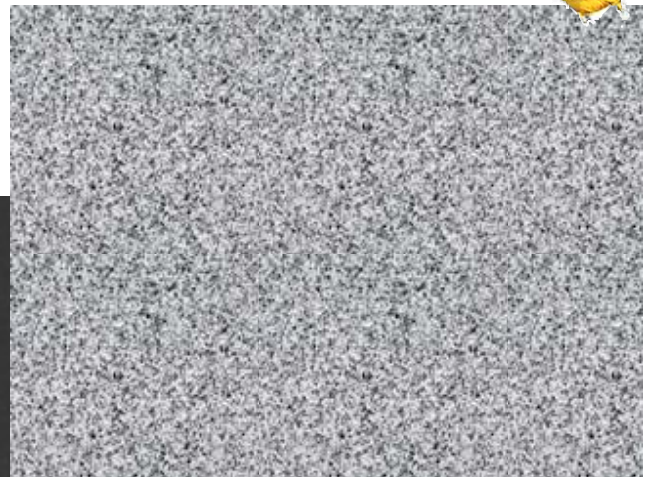
# Ground Segment – Dataflow



# Detection Advantage of SAR Satellites



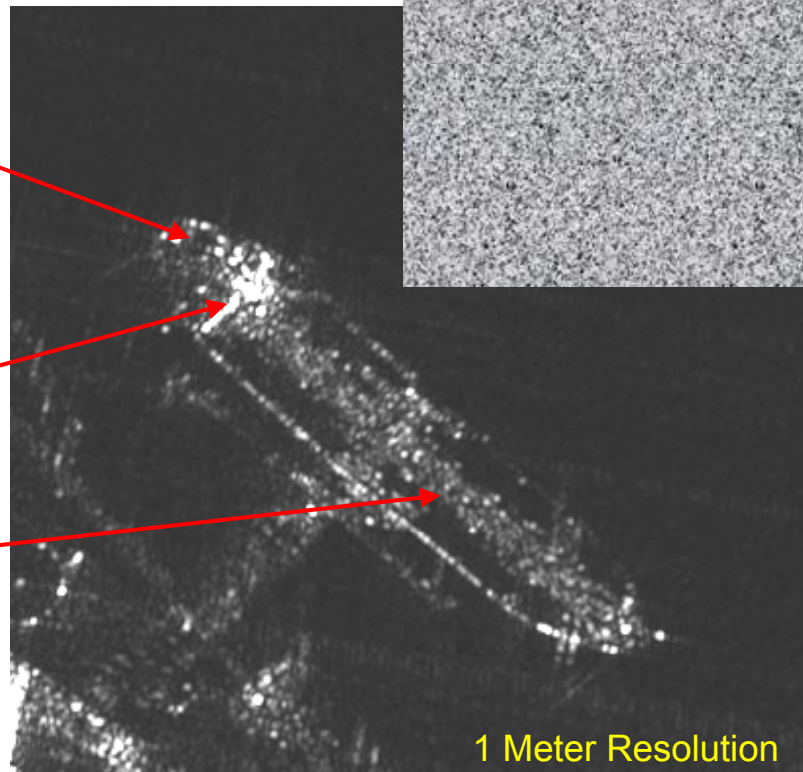
**With Heavy Fog**



Funnel

Bridge deck at stern

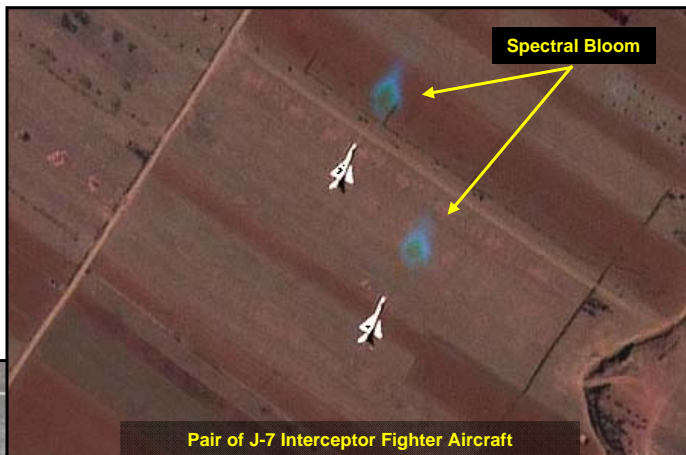
Pipelines



View

1 Meter Resolution

# Dual Use Applications

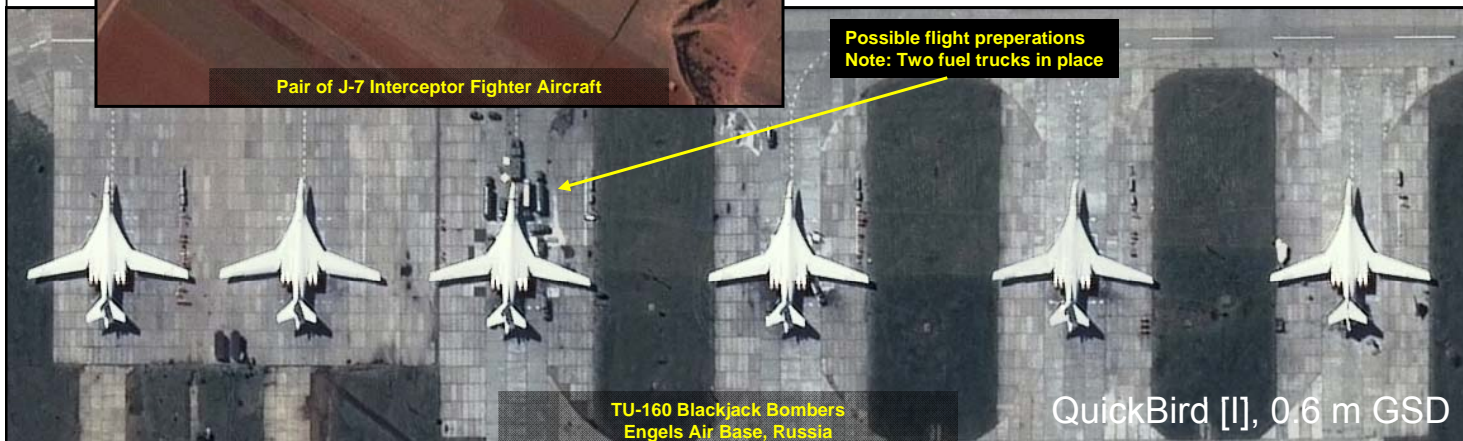


Pair of J-7 Interceptor Fighter Aircraft



Sukhoi SU-47 "Berkut" (Experimental Fighter)

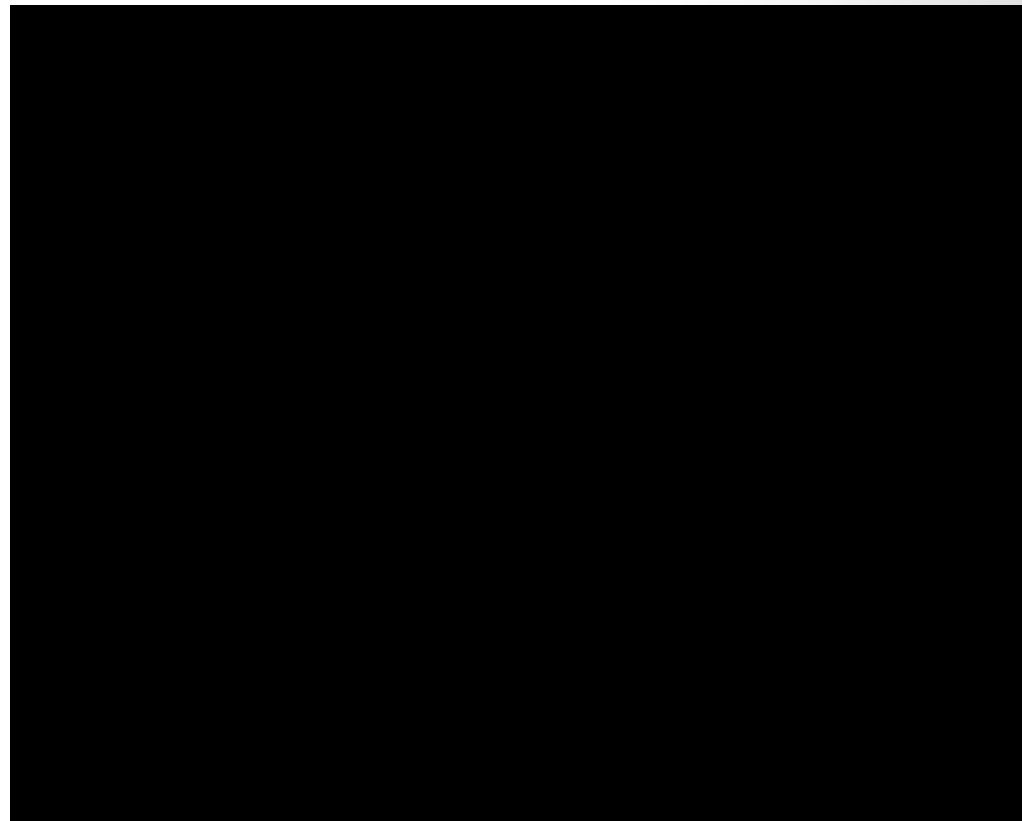
Possible flight preparations  
Note: Two fuel trucks in place



TU-160 Blackjack Bombers  
Engels Air Base, Russia

QuickBird [I], 0.6 m GSD

## 3D Images of Beijing (WV1, accuracy: x&y 50 cm, z 10 cm)



Status:  
Change detection  
3D HiROS data  
Product is 1 h  
after received  
data available

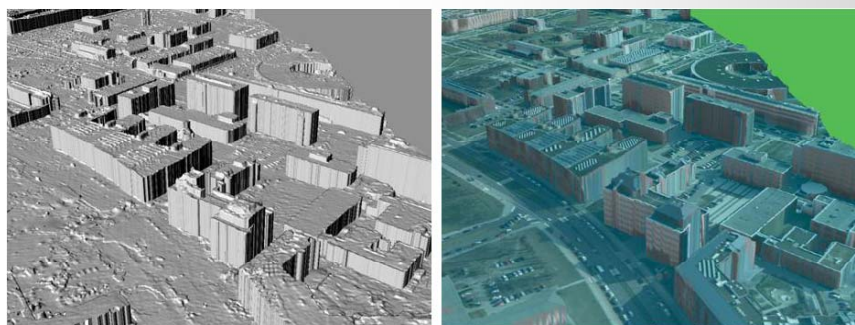
Goal (1):  
Data processing  
at ground segment  
in real time

Goal (2):  
Data processing  
on Board

Road Map

## Why we are so optimistic regarding the real time solution?

- Example: Airborne and Satellite data (MFC and WV)

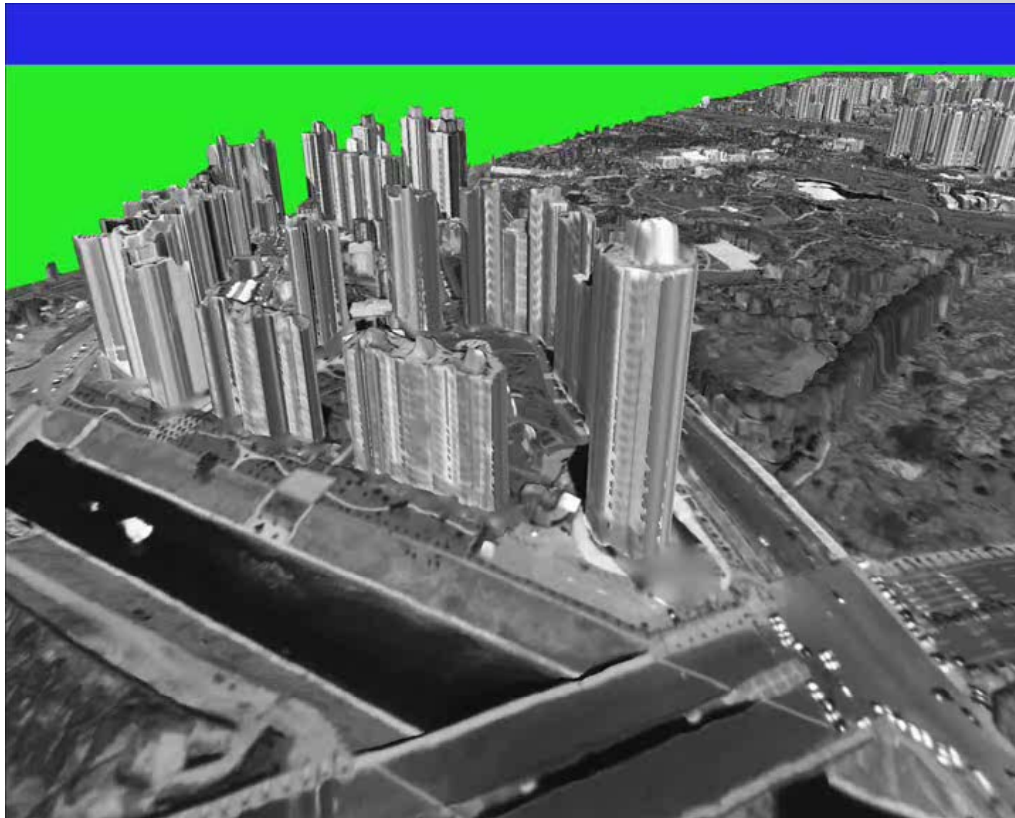


- Example: Driver assistance systems



Same SGM algorithm by  
1 k x 1 k stereo images 25 Hz  
will be used 2011 in S-MB

# 3D Images with facade of Beijing (WV1, accuracy: x&y 50 cm, z 10cm)

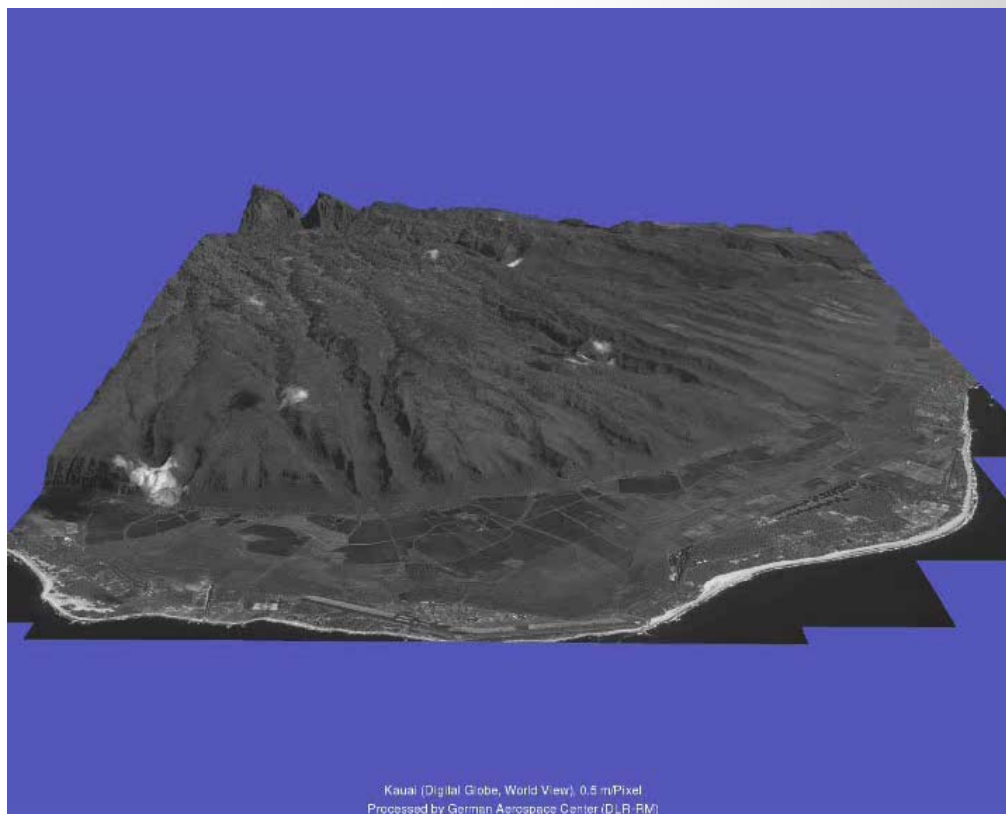


# Las Vegas WV1 data 50 cm GSD (accuracy: x&y 50 cm, z 25cm)



Las Vegas (Digital Globe WorldView) 0.5m Pixel  
Processed by German Aerospace Center (DLR) RM

# Kauai, Island near Hawaii, WV1 50 cm GSD (accuracy: x&y 50 cm, z 25cm)



Kauai (Digital Globe, World View), 0.5 m/Pixel  
Processed by German Aerospace Center (DLR RM)

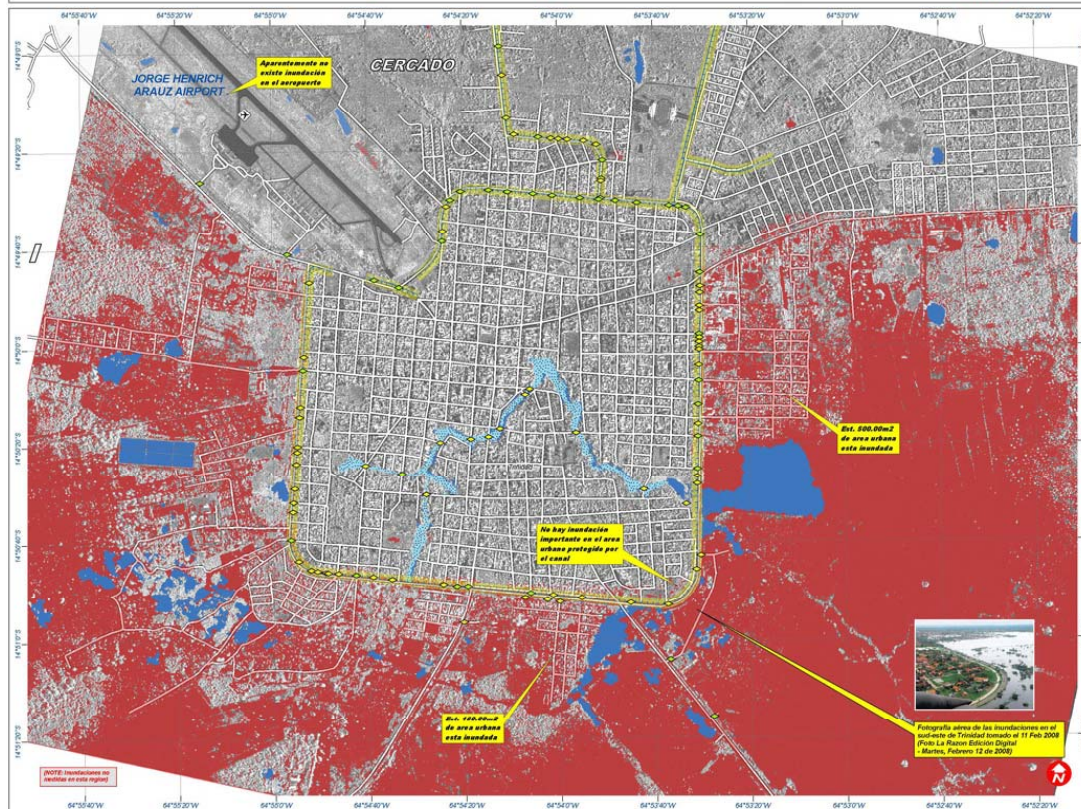
# Optics/SAR for UN Emergency Response Flooding in Bolivia, Feb 2008

## VERSIÓN ACTUALIZADA: INUNDACIONES EN TRINIDAD DEPARTAMENTO DEL BENI (14 FEB. 2008), BOLIVIA

Este mapa ilustra las inundaciones detectadas por satélite en la zona urbana de Trinidad, capital departamental de Beni. El análisis de inundaciones fue realizado mediante una sola escena TerraSAR-X captada el 14 febrero 2008. Escenas RADARSAT captadas el 6 de febrero 2008 y 6 de abril 2007 también han sido utilizadas. Es un análisis preliminar aun no validado en el terreno.



**18 Febrero 2008**  
**Precipitación**  
**Versión 1.0**  
Guide No: FL-2007-000231-BOL



**Legenda**

Alcaldía	Ciudad	Ciudad (general)	Ciudad (particular)	Ciudad (protección)
Canal de drenaje	Calle	Calle	Calle	Calle
Puerto	Puerto	Puerto	Puerto	Puerto
Finca	Finca	Finca	Finca	Finca
Linea Rieles	Linea Rieles	Linea Rieles	Linea Rieles	Linea Rieles
Arroyo	Arroyo	Arroyo	Arroyo	Arroyo

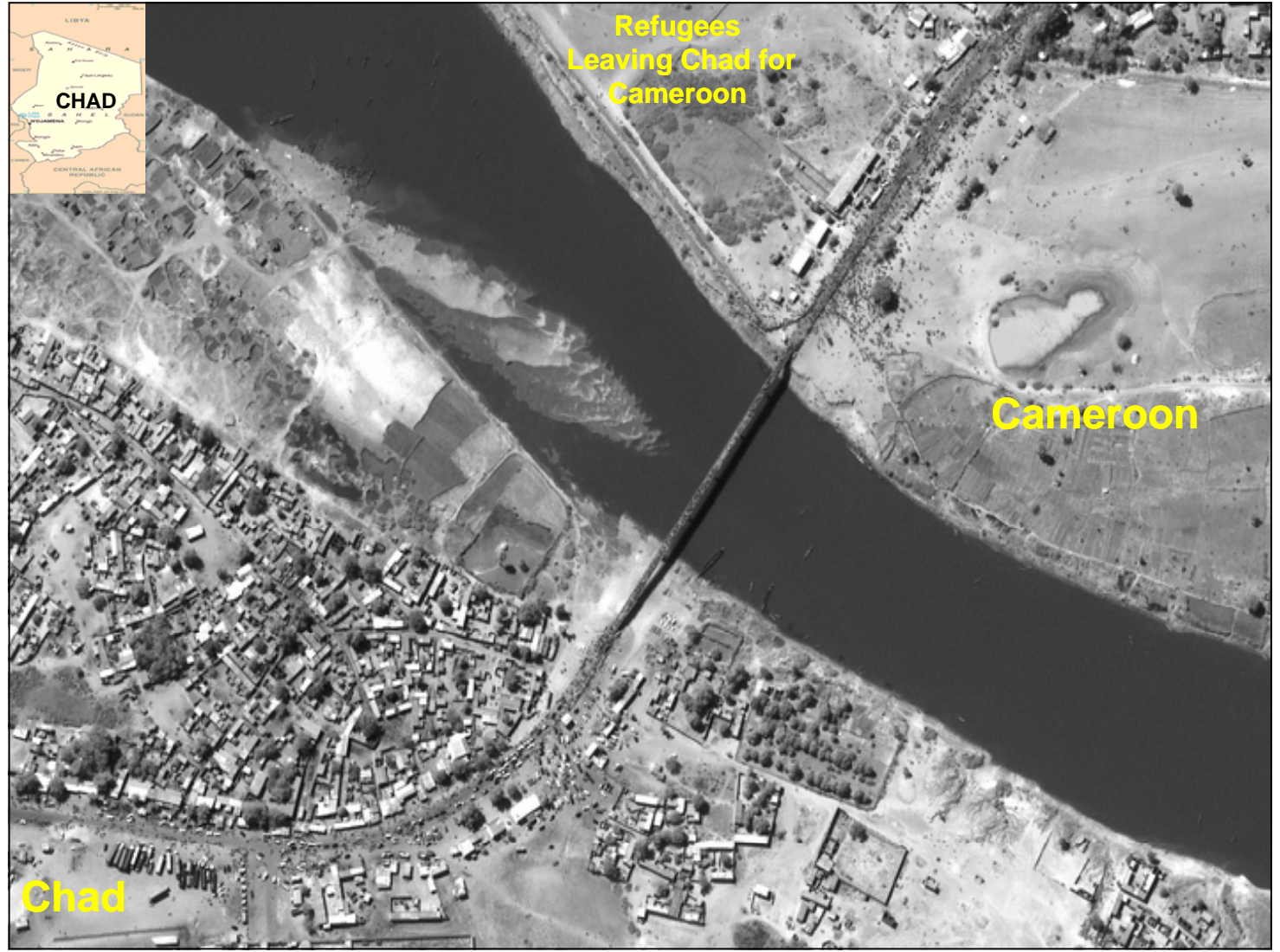
**ANÁLISIS DE INUNDACIONES**  
Derivado de escenas TerraSAR-X captada el 14 de febrero 2008.  
Inundaciones en rojo.  
Áreas protegidas en azul.

**Escala del mapa para A3: 1:20,000**

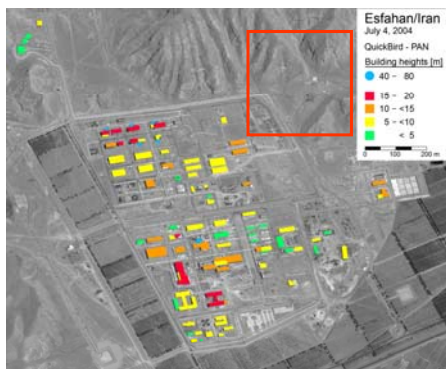
100 200 300 400 500 600 700 800 900 1000

Sensor: TerraSAR-X  
Fecha del satélite: 14 febrero 2008  
Operador de la estación: DLR (2008) Centro de Gestión de Datos de la Tierra  
Operación de procesamiento: DLR (2008) Centro de Gestión de Datos de la Tierra  
Operación de procesamiento: DLR (2008) Centro de Gestión de Datos de la Tierra  
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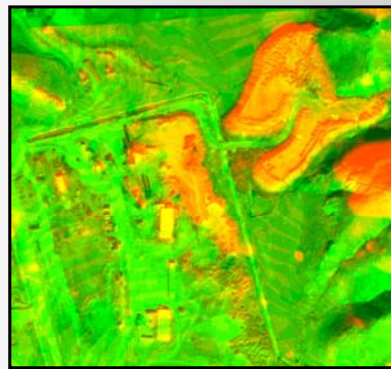
**UNOSAT**  
satellite solutions for all  
Contacto para información: info@unosat.org  
247 Lines directas: +41 76 607 0068  
Web Address: www.unosat.org



# HiROS Higher Level Data Products



Spaceborne DSM of 1 m accuracy from QuickBird



Changed DSM for analysis of under ground activities of the nuclear facilities in **Isfahan/Iran**



mass events



Automatic car detection Capabilities  
Highways and traffic ways detection

## Conclusion

- 1) Current digital airborne systems are working in a range of 5 cm – 1m GSD
- 2) Commercial satellites are working in a range 50 cm – 6.5 m GSD
- 3) HiROS constellation 24 h revisit time any area (10 Orbits: whole Germany ca. 3-5 days in 3D)
- 4) Minimal tasking 5-2 min before imaging (45 min standard, 5-2 min via patch antenna)
- 5) Fast data access 2 min after imaging via (Ka-Band) communication satellite
- 6) Processing time of 1000 km<sup>2</sup> in ca. 1 h (25 CPU's) near future real time
- 7) MR and HR satellite systems could not be used because of current law
- 8) System life time between 5 and 10 years
- 9) Data fusion between airborne / UAV systems of 1-25 cm GSD, radar and high resolution optical satellites for local and global applications

Today and in the near future space- and airborne / UAV systems are complementary

# Data fusion product of airborne and terrestrial Sensors



Data fusion of airborne camera, LIDAR and panoramic camera

Accuracy x, y, z better 5 cm → Geo 3D VR

Application Goal:

sensor systems space- **global 50 cm [GSD]** and airborne **local 1-25 cm [GSD]**