



department  
Mobility and  
Public Works

# Ship Behaviour in Shallow and Confined Water: an Overview of Hydrodynamic Effects through EFD

**Katrien Eloot and Marc Vantorre**  
**13-10-2011**  
**Portsmouth**

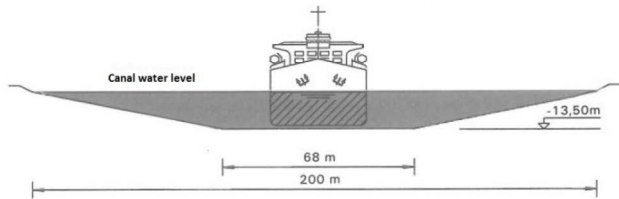


## Introduction

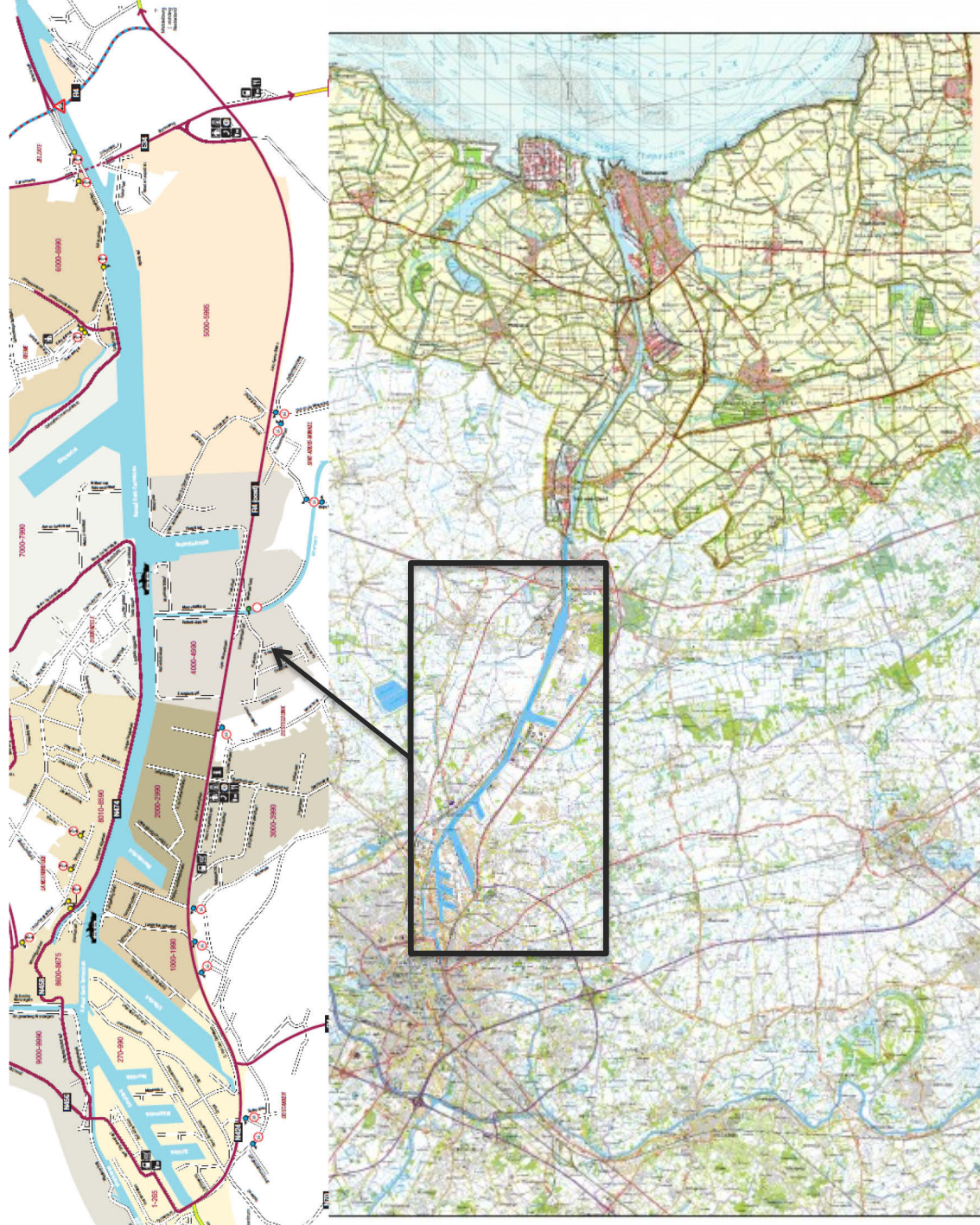
### Ship Behaviour in Shallow and Confined Water

- **Shallow and confined water areas in Flanders**
  - Canal Ghent-Terneuzen: interaction of maritime and inland fleet
  - Upper Sea-Scheldt: inland waterway
- **Effect on ship behaviour**
  - ship manoeuvring in open and shallow water
  - bank effects
  - ship-to-ship interaction
  - nautical bottom

# Canal Ghent- Terneuzen

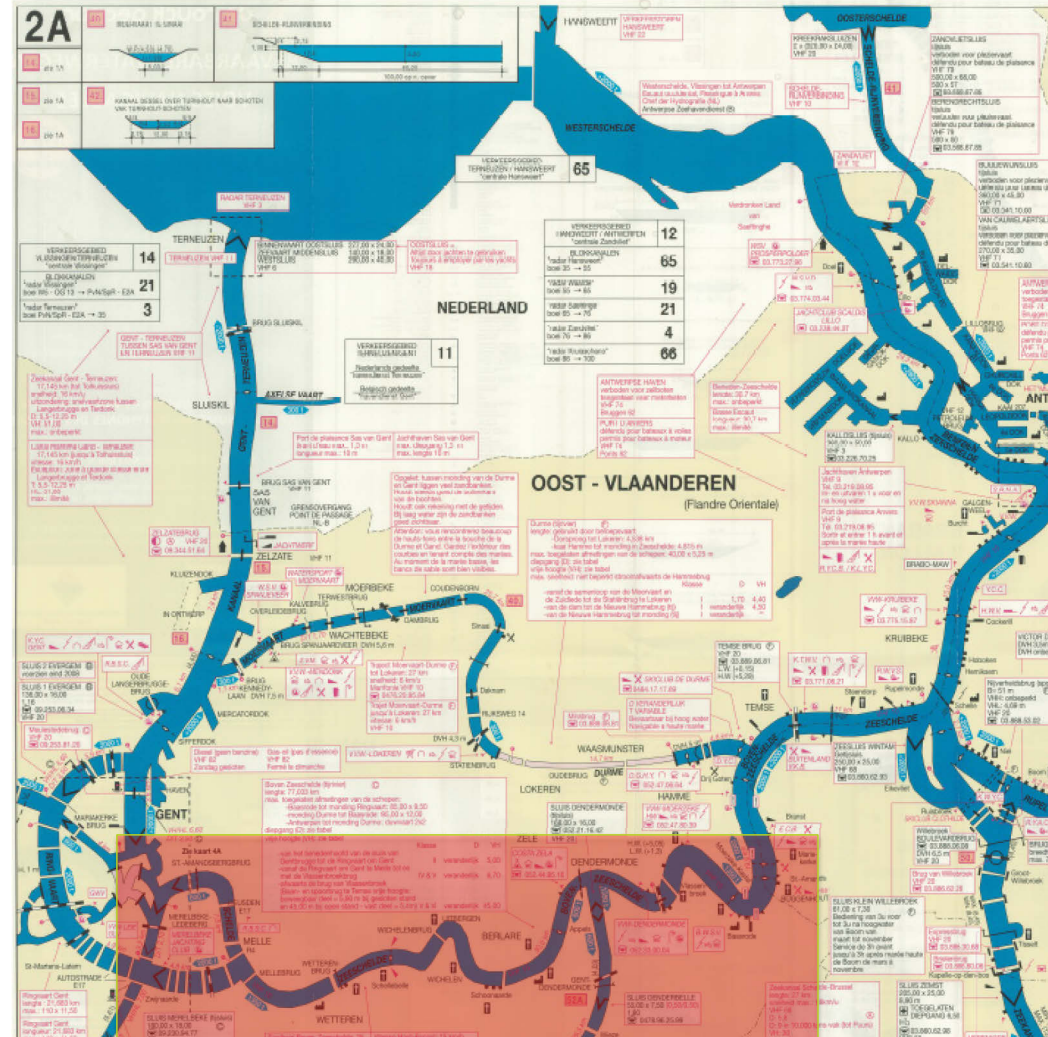


Designed for a panamax sized vessel increased to a beam of 37 m. 38 m is under investigation





# Upper Sea-Scheldt



## Introduction

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- **Shallow and confined water areas in Flanders**

- Canal Ghent-Terneuzen: interaction of maritime and inland fleet
- Upper Sea-Scheldt: inland waterway
- Port of Zeebrugge: nautical bottom – mud layer above a solid bottom

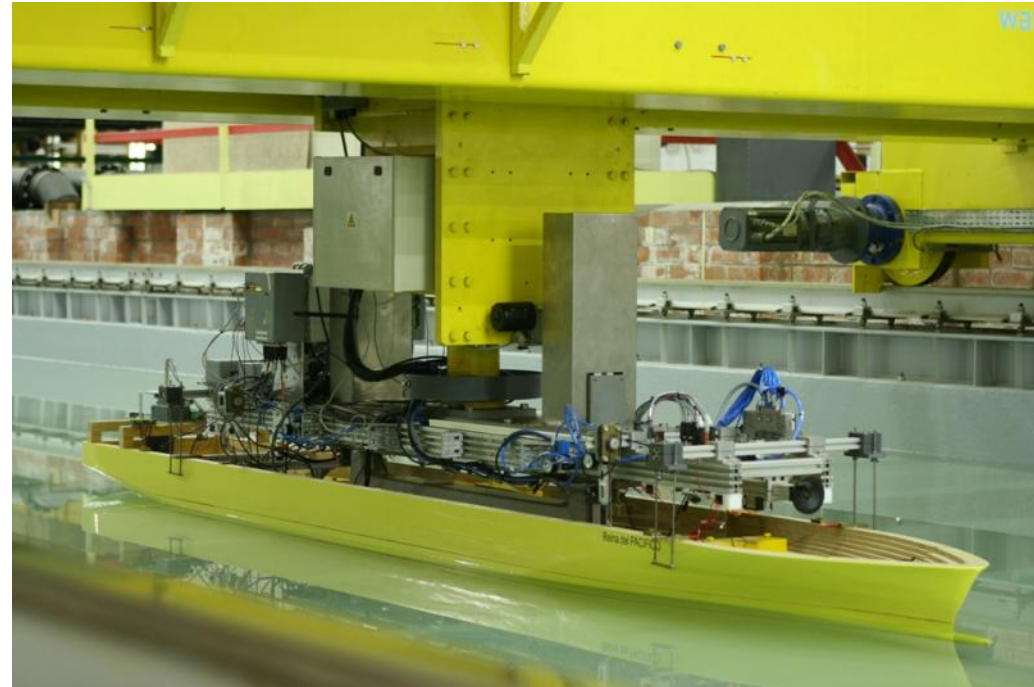




## Introduction

Ship Behaviour in Shallow and Confined Water

Towing tank for manoeuvres in shallow water (co-  
operation Flanders Hydraulics Research – Ghent  
University)



## Introduction

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    - bank effects
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    - nautical bottom
- used for
- admittance policy
  - inland navigation

## Introduction

### Ship Behaviour in Shallow and Confined Water

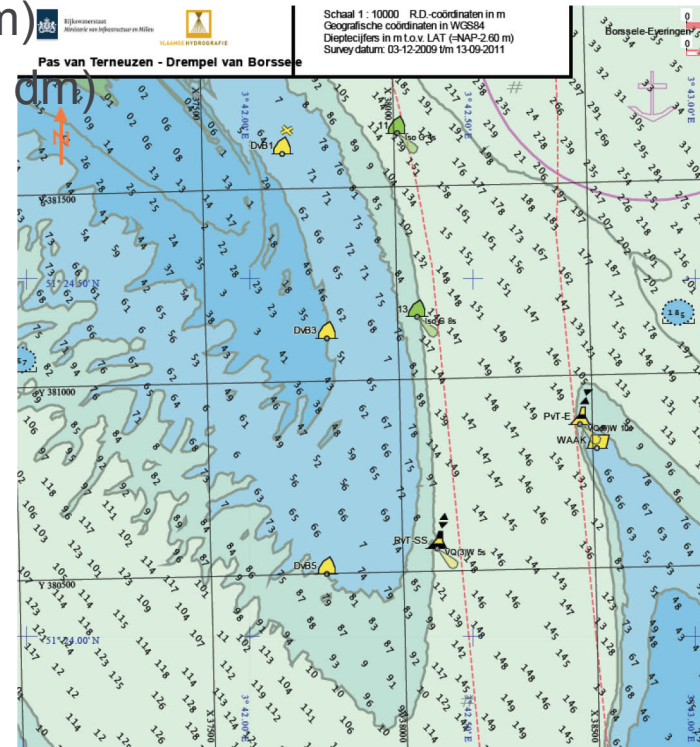
- **Effect on ship behaviour – video 38**

18/04/2005 – Vlissingen – Springergeul

Lykes Motivator 243 m x 32 m (103 dm)

MSC Katherine Ann 184 m x 25 m (77 dm)

Zarechensk 180 m x 28 m (107 dm)





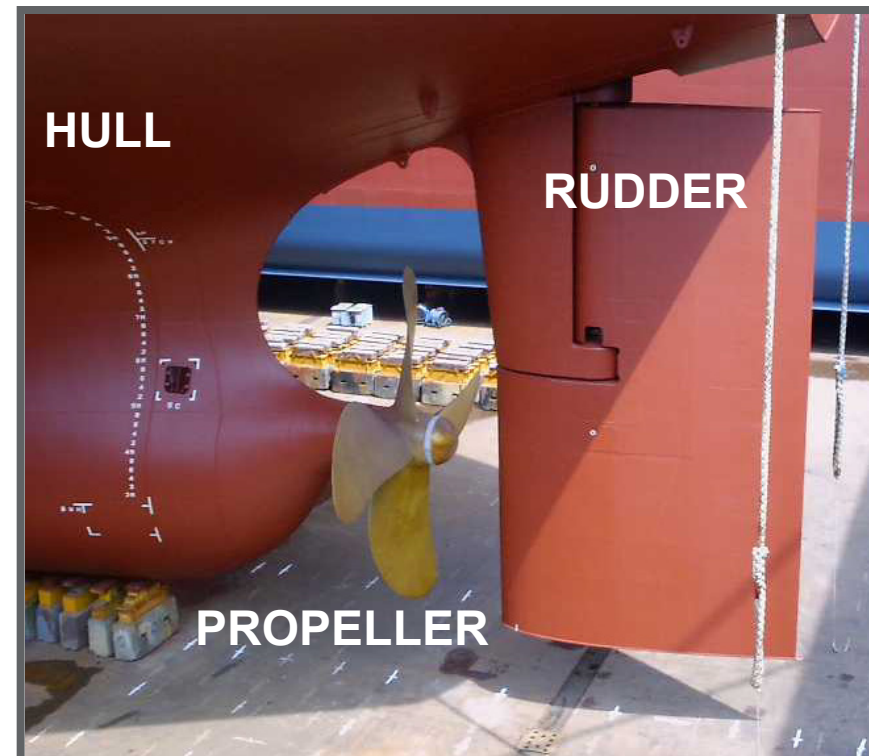
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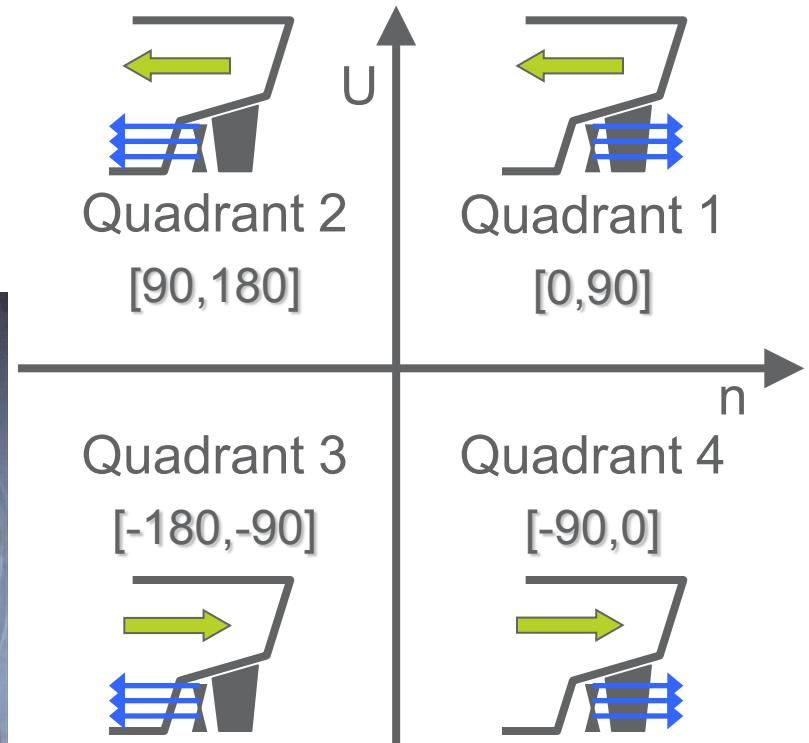
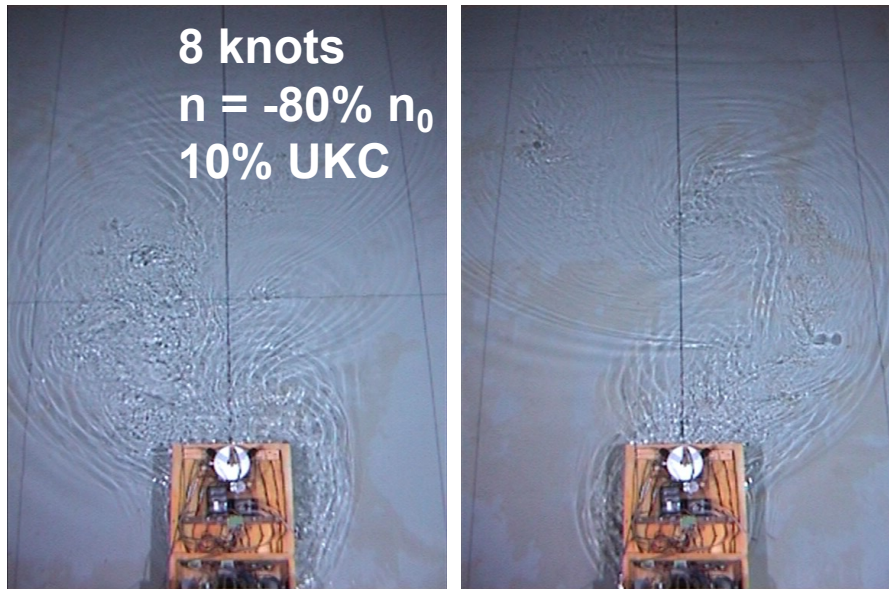
## Ship manoeuvring in shallow water

- Literature review: manoeuvring performance
  - **Ankudinov:** *“concept of modularity based on a separate representation of elements of the manoeuvring model”*
  - **Japan Towing Tank Committee:** MMG model



## Ship manoeuvring in shallow water

- Literature review: manoeuvring performance
  - Ankudinov
  - Japan Towing Tank Committee
  - Oltmann & Sharma, HSVA:  
four quadrant concept



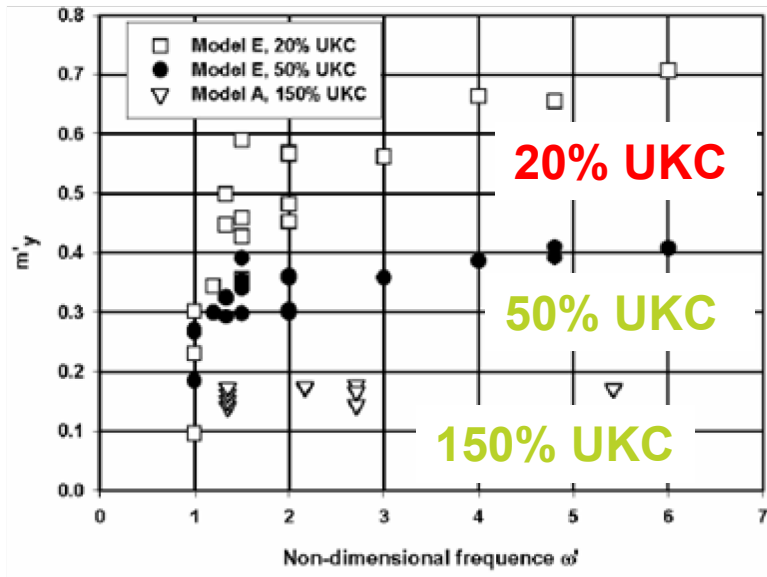


## • Ship manoeuvring in shallow water

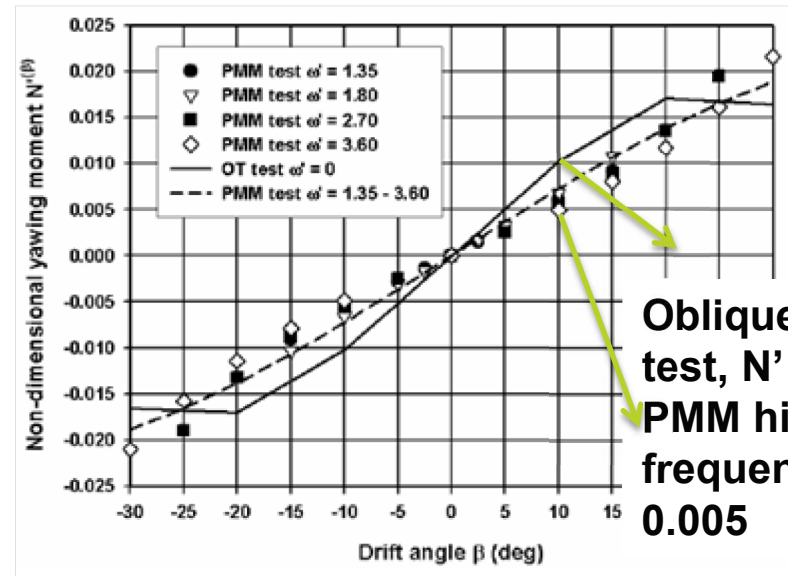
- Literature review: manoeuvring performance
  - **Ankudinov**
  - **Japan Towing Tank Committee**
  - **Oltmann & Sharma, HSVA**
  - **Hydronautics Research**: low speed manoeuvring models
  - **Force Technology (DMI)**: look-up tables
  - **Flanders Hydraulics Research**: modular and tabular manoeuvring models (3 or 4 DOF) based on captive model tests and validated using free-running model tests and full scale measurements

# Ship manoeuvring in shallow water

- Model tests
  - Flanders Hydraulics Research: *increasing influence of chosen test parameters during captive model tests on the derived mathematical model when UKC is decreasing*



Test frequency

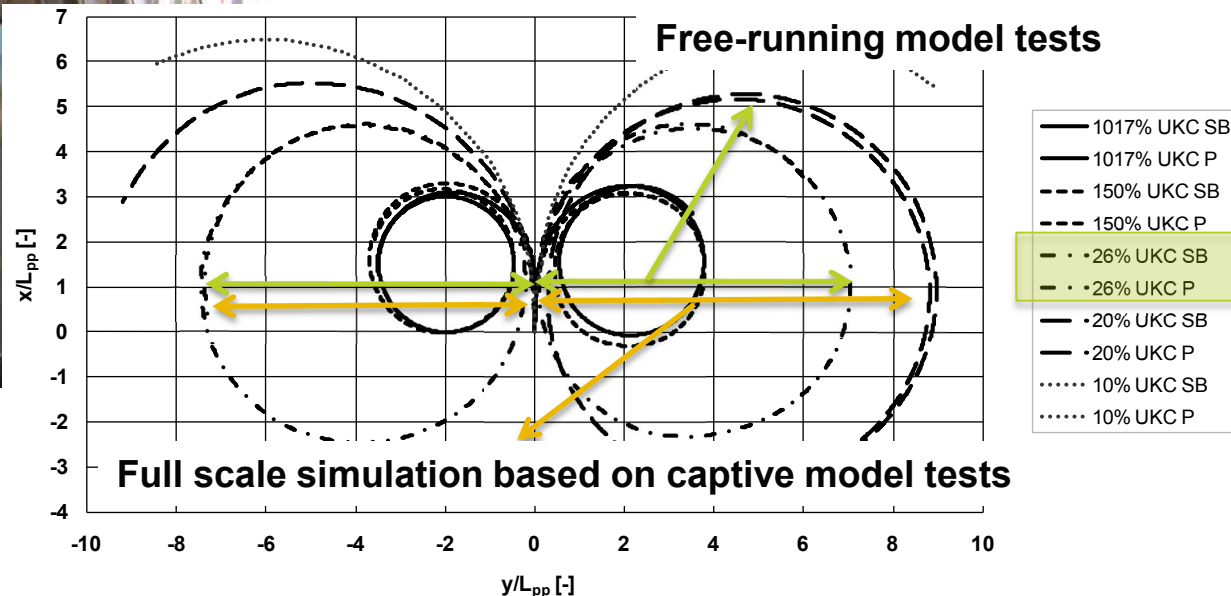
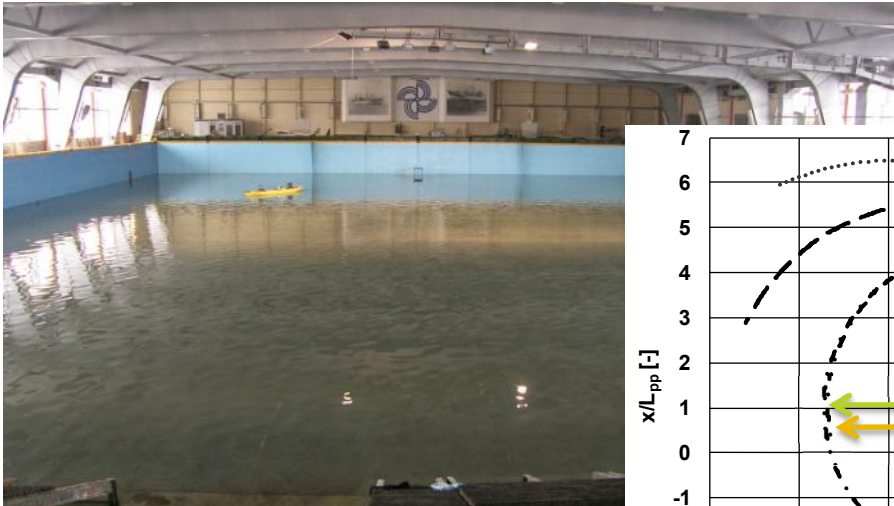


Test type

Oblique towing test,  $N' = 0.010$   
PMM highest frequency,  $N' = 0.005$

# Ship manoeuvring in shallow water

- Simulation model
  - **Flanders Hydraulics Research: increasing influence of chosen test parameters during captive model tests on the derived mathematical model when UKC is decreasing**





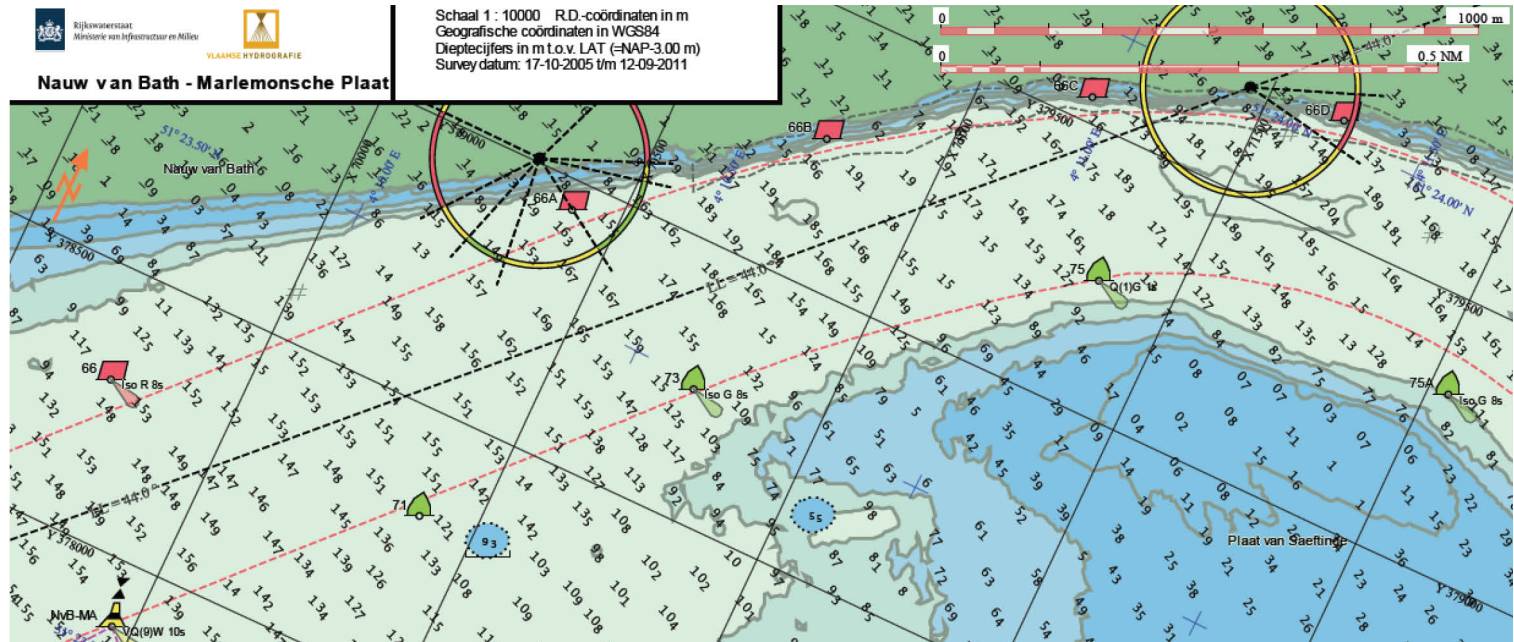
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  - inland navigation

# Ship behaviour due to bank effects

- Video



## Ship behaviour due to bank effects

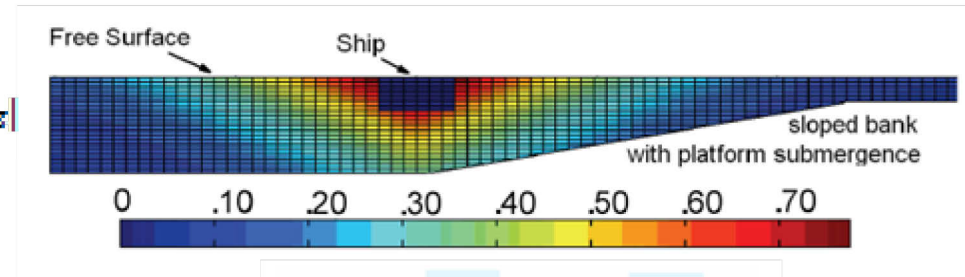
- Norrbin: “if the channel banks are not vertical walls but sloping beaches the definition of the bank distance parameter is less obvious.”, work extended by Ch’ng, Doctors and Renilson

Which vertical reference height to measure the distance between a ship and a bank?

Other formulations for the hydrodynamic changes in the water flow due to the vicinity of banks

- FHR and UGent:  $d_{2b}$  and  $m_{eq}$

Weight distribution  $e^{-a|y|-b|z|}$



$$m_{eq} = \left[ \text{Diagram 1} + \text{Diagram 2} \right] - \left[ \text{Diagram 3} + \text{Diagram 4} \right]$$

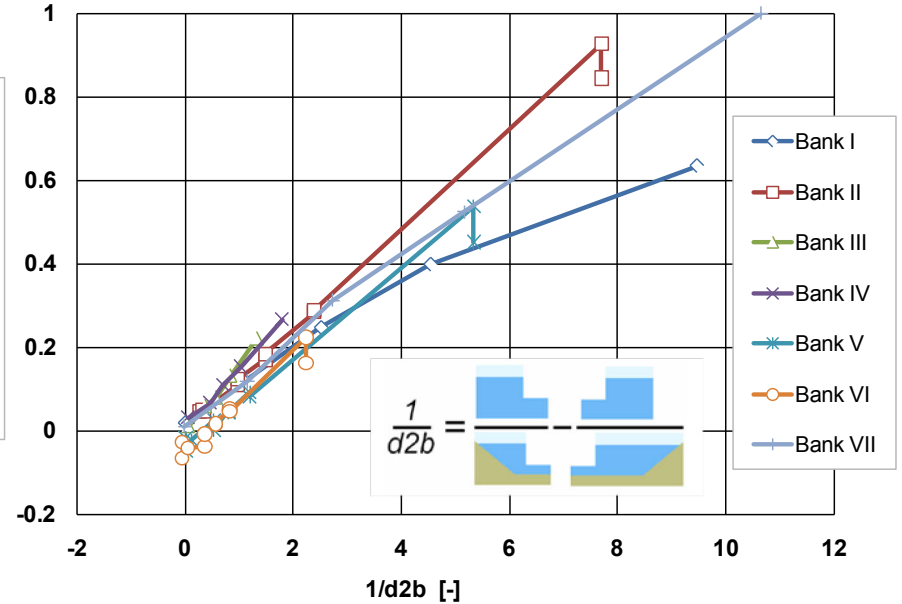
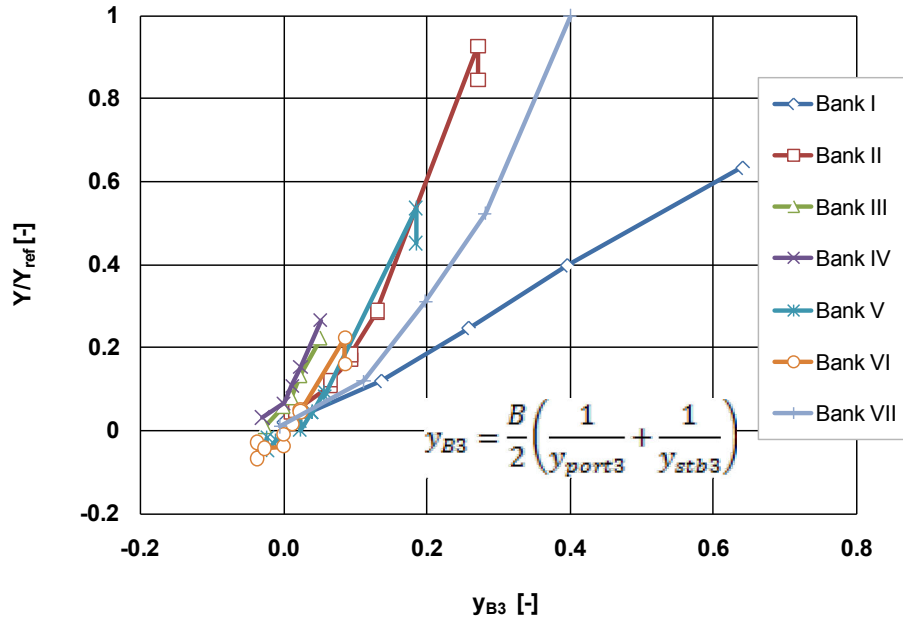
The diagram shows four cross-sectional views of a channel with a ship. The first two diagrams are added together, and the last two are subtracted from the sum. Each diagram shows the ship's position relative to the water surface and the channel banks.

$$\frac{1}{d_{2b}} = \left[ \text{Diagram 5} \right] - \left[ \text{Diagram 6} \right]$$

The diagram shows two cross-sectional views of a channel with a ship. The first diagram is subtracted from the second. Each diagram shows the ship's position relative to the water surface and the channel banks.

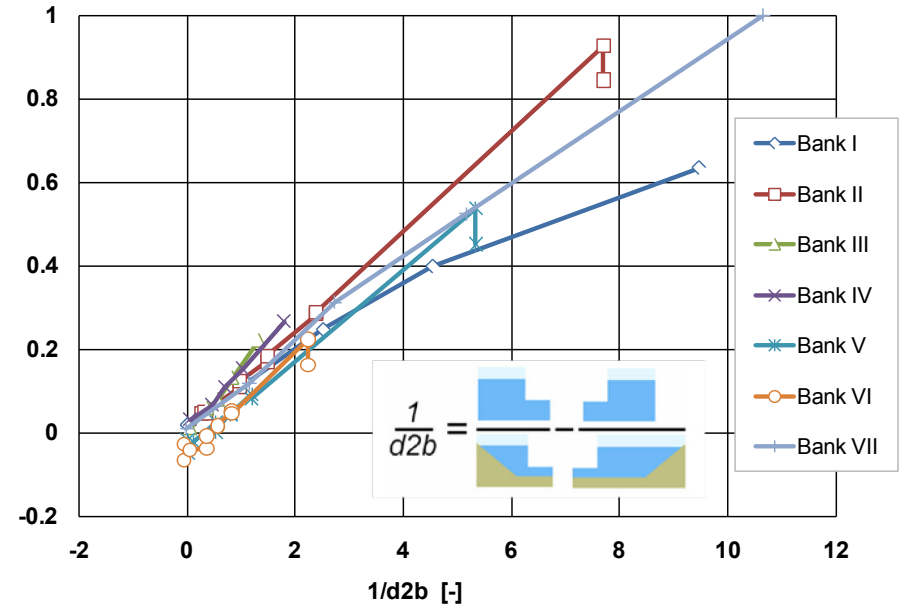
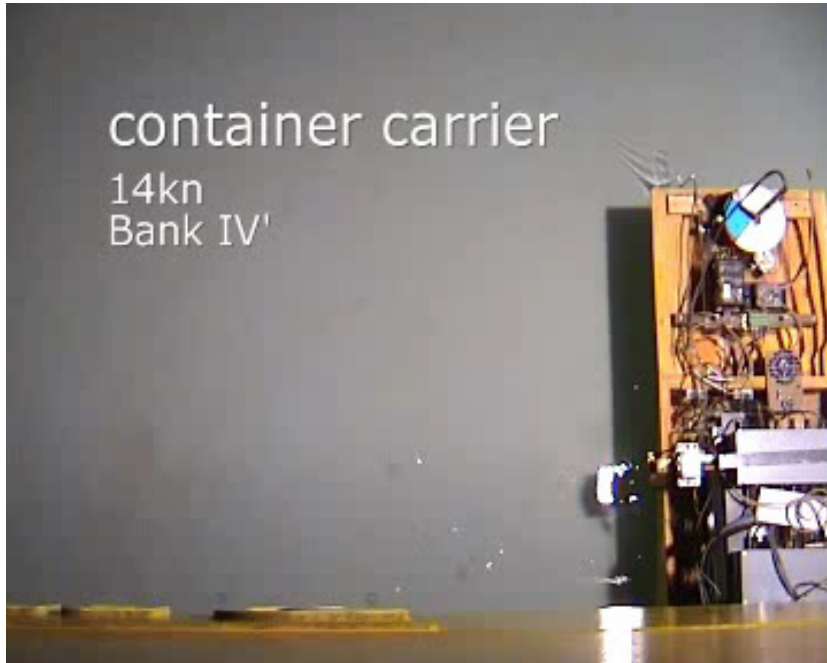


# Ship behaviour due to bank effects



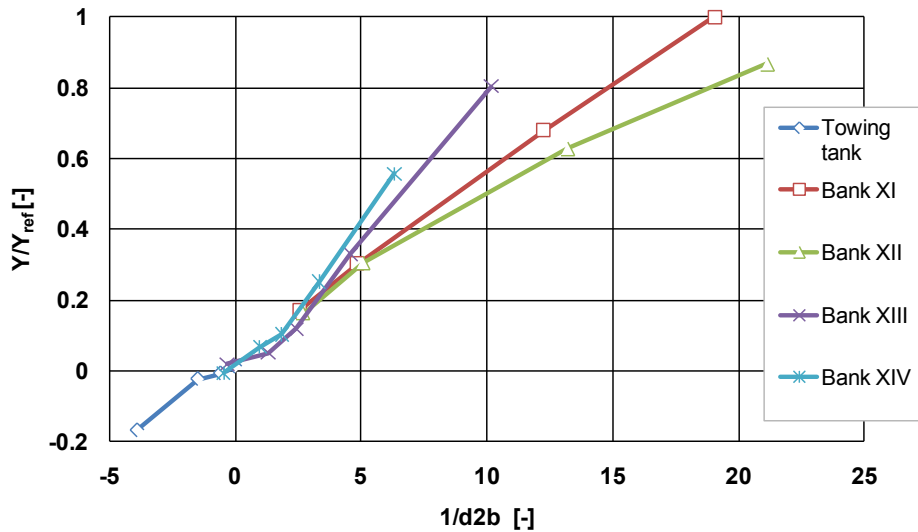
Container carrier at 10 knots and 100% UKC, no propeller

# Ship behaviour due to bank effects



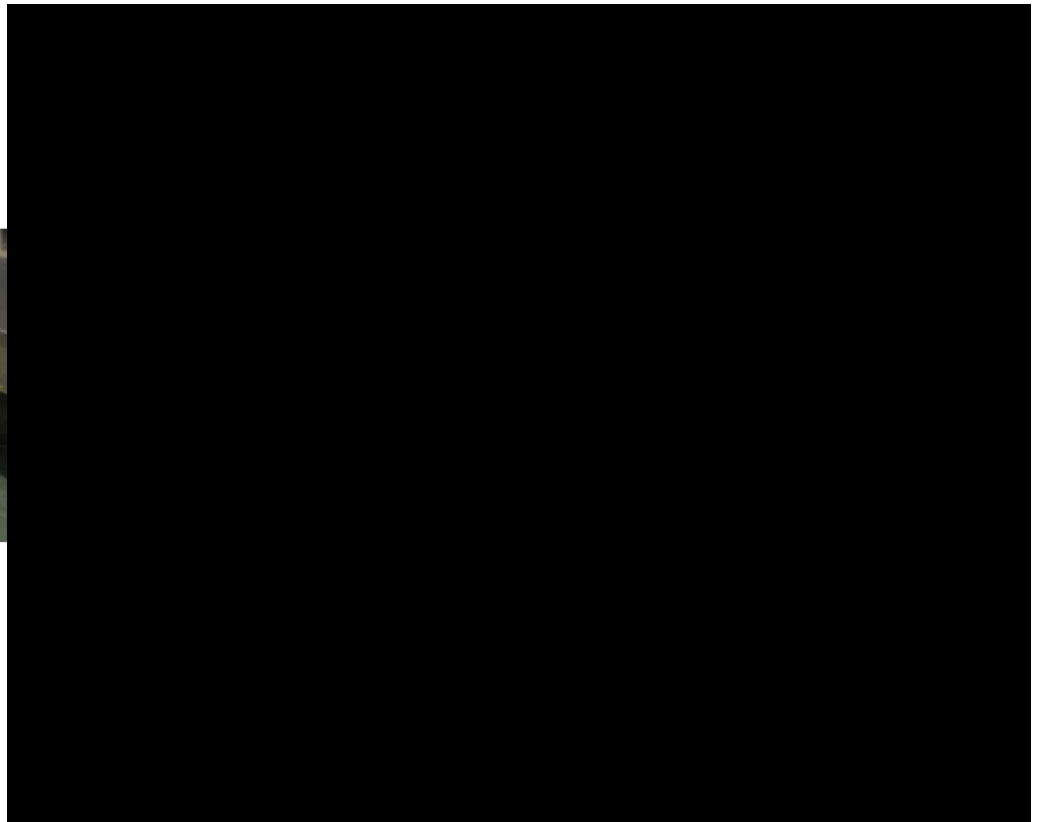
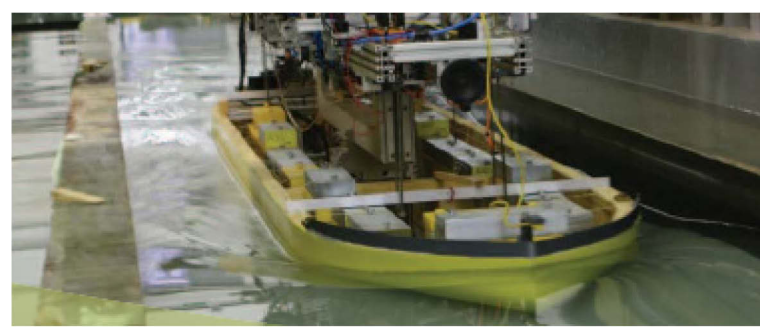
# Ship behaviour due to bank effects

- KVLCC2 (10 knots, 50% UKC)



# • Ship behaviour due to bank effects

- KVLCC2



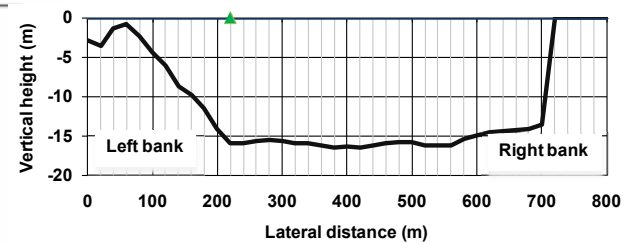
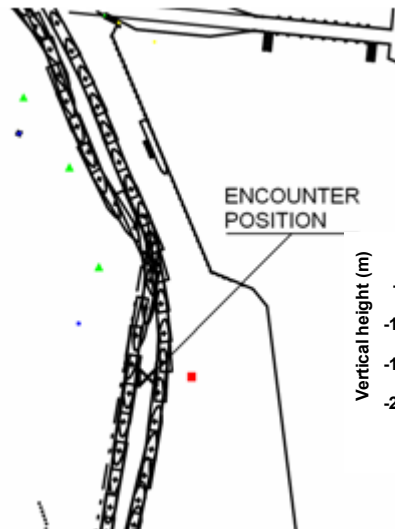
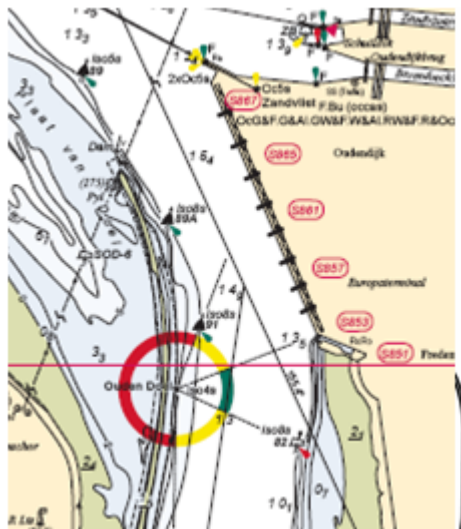


# Ship behaviour due to bank effects

Real-time simulation study: meeting of two ULCS

Length 350 to 400 m

Beam 42.8 to 56.4 m



## Overview

### Ship Behaviour in Shallow and Confined Water

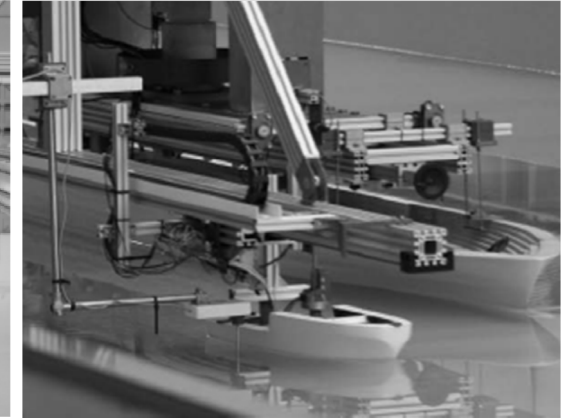
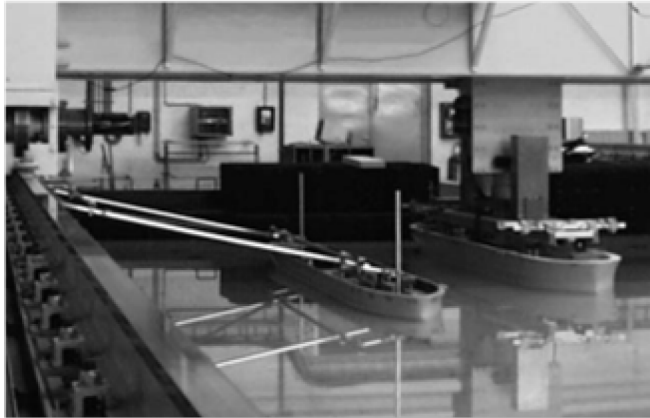
- **Shallow and confined water areas in Flanders**
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# Ship behaviour during ship-to-ship interaction

Knowledge Centre Manoeuvring in Shallow and Confined Water,  
Conference May 2011 hosted by NTNU and MARINTEK

- **moored ships alongside quays;**
- **ships anchored or moored to buoys;**
- **ships meeting / passing on parallel / oblique / curved / steered paths;**
- **interaction with more than one ship or marine structure;**
- **ship-to-ship interaction during lightering operations;**
- **ship-to-ship interaction during tug assistance.**

# Ship behaviour during ship-to-ship interaction



Meeting and overtaking

Lightering

Tug – ship interaction

Ship		C	D	E	H
$L_{pp}$	m	3.984	3.864	3.824	2.210
B	m	0.504	0.550	0.624	0.296
$T_{ref}$	m	0.180	0.180	0.207	0.178
$C_B$ (at $T_{ref}$ )	-	0.843	0.588	0.816	0.830
T	m	0.155 – 0.200	0.155 – 0.200	0.136 – 0.256	0.125 – 0.178



# Ship behaviour during ship-to-ship interaction

Project: KMB Investigating hydrodynamic aspect and control systems for ship-to-ship operations, co-ordinated by MARINTEK and financially supported by the Research Council of Norway

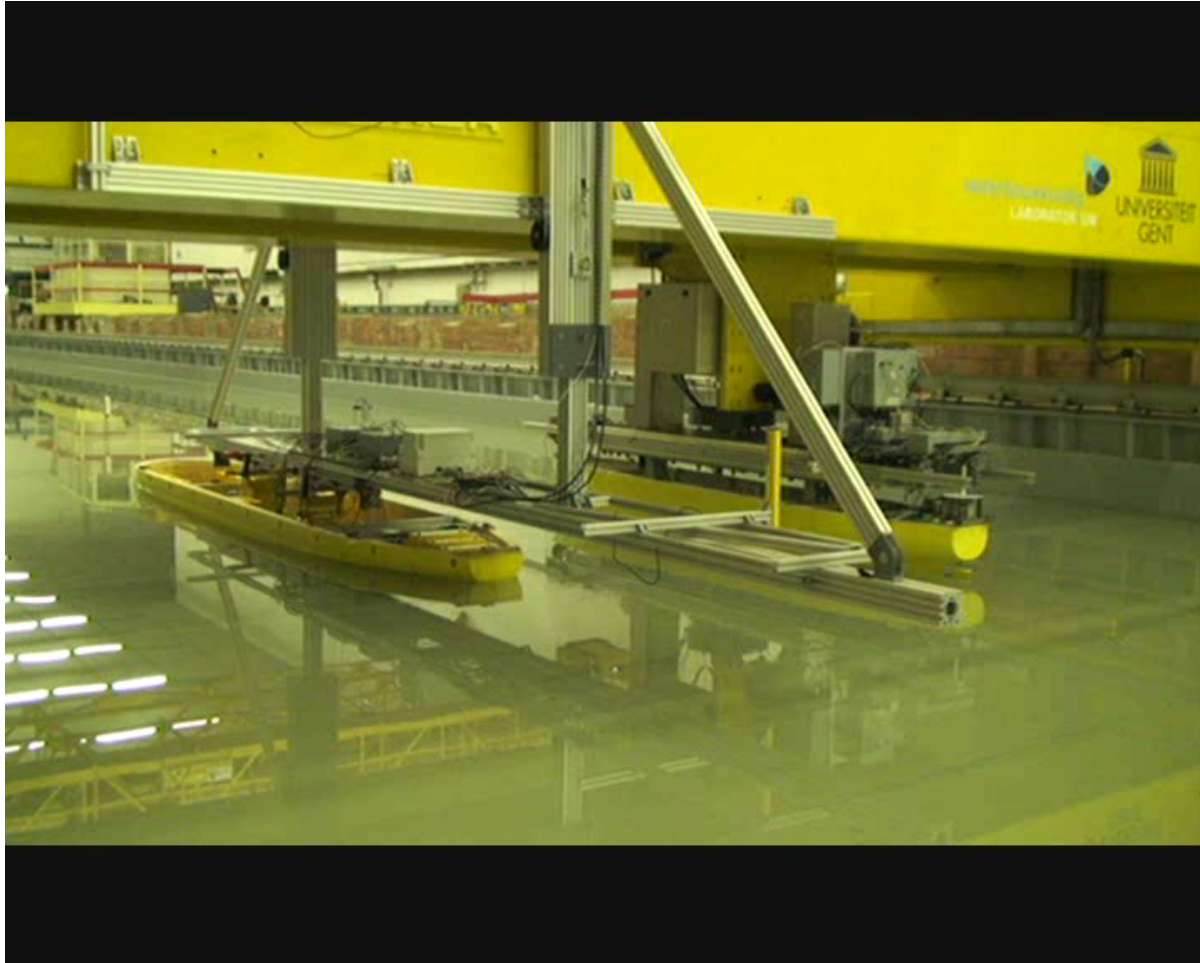
- Zero longitudinal speed difference
- Special case of overtaking and overtaken
- Steady state and dynamic tests
- Open STS data



Lightering

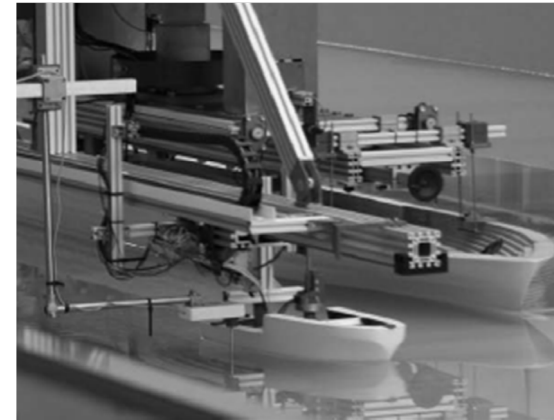
h	$T_{STBL}$	$n_{STBL}$	V	$T_{SS}$	$\psi_{SS}$	$n_{SS}$	$\delta y$	$\delta x$	
[m]	[m]	[-]	[kts]	[m]	[deg]	[-]	[m]	[m]	
$h_{max}$	20.8	selfprop	2.0	7.5	180	Slow	4	0	
$1.35 T_{STBL}$	12.8		4.0	15	179	Half	10	L/2	
			5.0		178	selfprop		25	-L/2
			6.0		177			50	
					175			100	

# Ship behaviour during ship-to-ship interaction



Lightering

# Ship behaviour during ship-to-ship interaction



Tug – ship interaction

Forward speed [knots], full scale	5, 6, 7, 8, 9
Longitudinal separation $x'_{rel}$ [-], from amidships of container vessel to centre of gravity of tug (non-dimensional value based on length of tug)	0.73, 1.25, 1.77, 2.29, 2.82, 3.33, 3.88, 4.41, 4.93
Transverse separation $y'_{rel}$ [-], from centreline to centreline (non-dimensional value based on breadth of tug)	2.6, 3.3, 4.0, 4.4, 5.3
Drift angle [°], negative angle bow-in since tug model is situated on starboard in the towing tank	-10, -5, 0, 5, 10

# Ship behaviour during ship-to-ship interaction

- Dedicated interaction models – complex pressure field change
- Different methodic combinations as EFD, CFD or other numerical codes
- JIP – ROPES, lead partner MARIN, Research on Passing Effects on Ships



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- **nautical bottom**

used for

- admittance policy
- inland navigation

## Nautical bottom

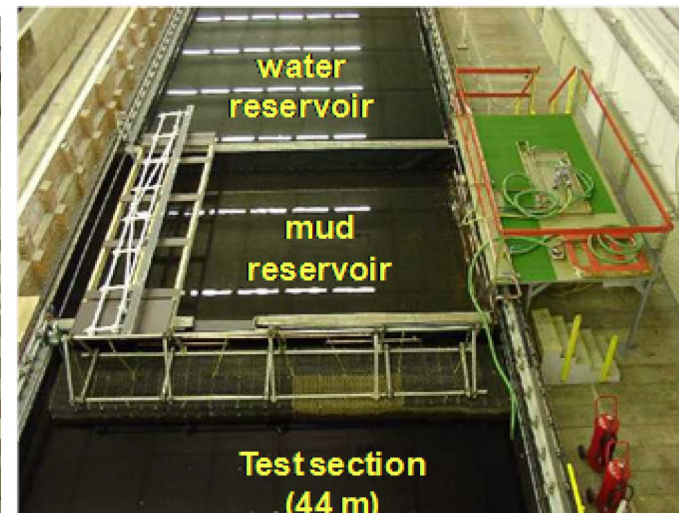
- PIANC: *“nautical bottom as the level where physical characteristics of the bottom reach a critical limit beyond which contact with a ship's keel causes either damage or unacceptable effects on controllability and manoeuvrability”*
  - **Multidisciplinary approach: measuring/survey techniques, dredging techniques, physical mud characteristics, effect of mud layers on the behaviour of ships**
  - **EFD and nautical bottom research = how incorporate viscous effects if Reynold's law is not fulfilled? Mud layer is a homogeneous layer with constant density and rheological properties.**

## Nautical bottom

- Model tests at FHR
  - Layer thickness
  - Mud density
  - Mud viscosity
  - Under keel clearance



78 parameter combinations



## Nautical bottom

- Results for the port of Zeebrugge
  - **Density criterion is 1.2 ton/m<sup>3</sup> instead of 1.15 ton/m<sup>3</sup>**
  - **Navigation through the mud (negative UKC's water-mud interface)**
  - **300 m length container ship -7% UKC assisted by two 45 ton tugs**
- Main causes for the effect of mud layers on ship manoeuvrability:
  - **Internal wave pattern in the water-mud interface greatly depended on mud density**
  - **Rheological characteristics of the mud: (non –) Newtonian fluid**
- Development of in situ survey techniques  
STT sediment test tank



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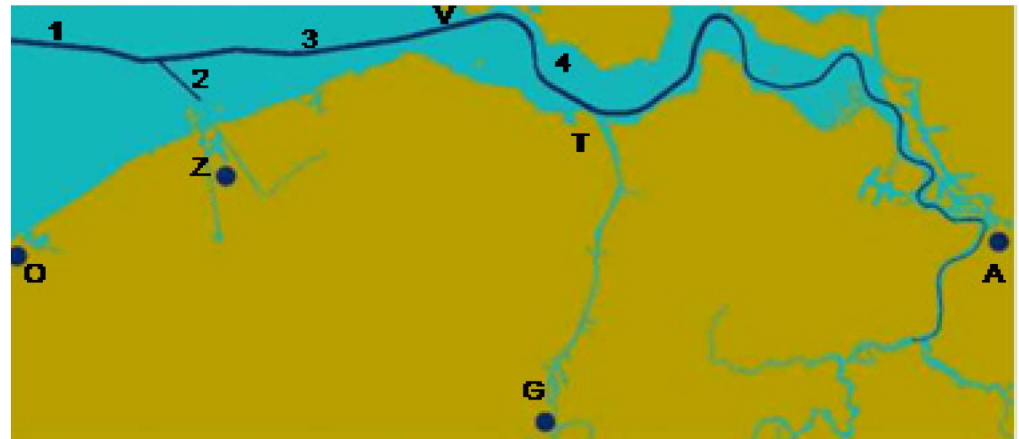
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## Example 1: admittance policy

Admittance policy based on a certain window

- **Tidal water level (min. gross UKC, % ship's draft):**
  - 15% coastal channels 1, 3
  - 12.5% for 2 and 4 (Dutch part)
  - 10% for 4 (Belgian part) and Z outer harbour
  - 1 m for Sea Canal Terneuzen – Ghent
- **Current (Z: 2 kn – 1.5 kn)**
- **Penetration in fluid mud (Z: 7%)**



## Example 1: admittance policy

Admittance policy based on a gross UKC



Improved by a decision supporting tool ProToel:

- **Deterministic:** *gross UKC (nautical bottom and top of fluid mud layers, lateral current component)*
- **Probabilistic:** *probability of bottom touch (due to squat and response to waves) < selected maximum value*

Used for long term and short term decisions for the maximum allowable draft

Evaluation phase by the Flemish Pilotage and Shipping Assistance Division for the port of Zeebrugge

# Example 1: admittance policy

ship hull: W100 trajectory: KWB\_Z-All\_K120 (S1)  
maximal draft [m]: 15.5 date of departure: 01/08/2008 CET  
GM [m]: 0.0 waves considered: true

location	8:15 CET	8:30 CET	8:45 CET	9:00 CET	9:15 CET	9:30 CET	9:45 CET	10:00 CET	10:15 CET	10:30 CET	10:45 CET	11:00 CET	11:15 CET	11:30 CET	11:45 CET	12:00 CET	12:15 CET	12:30 CET	12:45 CET	13:00 CET	13:15 CET	13:30 CET	13:45 CET	14:00 CET	
Kwintebank	0.70	0.70	0.78	0.85	0.90	0.94	0.99	1.04	1.09	1.14	1.19	1.24	1.29	1.34	1.39	1.44	1.49	1.54	1.59	1.64	1.69	1.74	1.79	1.84	1.89
PvhZ-SZ	1.29	1.44	1.55	1.65	1.73	1.84	1.96	2.08	2.22	2.38	2.56	2.80	3.07	3.40	3.76	4.11	4.41	4.60	4.70	4.71	4.67	4.60	4.51	4.39	4.21
PvhZ-Strekdammen	0.94	0.95	10.10	10.25	10.40	10.55	11.10	11.25	11.40	11.55	12.10	12.25	12.40	12.55	13.10	13.25	13.40	13.55	14.10	14.25	14.40	14.55	15.10	15.25	15.40
Zeebrugge A2 K120	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02	1.02
Kwintebank-Scheur	1.82	1.87	1.97	2.04	2.21	2.30	2.48	2.57	2.76	2.85	3.02	3.11	3.31	3.42	3.69	3.84	4.20	4.41	4.82	5.01	5.30	5.40	5.42	5.37	5.37
Scheur_West	2.01	2.16	2.30	2.42	2.52	2.62	2.73	2.85	2.99	3.12	3.29	3.49	3.73	4.02	4.36	4.71	5.03	5.30	5.46						
Pas_van_het_Zand	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10	1.10
Zeebrugge	1.48	1.51	1.61	1.67	1.75	1.74	1.82	1.91	2.03	2.17	2.34	2.52	2.80	3.12	3.49	3.76	4.02	4.36	4.71	5.03	5.30	5.46			
Zeebrugge_Ingang	1.48	1.51	1.61	1.67	1.75	1.74	1.82	1.91	2.03	2.17	2.34	2.52	2.80	3.12	3.49	3.76	4.02	4.36	4.71	5.03	5.30	5.46			
Zeebrugge_Kaai	1.48	1.51	1.61	1.67	1.75	1.74	1.82	1.91	2.03	2.17	2.34	2.52	2.80	3.12	3.49	3.76	4.02	4.36	4.71	5.03	5.30	5.46			

ship hull: W100 trajectory: KWB\_Z-All\_K120 (S1)  
maximal draft [m]: 15.5 date of departure: 01/08/2008 CET  
GM [m]: 0.0 waves considered: true

location	limit	8:15 CET	8:30 CET	8:45 CET	9:00 CET	9:15 CET	9:30 CET	9:45 CET	10:00 CET	10:15 CET	10:30 CET	10:45 CET	11:00 CET	11:15 CET	11:30 CET	11:45 CET	12:00 CET	12:15 CET	12:30 CET	12:45 CET	13:00 CET	13:15 CET	13:30 CET	13:45 CET	14:00 CET	
Kwintebank	location reached at [CET]	08:24	08:39	08:54	09:09	09:24	09:39	09:54	10:09	10:24	10:39	10:54	11:09	11:24	11:39	11:54	12:09	12:24	12:39	12:54	13:09	13:24	13:39	13:54	14:09	
PvhZ-SZ	location reached at [CET]	09:40	09:55	10:10	10:25	10:40	10:55	11:10	11:25	11:40	11:55	12:10	12:25	12:40	12:55	13:10	13:25	13:40	13:55	14:10	14:25	14:40	14:55	15:10	15:25	
PvhZ-Strekdammen	location reached at [CET]	1:37	1:49	1:58	1:67	1:78	1:90	2:03	2:17	2:34	2:53	2:78	3:07	3:42	3:79	4:15	4:44	4:63	4:71	4:71	4:66	4:58	4:48	4:36	4:21	
Zeebrugge A2 K120	location reached at [CET]	10:12	10:27	10:42	10:57	11:12	11:27	11:42	11:57	12:12	12:27	12:42	12:57	13:12	13:27	13:42	13:57	14:12	14:27	14:42	14:57	15:12	15:27	15:42	15:57	
Kwintebank-Scheur	min gross UKC to nautical bottom [%]	15.00	11.77	12.07	12.71	13.16	14.23	14.81	15.98	16.59	17.79	18.37	19.49	20.07	21.35	22.08	23.78	24.79	27.12	28.43	31.09	32.31	34.22	34.85	35.00	34.62
	min gross UKC to nautical bottom [m]	2.32	1.82	1.87	1.97	2.04	2.21	2.30	2.48	2.57	2.76	2.85	3.02	3.11	3.31	3.42	3.69	3.84	4.20	4.41	4.82	5.01	5.30	5.40	5.42	5.37
	point on trajectory	200	500	500	500	500	500	500	500	500	500	500	500	500	500	500	500	500	500	500	500	500	500	500	500	
Scheur_West	min gross UKC to nautical bottom [%]	15.00	12.96	13.95	14.85	15.63	16.36	16.93	17.64	18.41	19.26	20.16	21.23	22.50	24.08	25.96	28.13	30.39	32.48	34.19	35.23					
	min gross UKC to nautical bottom [m]	2.32	2.01	2.16	2.30	2.42	2.52	2.62	2.73	2.85	2.99	3.12	3.29	3.49	3.73	4.02	4.36	4.71	5.03	5.30	5.46					
Pas_van_het_Zand	min gross UKC to nautical bottom [%]	12.50	14.12	15.07	15.83	16.42	16.99	17.67	18.43																	
	min gross UKC to nautical bottom [m]	1.94	2.19	2.34	2.45	2.55	2.63	2.74	2.86																	
	point on trajectory	7	7	7	7	7	7	5	7	5	7	5	7	5	7	5	7	5	7	5	7	5	7	5	7	
Zeebrugge	min gross UKC to nautical bottom [%]	12.50	14.84	15.61	16.18	16.75	17.49	18.29	19.13	20.03	21.08	22.34	23.92	25.80	28.04	30.45	32.76	34.68	35.85	36.41	36.36	36.03	35.54	34.93	34.12	33.14
	min gross UKC to nautical bottom [m]	1.94	2.30	2.42	2.51	2.60	2.71	2.84	2.96	3.10	3.27	3.46	3.71	4.00	4.35	4.72	5.08	5.38	5.56	5.64	5.64	5.59	5.51	5.41	5.29	5.14
	point on trajectory	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
	min gross UKC to top mud [%]	-7.00	14.84	15.61	16.18	16.75	17.49	18.29	19.13	20.03	21.08	22.34	23.92	25.80	28.04	30.45	32.76	34.68	35.85	36.41	36.36	36.03	35.54	34.93	34.12	33.14
	min gross UKC to top mud [m]	-1.08	2.30	2.42	2.51	2.60	2.71	2.84	2.96	3.10	3.27	3.46	3.71	4.00	4.35	4.72	5.08	5.38	5.56	5.64	5.64	5.59	5.51	5.41	5.29	5.14
	point on trajectory	2.00	1.41	1.31	1.22	1.19																				
Zeebrugge	min gross UKC to nautical bottom [%]	10.00	10.86	11.29	12.00	12.47																				
	min gross UKC to nautical bottom [m]	1.55	1.68	1.75	1.87	1.93																				
	point on trajectory	800	800	800	800	800																				
	min gross UKC to top mud [%]	-7.00	-7.21	-6.40	-6.02	-5.99																				
	min gross UKC to top mud [m]	-1.08	-1.12	-0.99	-0.93	-0.90																				
	point on trajectory	601	610	601	610	610	601	601	601	601	601	601	601	601	601	601	601	601	601	601	601	601	601	601	601	
Zeebrugge_Kaai	min gross UKC to nautical bottom [%]	10.00	11.29	11.67	12.47	13.97	14.05	14.61	15.85	16.56	18.33	19.41	22.01	23.52	26.73	28.25	30.61	31.33	31.91	31.95	31.36	31.02	30.16	29.60	28.26	27.52
	min gross UKC to nautical bottom [m]	1.55	1.75	1.81	1.93	2.01	2.18	2.26	2.46	2.57	2.84	3.01	3.41	3.85	4.14	4.38	4.74	4.86	4.95	4.94	4.86	4.81	4.67	4.59	4.38	4.27
	point on trajectory	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	
	min gross UKC to top mud [%]	-7.00	-6.77	-6.40	-5.59	-5.09	-4.02	-3.45	-2.22	-1.50	0.26	1.34	3.95	5.46	8.66	10.18	12.55	13.27	13.84	13.78	13.29	12.95	12.09	11.54	10.20	9.45
	min gross UKC to top mud [m]	-1.08	-1.05	-0.99	-0.87	-0.79	-0.62	-0.54	-0.34	-0.23	0.04	0.21	0.81	1.34	1.58	1.94	2.06	2.15	2.14	2.06	2.01	1.87	1.79	1.58	1.47	
	point on trajectory	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	615	
probability of bottom touch	1.00E-2	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	1.00E0	

Cross current

Min gross UKC nautical bottom

Penetration in fluid mud

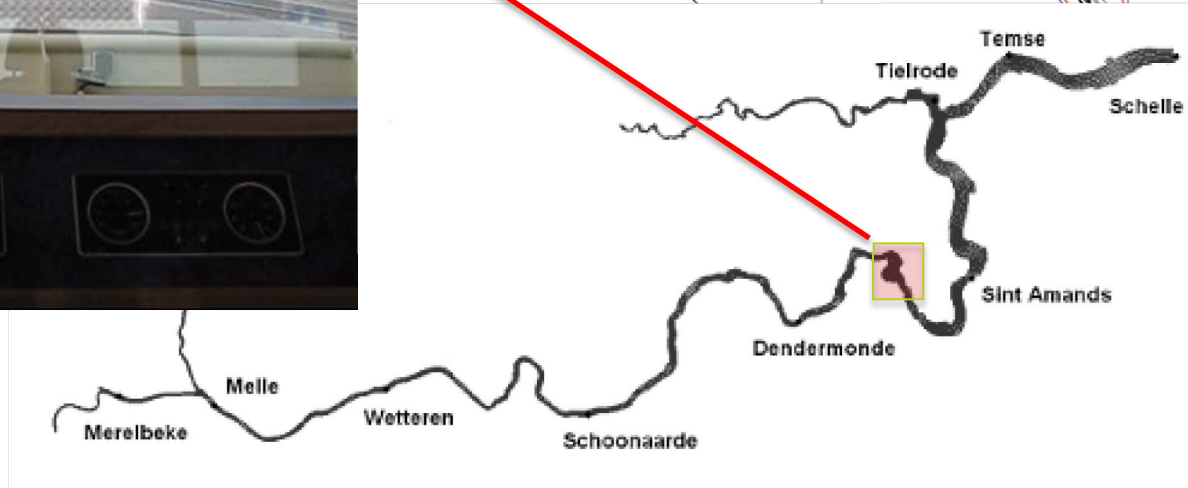
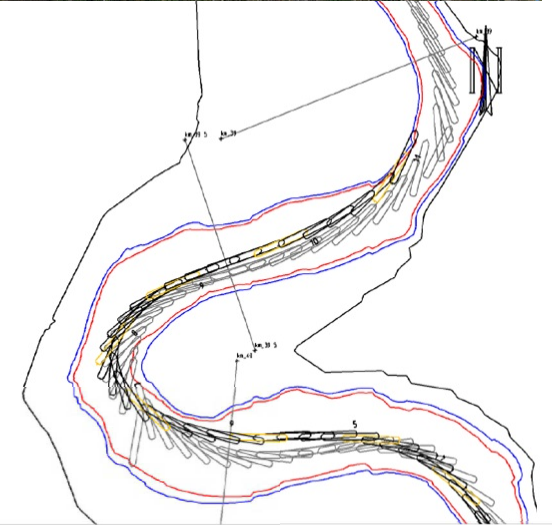
## Overview

### Ship Behaviour in Shallow and Confined Water

- **Shallow and confined water areas in Flanders**
  - **Effect on ship behaviour**
    - ship manoeuvring in open and shallow water
    - bank effects
    - ship-to-ship interaction
    - nautical bottom
- used for
- admittance policy
  - **inland navigation**

## Example 2: inland navigation

Design criteria for inland transport



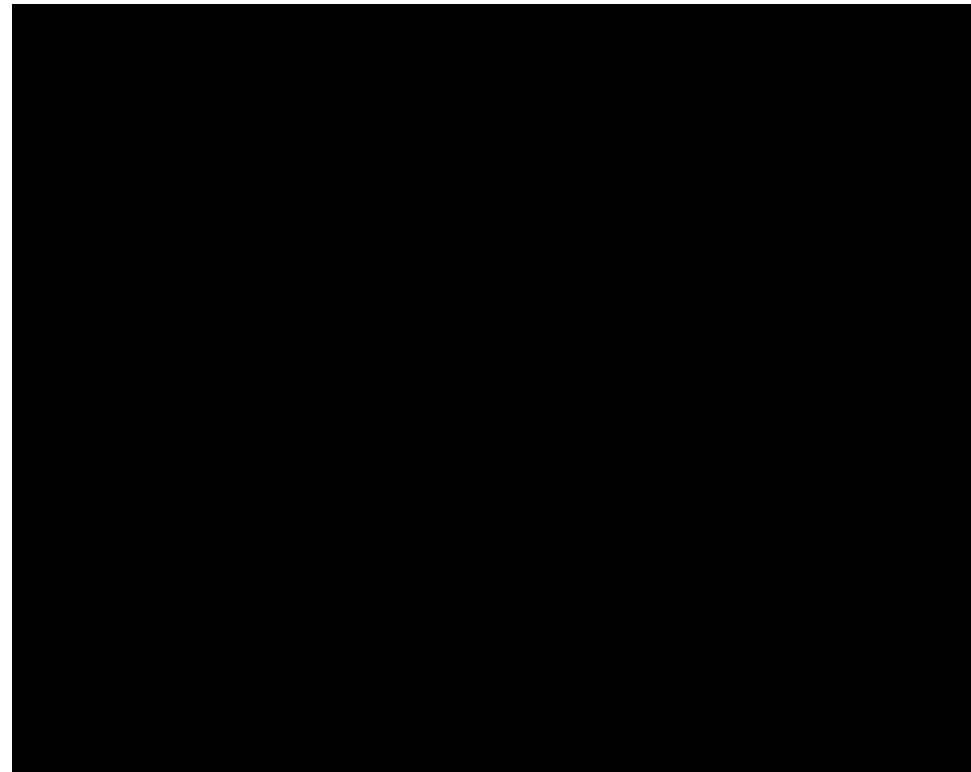
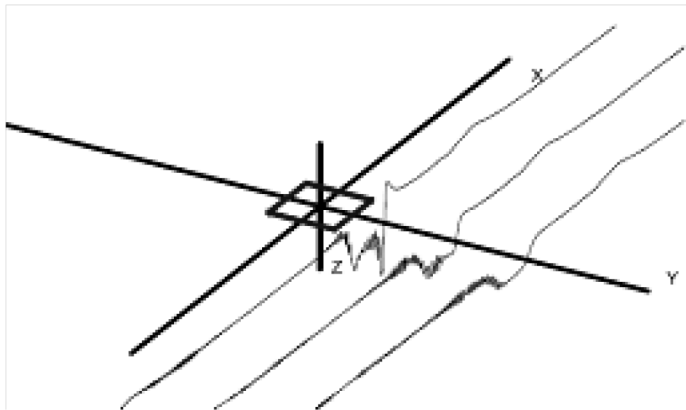


## Example 2: inland navigation

Simulation model based on captive model tests

- Ship manoeuvring in shallow water
- Bank effects
- STS interaction module

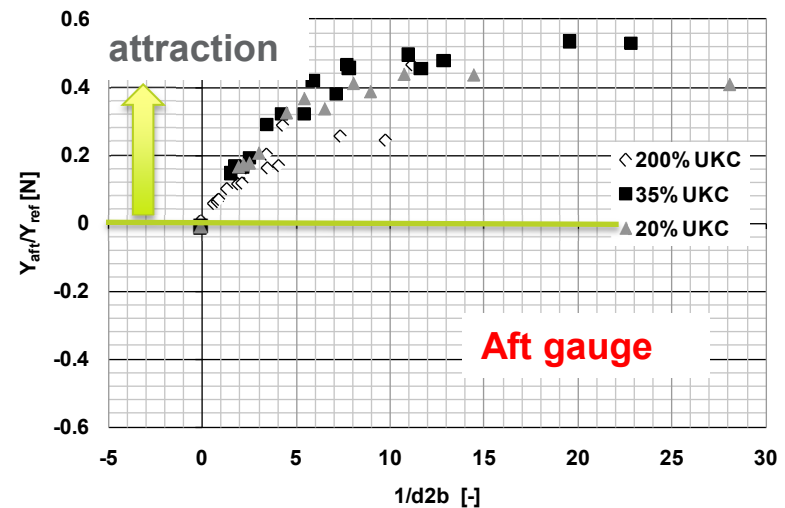
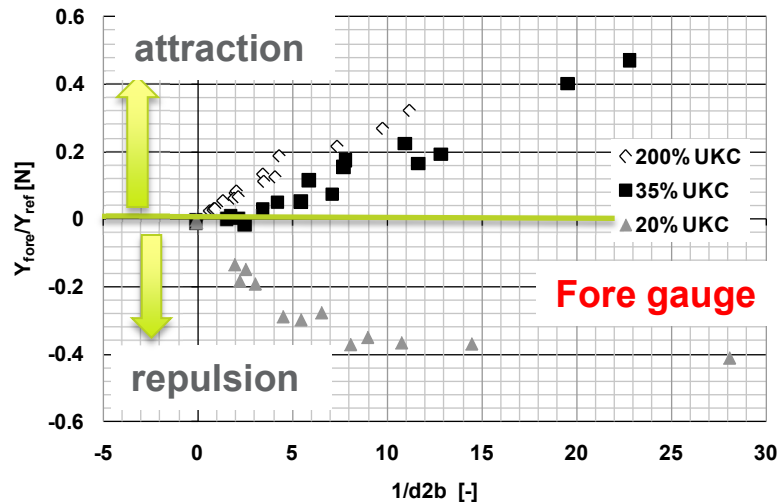
based on generalised model  
for maritime ships



## Example 2: inland navigation

### Validation

- Multimodal captive model tests
- Free-running model tests
- Full scale measurements during trial voyages
- Real-time simulation by a skipper on the inland simulator Lara



Lateral force due to bank effects at fore and aft gauges

## Summary

- Ship manoeuvrability decreases for UKC < 50% draft
- Complex hydrodynamic effects due to horizontal (bank, ship) and vertical (shallow water, nautical bottom) restrictions
- Knowledge based on different methodologies
  - **Experimental fluid dynamics (force – water flow)**
  - **Computational fluid dynamics (pressure – water flow)**
  - **Numerical methods**
- Co-operation