FAIL-SAFE CHART

1. FAIL-SAFE FUNCTION

- (a) When communication fails in any of the CAN bus lines (communication lines) due to a short circuit or any other causes, the fail-safe function, which is specified for each system, operates to prevent the system from malfunctioning.
- (b) This function operates for each system when communication is impossible. (For further details, see the pages for each system.)

Function	ECM	Skid Control ECU	Steering Angle Sensor	Yaw Rate Sensor	Action when unable to communicate	DTC detection (Driver detectable)
VSC Control (Controls VSC/TRAC engine output)	-	Rx	Тх	Tx	VSC function stops	Detectable (Light comes on)
VSC Control (Controls VSC/TRAC engine output)	Rx	Tx	-	-	VSC function stops	Detectable (Light comes on)

HINT:

- Rx: Reception from each ECU (sensor)
- Tx: Transmission to each ECU (sensor)



Skid Control ECU Communication Stop Mode

DESCRIPTION

Detection Item	Symptom	Trouble Area	
SKID CONTROL ECU COMMUNICATION STOP MODE	 ABS/VSC/TARC is not displayed on the "BUS CHECK" screen of the intelligent tester via the CAN VIM. DTCs are output from each ECU in skid control ECU communication stop mode as shown in the "DTC COMBINATION TABLE" (See page CA-7). 	 Power source or inside the skid control ECU Skid control ECU sub bus line or connector 	

WIRING DIAGRAM



CA

CA-21



REPLACE MASTER CYLINDER SOLENOID