## Topics in Graph Theory - Lecture Notes I (Tuesday)

## 1. Basics: Graphs and Spanning Trees

Notation: $G=(V, E)$ means that $G$ is a graph with vertices $V$ and edges $E$. Each edge $e$ has either one or two vertices as endpoints; an edge with only one endpoint (equivalently, two equal endpoints) is called a loop. Two edges $e, e^{\prime}$ are allowed to have the same pairs of endpoints; such edges are called parallel. Unless otherwise specified, all graphs are undirected - if the endpoints of $e$ are $v$ and $w$, we will write $e=v w=w v$. If $v$ and $w$ are adjacent (that is, they share at least one edge), then we'll write $v \sim w$.

I'll assume that everyone has seen graphs before, and is either familiar with, or can easily figure out, what such elementary concepts as "vertex", "edge", "connected", etc. mean. However, if you don't know what something means, you should ask immediately-I promise I won't bite, and chances are that you are not the only one!

Unless otherwise specified, all graphs are undirected - that is, each edge is an unordered pair of vertices. Parallel edges are OK, but we may as well assume that our graphs have no loops; you'll see why very soon.

Definition: A spanning tree of a connected graph $G$ is a connected, acyclic subgraph of $G$ that spans every vertex. (Note that "acyclic" implies that a spanning tree has no loops; this is why we can assume that $G$ is a loopless graph.)

For example, the complete graph $K_{5}$ on 5 vertices, which looks like this...

has exactly 125 spanning trees (as we'll see soon), three of which are the following:


Let's introduce the notation

$$
\begin{aligned}
\mathcal{T}(G) & :=\{\text { spanning trees of } G\} \\
\tau(G) & :=|\mathcal{T}(G)|
\end{aligned}
$$

Note that every spanning tree of $K_{5}$ has four edges. More generally, every spanning tree of $G=(V, E)$ has precisely $|V|-1$ edges. This gives us a stupid upper bound for $\tau(G)$, namely

$$
\tau(G) \leq\binom{|E|}{|V|-1}
$$

For example, $\tau\left(K_{5}\right) \leq\binom{ 10}{4}=210$. But we can do better. As it turns out, there are two nice ways to calculate $\tau(G)$ exactly.

## 2. Calculating $\tau(G)$ by Deletion-Contraction

Let $G=(V, E)$ be a connected graph and $e=v w \in E$. The deletion $G-e$ is just the graph $(V, E-\{e\})$. The contraction $G / e$ is obtained from $G-e$ by identifying $v$ and $w$ (or "fusing" the two vertices together). For contraction to make sense, we usually require that $e$ not be a loop. For example, if $G=K_{5}$ and $e=23$, then the deletion and contraction are as follows:


Proposition: Let $e \in E$. There are bijections

$$
\{T \in \mathcal{T}(G) \mid e \notin T\} \quad \longleftrightarrow \quad \mathcal{T}(G-e)
$$

and

$$
\{T \in \mathcal{T}(G) \mid e \in T\} \quad \longleftrightarrow \quad \mathcal{T}(G / e)
$$

That is, the spanning trees of $G$ that don't contain $e$ are in bijection with the spanning trees of the deletion $G-e$, and the spanning trees of $G$ that do contain $e$ are in bijection with the spanning trees of the contraction $G / e$.

It is pretty easy to check these bijections; I'll leave it as an exercise. Having done so, we have proven that

$$
\tau(G)=\tau(G-e)+\tau(G / e)
$$

for any graph $G$ and edge $e$. This gives an obvious algorithm to compute $\tau(G)$ for any graph; unfortunately, it is computationally inefficient to do so-the runtime of the algorithm is $O\left(2^{|E(G)|}\right)$. However, this type of deletion-contraction recurrence is theoretically very important; make a mental note of it!

## 3. The Kirchhoff Matrix-Tree Theorem

A less illuminating, but much more efficient way to calculate $\tau(G)$ uses linear algebra. Assume for the moment that $G$ has no loops - the loops are precisely the edges that belong to no spanning tree of $G$, so deleting all the loops does not change the value of $\tau(G)$. Also, label the vertices of $V=V(G)$ as $\left\{v_{1}, \ldots, v_{n}\right\}$.

Define the valence of a vertex $v \in V(G)$, denoted $\operatorname{val}(v)$ or $\operatorname{val}_{G}(v)$, to be the number of edges having $v$ as an endpoint ${ }^{1}$ Also, for two vertices $v_{i} \neq v_{j} \in V(G)$, let us write $\epsilon_{i j}$ for the number of edges joining $i$ and $j$. So $\epsilon_{i j} \in \mathbb{N}$; we are not requiring that $G$ be a simple graph, so $\epsilon_{i j} \geq 2$ is possible.

We now define the Laplacian matrix of $G$ to be the $n \times n$ matrix $L(G)$ given by

$$
[L(G)]_{i j}= \begin{cases}\operatorname{val}_{G}\left(v_{i}\right) & \text { if } i=j \\ -\epsilon_{i j} & \text { if } i \neq j\end{cases}
$$

Note that $\epsilon_{i j}=\epsilon_{j i}$, so $L(G)$ is a symmetric matrix. For example, if $G$ is the 4 -cycle with two adjacent edges doubled, that is,

then the Laplacian matrix is

$$
L(G)=\left[\begin{array}{cccc}
\operatorname{val}(1) & -\epsilon_{12} & -\epsilon_{13} & -\epsilon_{14} \\
-\epsilon_{21} & \operatorname{val}(2) & -\epsilon_{23} & -\epsilon_{24} \\
-\epsilon_{31} & -\epsilon_{32} & \operatorname{val}(3) & -\epsilon_{34} \\
-\epsilon_{41} & -\epsilon_{42} & -\epsilon_{43} & \operatorname{val}(4)
\end{array}\right]=\left[\begin{array}{rrrr}
4 & -2 & -2 & 0 \\
-2 & 3 & 0 & -1 \\
-2 & 0 & 3 & -1 \\
0 & -1 & -1 & 2
\end{array}\right]
$$

Notice that each row and column of $L(G)$ sums to zero, so it is certainly true that $\operatorname{det} L(G)=0$. However, something really neat happens with maximal square submatrixes:

Kirchhoff's Matrix-Tree Theorem: Let $v_{i} \in V(G)$, and let $\hat{L}(G)$ be the matrix obtained from $L(G)$ by deleting the row and column corresponding to $v_{i}$. Then

$$
\operatorname{det} \hat{L}(G)=\tau(G)
$$

Impressive, isn't it? There are several different ways to prove it; the way that I like the best is by deletioncontraction (because I can understand it). Of course, you need some linear algebra machinery - See the exercises.

There's actually a fancy version of the Matrix-Tree Theorem (at least for simple graphs; I haven't thought about how to extend it to arbitrary graphs but it ought to be possible) which we'll need later.

Souped-Up Matrix-Tree Theorem: Let $G$ be a simple graph with vertices $V=\left\{v_{1}, \ldots, v_{n}\right\}$. Introduce an indeterminate $\epsilon_{i j}$ for each edge $e=v_{i} v_{j}$, and define the $n \times n$ weighted Laplacian matrix of $G$, denoted $\mathbf{L}(G)$, by

$$
[\mathbf{L}(G)]_{i j}= \begin{cases}\sum_{v_{j} \sim v_{i}} \epsilon_{i j} & \text { if } i=j, \\ -\epsilon_{i j} & \text { if } i \neq j \text { and } i \sim j \\ 0 & \text { if } i \neq j \text { and } i \nsim j\end{cases}
$$

Choose a vertex $v_{i}$, and let $\hat{\mathbf{L}}(G)$ be the submatrix obtained by deleting the row and column corresponding to $v_{i}$. Then

$$
\operatorname{det} \hat{\mathbf{L}}(G)=\sum_{T \in \mathcal{T}(G)}\left(\prod_{e=v_{i} v_{j} \in T} \epsilon_{i j}\right) .
$$

[^0]That is, the determinant, which is clearly a polynomial in the variables $\epsilon_{i j}$, is in fact a sum of monomials corresponding to the spanning trees of $G$. Note that setting $\epsilon_{i j}=1$ recovers the original Matrix-Tree Theorem.

The Souped-Up Matrix-Tree Theorem is particularly useful when we replace the indeterminates $\epsilon_{i j}$ with "natural" weights on the edges-for instance, we might set $\epsilon_{i j}=x_{i} x_{j}$ to keep track of vertex valences.

## 4. Spanning Trees of $K_{n}$

Using the Matrix-Tree Theorem, one can prove the following remarkable formula (typically attributed to Cayley):

$$
\begin{equation*}
\tau\left(K_{n}\right)=n^{n-2} \tag{1}
\end{equation*}
$$

Using the Souped-Up Matrix-Tree Theorem, one can prove the following more general result. Define the weight of a spanning tree $T \subset E\left(K_{n}\right)$ to be the monomial

$$
\mathrm{wt}(T)=\prod_{i=1}^{n} x_{i}^{\mathrm{val}_{T}(i)}
$$

Then

$$
\begin{equation*}
\sum_{T \in \mathcal{T}\left(K_{n}\right)} \operatorname{wt}(T)=x_{1} x_{2} \cdots x_{n}\left(x_{1}+x_{2}+\cdots+x_{n}\right)^{n-2} \tag{2}
\end{equation*}
$$

Note that setting all of the $x_{i}$ 's to 1 recovers (1), which is why this result is more general.
There is a beautiful combinatorial proof of (2) called Prüfer coding. (There are other proof known, but this is the most popular!) The idea is to define a bijection

$$
P: \mathcal{T}\left(K_{n}\right) \rightarrow[n]^{n-2}
$$

by iteratively "pruning leaves" from a spanning tree $T$. Here $[n]$ means $\{1,2, \ldots, n\}$ (this is very standard notation in combinatorics), so $[n]^{n-2}$ denotes the set of $(n-2)$-tuples of members of $[n]$.

In general, a leaf of a graph is a vertex of valence 1. A tree with at least two vertices has at least two leaves (prove this!), so it makes sense to speak of the smallest leaf of a tree (with respect to the labeling of the vertices of $K_{n}$ by the elements of $[n]$ ). For example, consider the following spanning tree of $K_{8}$ :


The leaves are $2,3,4,7,8$, so the smallest leaf is 2 . To obtain the Prüfer code $P(T)$, we run the following algorithm:
(1) Let $i=1$.
(2) Let $x$ be the smallest leaf of $T$.
(3) Let $v_{i}$ be the "stem" (that is, the unique neighbor) of $x$.
(4) Replace $T$ with $T-v$ (that is, delete vertex $v$ and edge $v w$ ).
(5) If $i=n-2$, then STOP; otherwise, replace $i$ with $i+1$ and go to step 2 .

The Prüfer code $P(T)$ is then the sequence $\left(v_{1}, \ldots, v_{n-2}\right) \in[n]^{n-2}$.
For the tree $T$ shown above, we begin by deleting 2 , writing down the stem $v_{1}=6$, and replacing $T$ with the tree $T-2$ :


Now the leaves are $3,4,7,9$, so the smallest leaf is 3 . We write down the stem $v_{2}=5$ and delete vertex 3 , obtaining the tree


And so on. Ultimately, we obtain the Prüfer code

$$
P(T)=(6,5,1,9,5,6,6) \in[9]^{7}
$$

That the function $P$ is a bijection is left an exercise to the reader (mwahahaha). It's not that hard; you essentially have to figure out how to run the algorithm in reverse.

Now here's something interesting. For each vertex $v_{i}$, Compare the valence val ${ }_{T}\left(v_{i}\right)$ with the number of times that $v_{i}$ appears in the Prüfer code $P(T)$ :

| Vertex | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Valence in $T$ | 2 | 1 | 1 | 1 | 3 | 4 | 1 | 1 | 2 |
| \# occurrences in $P(T)$ | 1 | 0 | 0 | 0 | 2 | 3 | 0 | 0 | 1 |

It certainly looks like

$$
\text { the number of occurrences of } v_{i} \text { in } P(T) \text { is } \operatorname{val}_{T}\left(v_{i}\right)-1
$$

This makes perfect sense - if $v_{i}$ starts life as a leaf, then $v_{i}$ can never be the stem of any other vertex and hence cannot appear at all in $P(T)$. On the other hand, if $v_{i}$ has more than one neighbor, then it does not become a leaf until exactly $\operatorname{val}_{T}\left(v_{i}\right)-1$ of the neighbors of $v_{i}$ have been killed off, and each such off-killing accounts for one instance of $v_{i}$ in $P(T)$.

This observation leads to a purely combinatorial (as opposed to linear-algebraic) proof of the weighted version (2) of Cayley's formula:

$$
\begin{aligned}
\sum_{T \in \mathcal{T}\left(K_{n}\right)} \mathrm{wt}(T) & =\sum_{P=\left(v_{1}, \ldots, v_{n}\right) \in[n]^{n-2}} \prod_{i=1}^{n} x_{i}^{1+(\text { number of occurrences of } i \text { in } P)} \\
& =x_{1} \cdots x_{n} \sum_{P=\left(v_{1}, \ldots, v_{n}\right) \in[n]^{n-2}} \prod_{i=1}^{n} x_{i}^{(\text {number of occurrences of } i \text { in } P)} \\
& =x_{1} \cdots x_{n}\left(x_{1}+\cdots+x_{n}\right)^{n-2} .
\end{aligned}
$$

## 5. Spanning Trees of $Q_{n}$

The n-cube $Q_{n}$ is the graph whose vertices are the bit strings of length $n$, with two vertices joined by an edge if and only if they differ in exactly one bit. Thus $\left|V\left(Q_{n}\right)\right|=2^{n}$ and $\left|E\left(Q_{n}\right)\right|=n \cdot 2^{n-1}$ (check this!) For instance, the graph $Q_{3}$ is as follows:


A side note: A really cool way to draw the graph $Q_{4}$ is as follows. First, draw a $7 \times 7$ chessboard. Put a dot in the middle square of the top and bottom rows. Now, draw in all the ways to connect the two squares by a sequence of four knight's moves. Amazing.

Using the Matrix-Tree Theorem, one can prove the following surprising formula:

$$
\begin{equation*}
\tau\left(Q_{n}\right)=\prod_{\substack{S \subset[n] \\|S| \geq 2}} 2|S|=\prod_{k=2}^{n}(2 k)^{\binom{n}{k}} \tag{3}
\end{equation*}
$$

Again, there is a weighted version of this fact, which appears in a paper I coauthored 2]. Define the direction of an edge $e \in E\left(Q_{n}\right)$ to be the unique bit in which its endpoints differ; this is a number $\operatorname{dir}(e) \in[n]$.

Theorem: Introduce indeterminates $q_{1}, \ldots, q_{n}$. For a spanning tree $T \in \mathcal{T}\left(Q_{n}\right)$, define

$$
\mathrm{wt}(T)=\prod_{e \in T} q_{\operatorname{dir}(e)}=\prod_{i=1}^{n} q_{i}^{\text {number of edges of direction } i \text { in } T} .
$$

Then

$$
\begin{equation*}
\sum_{T \in \mathcal{T}\left(Q_{n}\right)} \operatorname{wt}(T)=q_{1} \ldots q_{n} \prod_{\substack{S \subset[n] \\|S| \geq 2}}\left(2 \sum_{i \in S} q_{i}\right)=\sum_{T \in \mathcal{T}\left(Q_{n}\right)} \mathrm{wt}(T)=2^{2^{n}-n-1} q_{1} \ldots q_{n} \prod_{\substack{S \subset[n] \\|S| \geq 2}}\left(\sum_{i \in S} q_{i}\right) \tag{4}
\end{equation*}
$$

The factor $q_{1} \ldots q_{n}$ can be explained pretty easily: as pointed out in class, every $T \in \mathcal{T}\left(Q_{n}\right)$ must use at least one edge from each of the $n$ possible directions. (For instance, if $T \in \mathcal{T}\left(Q_{3}\right)$ contains no edge in direction 2, then there is no way to get from 001 to 011 using only edges of $T$.)

Setting all of the $q_{i}$ 's to 1 specializes (4) to (3). As we shall soon see, even (4) can be strengthened. However, according to the "Bible of Combinatorics" [3], no bijective proof is known. Your job is to find a proof!

UPDATE: In 2012, Olivier Bernardi found a beautiful combinatorial proof of (4) (among other formulas). See [1].

## References

[1] Olivier Bernardi, On the spanning trees of the hypercube and other products of graphs, Electronic J. Combin. 19, no. 4 (2012), Paper P51. [Link to published version]
[2] Jeremy L. Martin and Victor Reiner, Factorizations of some weighted spanning tree enumerators, J. Comb. Theory Ser. A 104, no. 2 (2003), pp. 287-300. [Hyperlink to arXiv version]
[3] R.P. Stanley, Enumerative Combinatorics, Volume II. Cambridge Studies in Advanced Mathematics 62. Cambridge University, 1999.


[^0]:    ${ }^{1}$ This is usually called "degree", but I prefer "valence" because "degree" already has far too many meanings in mathematics. In chemistry, the valence of an atom in a molecule is (essentially) the number of bonds it forms, so it seems an appropriate term to use here.

