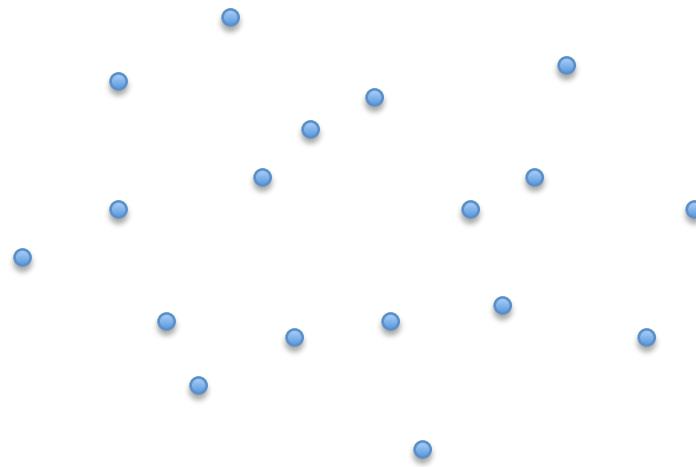


Convex Hull (divide and conquer)

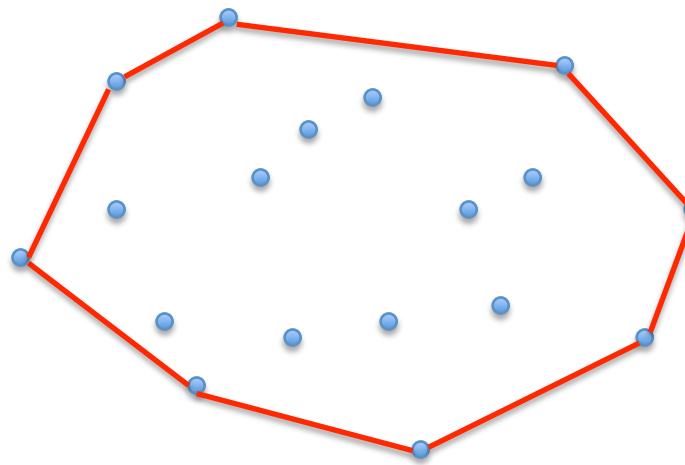
Denis TRYSTRAM

Grenoble-INP / april 2010

Set of points Q



Convex hull (definition)



H is the smallest convex polygon that contains all the points of Q

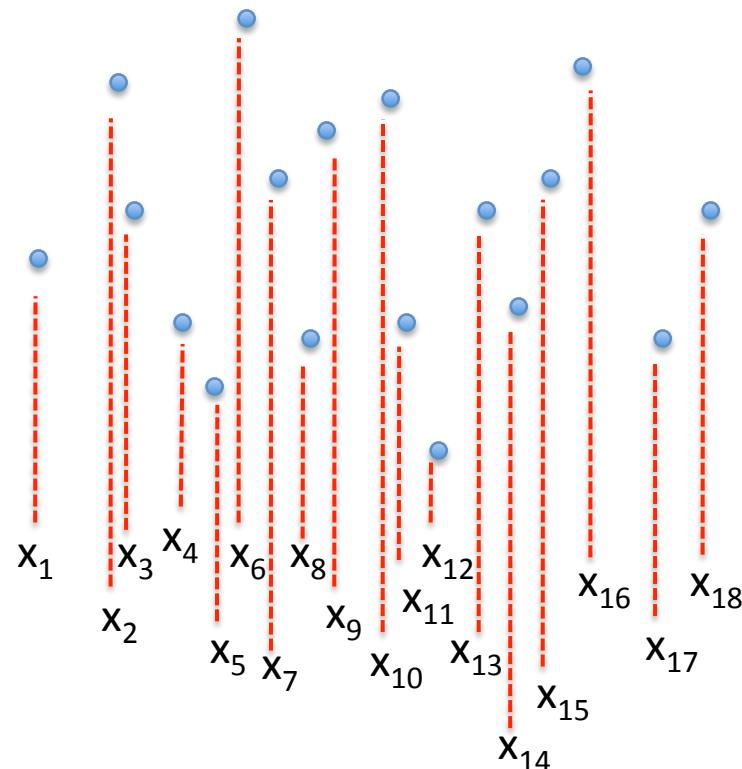
Principle

Decompose the set of points in equal parts (Qleft and Qright)

Solve the sub-problems respectively on Qleft and Qright

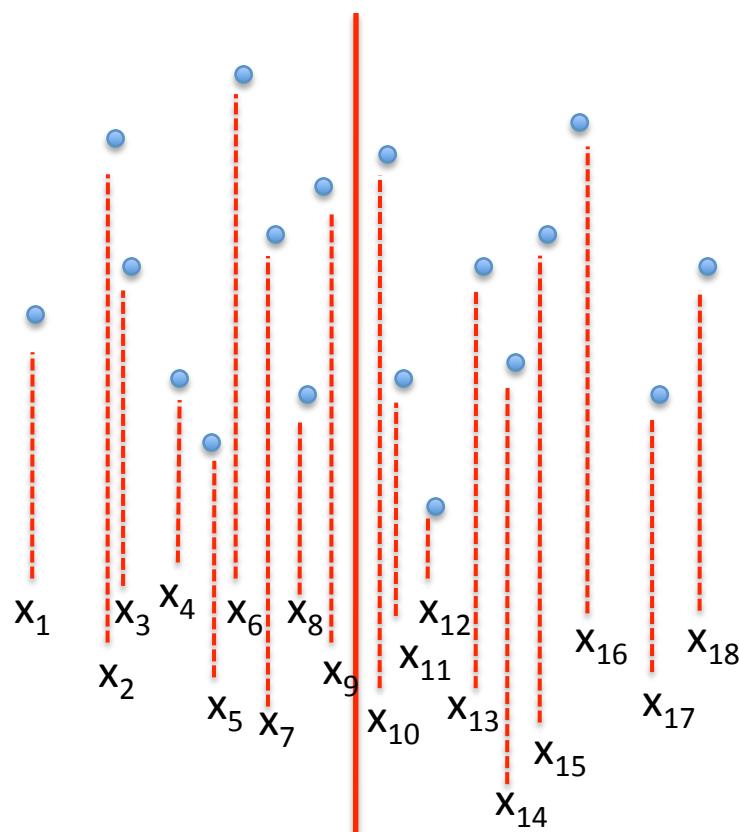
Merge both convex hulls Hleft and Hright

1. decomposition



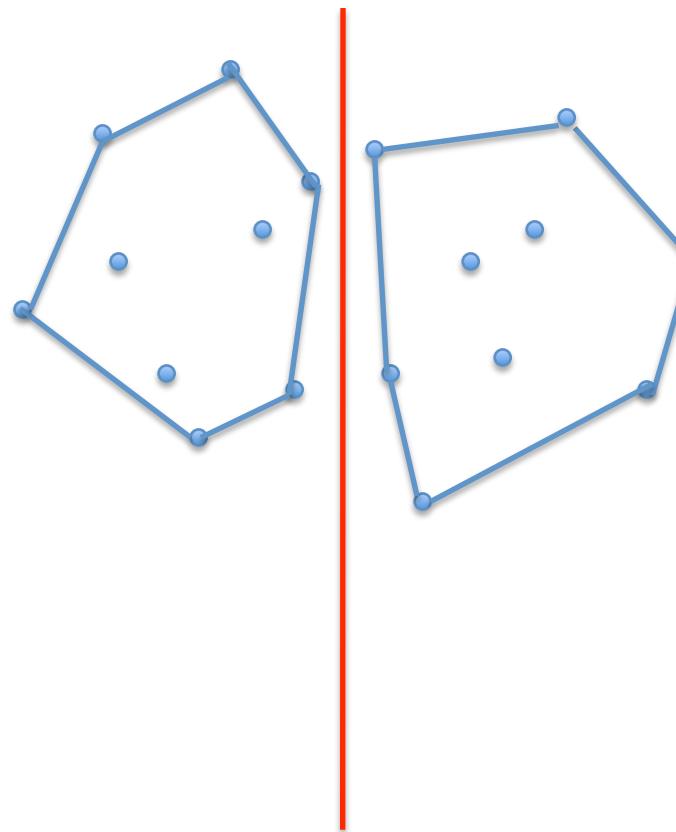
Sort the points by increasing abscissa

1. decomposition



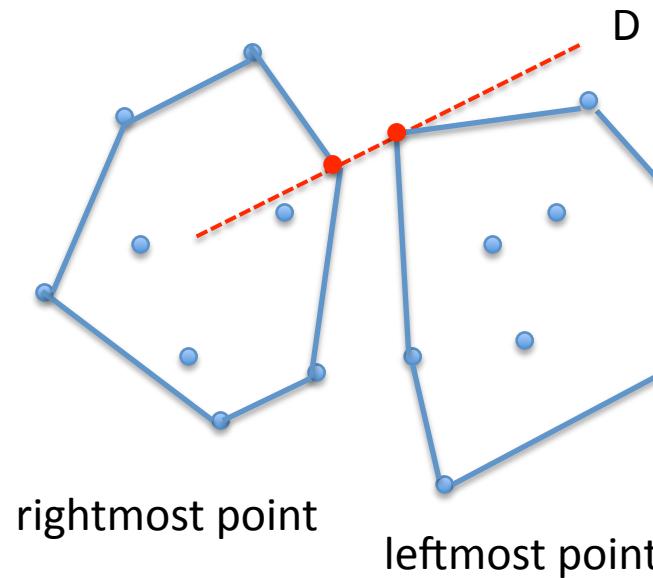
Split the points into two sets of equal size

2. Solve sub-problems

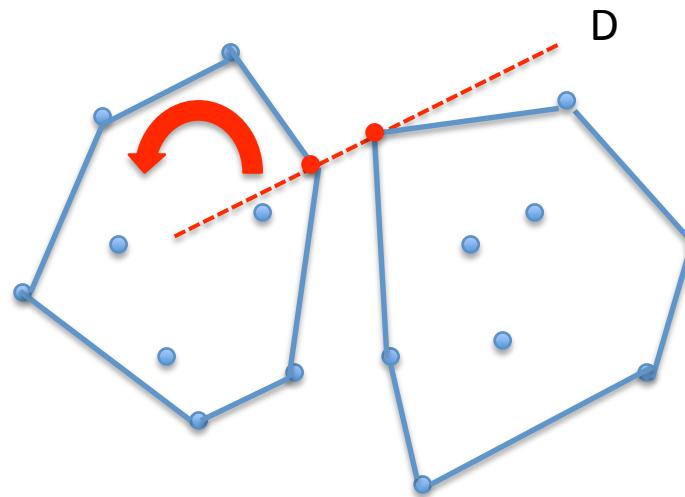


Compute the convex hulls on Q_{left} and Q_{right}

3. Merge both solutions

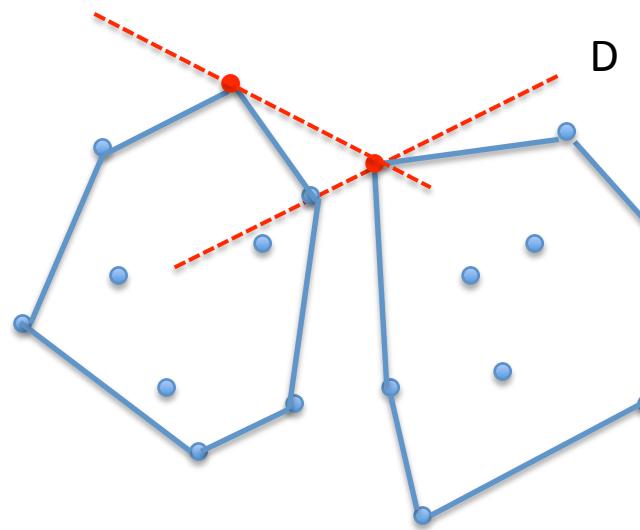


3. Merge both solutions



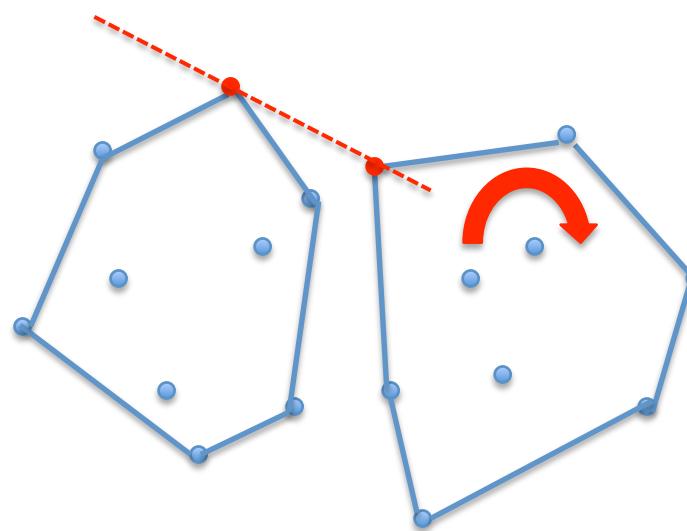
Determine the upper tangente

3. Merge both solutions



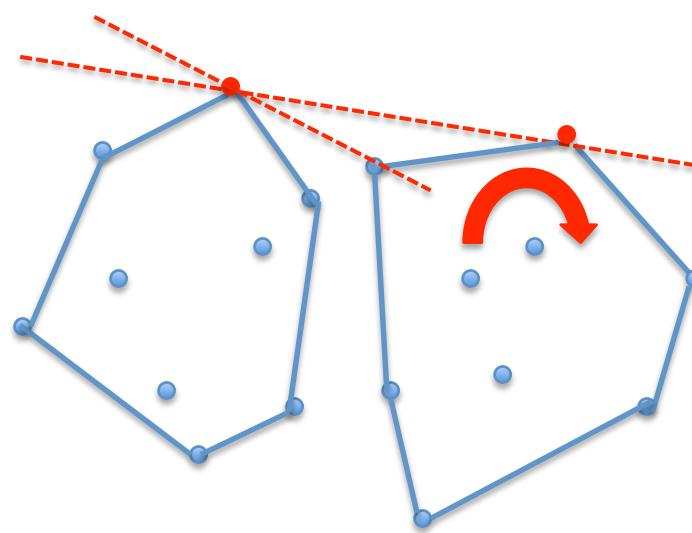
Determine the upper tangente

3. Merge both solutions



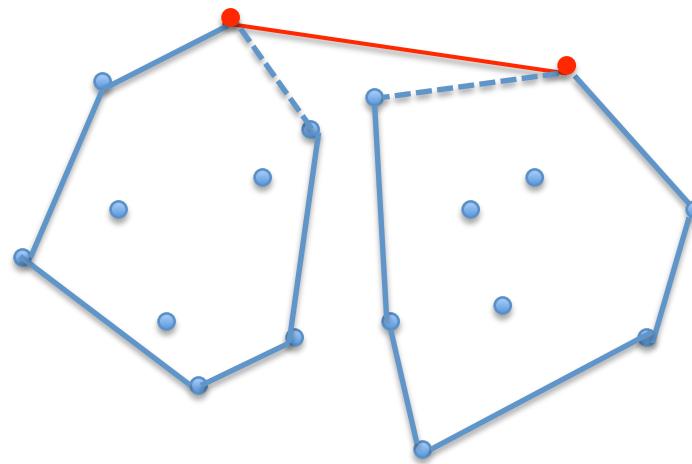
Determine the upper tangente

3. Merge both solutions



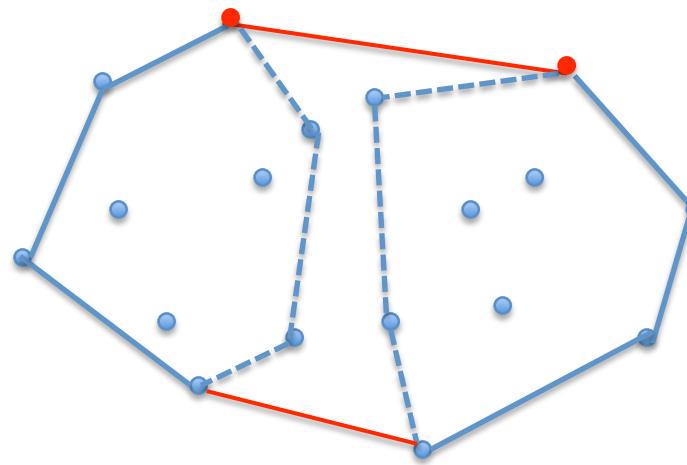
Determine the upper tangente

3. Merge both solutions



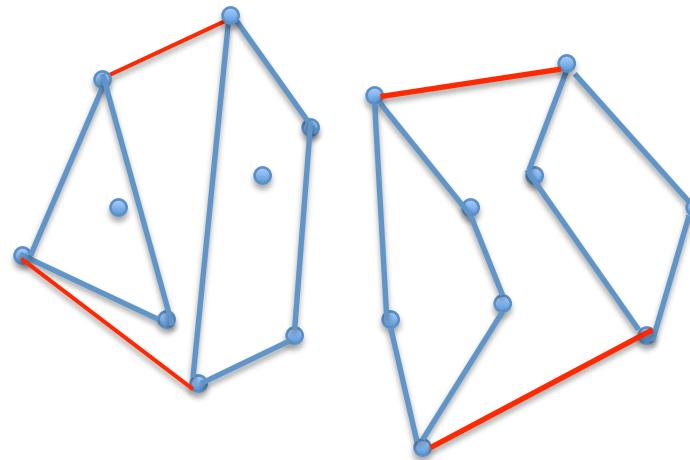
Determine the upper tangente

3. Merge both solutions

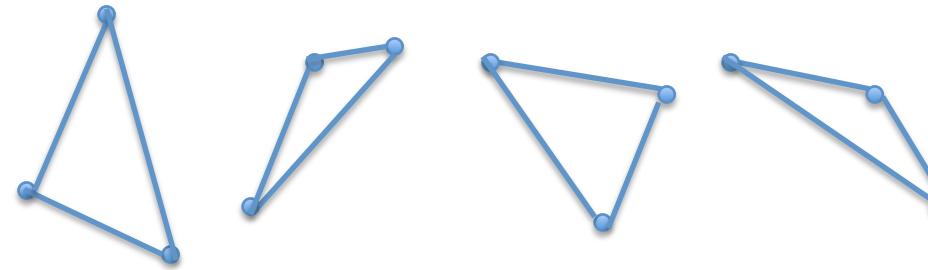


Determine the lower tangent

Recursive decomposition



Basis of the induction by « brute force » case analysis



4 types of triangles

Cost analysis: $T(n) = 2 T(n/2) + O(n) = O(n \log_2(n))$