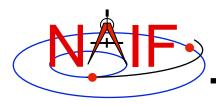


Navigation and Ancillary Information Facility

SPICE Geometry Finder (GF) Subsystem

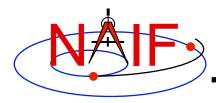
Searching for times when specified geometric conditions occur

April 2016



Topics

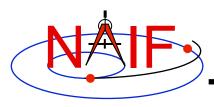
- GF Subsystem Overview
- SPICE Windows
- GF Search Examples
- Geometric Search Types and Constraints
- More Details
 - Root finding, including step size
 - Workspace
- An Example



Navigation and Ancillary Information Facility

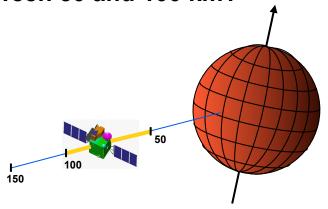
GF Subsystem Overview

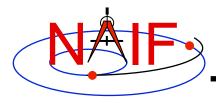
Geometry Finder Subsystem



Purpose

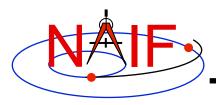
- Much SPICE software computes a geometry parameter at a given time, t, i.e. x = f(t).
 - Example: on 2011 MAR 30 14:57:08, what is the spacecraft's altitude above Mars?
- The Geometry Finder subsystem does the inverse: it finds times when specified geometric events occur.
 - Example: within some time bounds, when is the spacecraft's altitude between 50 and 100 km?





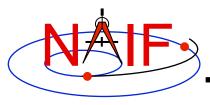
Some Examples

- The SPICE Geometry Finder (GF) subsystem can find times when:
 - Mars Express distance from Mars is at a local minimum (periapse)
 - Elevation of the Cassini orbiter is above a given threshold angle as seen from DSS-14
 - Titan is completely occulted by Saturn
 - The Mars Reconnaissance Orbiter is in the penumbral shadow of Mars
 - The Saturn phase angle as seen by the Cassini orbiter is 60 degrees



Types of GF APIs

- GF provides two primary types of event-finding APIs
 - Boolean: a geometric condition (an event) is true or false
 - » Example: Phobos is occulted by Mars
 - » Example: Vesta is not in the OSIRIS instrument's field of view
 - We also call these binary conditions
 - Numeric: a geometric quantity has a given value, is within a given range or has achieved a local or global maximum or minimum
 - » Example: spacecraft altitude is between X and Y km above the surface
 - » Example: angular separation of Titan from Saturn has reached the maximum (within the search window being used)



GF High-Level API Computations

Navigation and Ancillary Information Facility

The current GF subsystem allows one to search for events involving the geometric quantities listed below.

Boolean

Occultations or transits

Ray containment in an instrument's field of view

Target body appears in an instrument's field of view

User-defined Boolean quantity

Numeric

Observer-target distance

Observer-target range rate

Target body angular separation

Phase angle

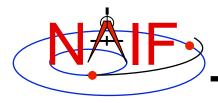
Illumination angles

Ray-body surface intercept coordinates

Position vector coordinates

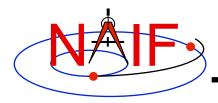
Sub-observer point coordinates

User-defined scalar quantity



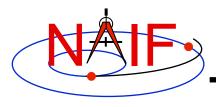
GF High-Level API Routines

- The GF subsystem provides the following high-level API routines; these search for events involving the respective geometric quantities listed below
 - GFDIST: observer-target distance
 - GFILUM: illumination angles
 - GFOCLT: occultations or transits
 - GFPA: phase angle
 - GFPOSC: position vector coordinates
 - GFRFOV: ray is contained in an instrument's field of view
 - GFRR: observer-target range rate
 - GFSEP: target body angular separation
 - GFSNTC: ray-body surface intercept coordinates
 - GFSUBC: sub-observer point coordinates
 - GFTFOV: target body appears in an instrument's field of view
 - GFUDB: user-defined Boolean quantity (only Fortran and C)
 - GFUDS: user-defined scalar quantity (only Fortran and C)



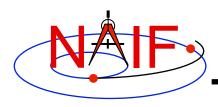
The SPICE Window

- GF uses a SPICE window to constrain the time period over which to conduct a search. (This is called the confinement window.)
- GF also uses SPICE windows to specify intervals of time when some set of user constraints are satisfied.
 - The high-level GF routines return search results as SPICE windows.
- A SPICE window is a list of disjoint intervals arranged in ascending order.
- In simple terms, one can describe a SPICE time window as:
 - a time-ordered sequence of zero or more time intervals, each having zero or non-zero length
 - an interval is specified by a pair of double precision numbers, with the second greater than or equal to the first
 - a zero-length interval is often called a "singleton," wherein the start and end times are identical



SPICE Windows Operations

- SPICE provides routines to:
 - compute unions, intersections, and differences of windows
 - contract each interval within a window ...
 - » by increasing the left endpoint and decreasing the right endpoint
- See the next page for an example

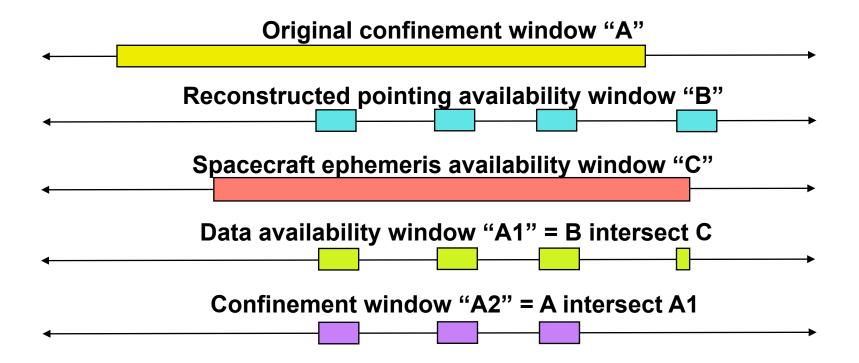


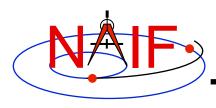
Example of Window Operations

Navigation and Ancillary Information Facility

Given an initial confinement window, restrict that window to times when required CK and SPK data are available.

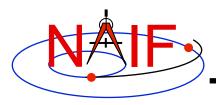
Use CKCOV and SPKCOV to find CK and SPK availability windows. Contract CK window slightly to avoid round-off problems. Contract SPK window by a few seconds if discrete differentiation is used by search algorithms (e.g. for acceleration or for "is function decreasing?" tests).





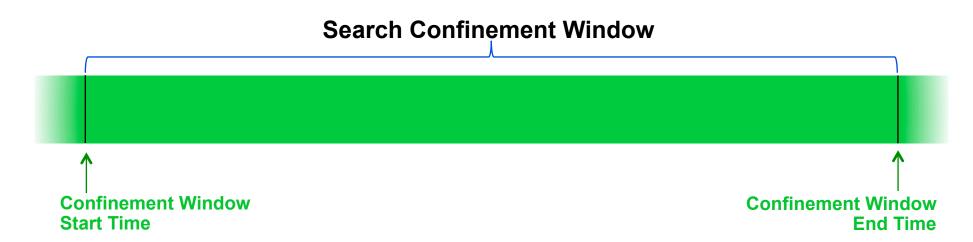
Using Time Windows in GF

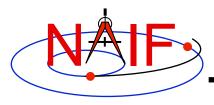




Using Time Windows in GF

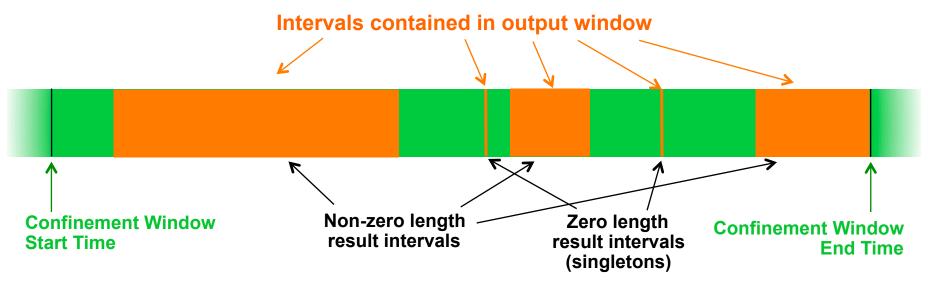
- GF uses a SPICE window to:
 - confine the time bounds over which a search is to take place





Using Time Windows in GF

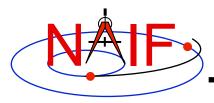
- GF uses SPICE windows for input and output
 - Input: confine the time bounds over which a search is to take place
 - Output: contain the time intervals that meet the search criteria
 - » There may be none, one or multiple result intervals
 - » The result intervals can be of non-zero or zero length
 - A zero-length interval is simply an epoch—an instant in time





Cascading Search Using Multiple SPICE Windows

- The result window from one search can be used as the confinement window for another.
 - This is often a convenient and efficient way of performing searches for times when multiple constraints are met.
 - This technique can be used to accelerate searches in cases where a fast search can be performed to produce a small confinement window for a second, slower search.
 - » See the next chart and the example program "CASCADE" in the Geometry Finder Required Reading document.



Cascading Search Example

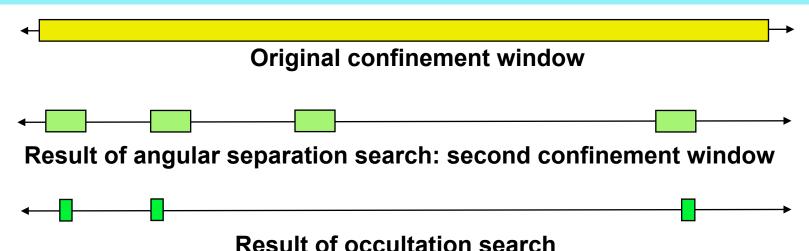
Navigation and Ancillary Information Facility

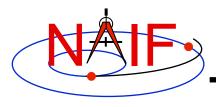
Example: accelerate a solar occultation search.

First search for times when the angular separation of the figures of the Sun and Moon, as seen from DSS-14, is less than 3 degrees.

Use the result window of the angular separation search as the confinement window of an occultation search.

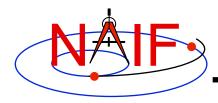
Because the angular separation search is much faster than the occultation search (on the original confinement window), the total search time is greatly reduced. See the Geometry Finder Required Reading for a detailed discussion.





GF Documentation

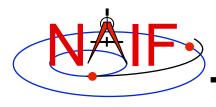
- The GF module headers contain complete example programs for each GF API routine
- The GF Required Reading document (gf.req) contains lots of details
- Documentation on SPICE windows:
 - The WINDOWS Required Reading windows.req
 - The Other Functions tutorial
 - API documentation for SPICE window routines



Navigation and Ancillary Information Facility

GF Search Examples

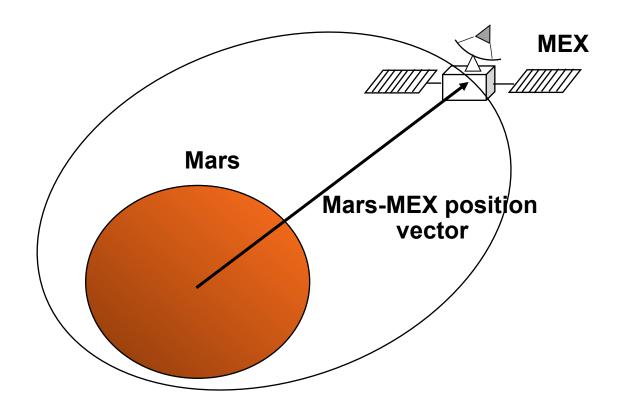
Geometry Finder Subsystem



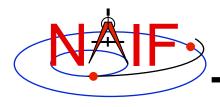
Distance Local Extremum Search

Navigation and Ancillary Information Facility

Find the time of apoapse of the Mars Express Orbiter (MEX)



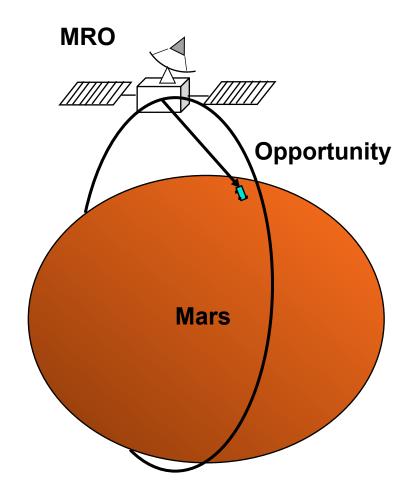
API: GFDIST



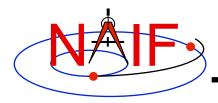
Distance Inequality Search

Navigation and Ancillary Information Facility

Find the time period when the Mars Reconnaissance Orbiter (MRO) is within 500km of the Opportunity rover.



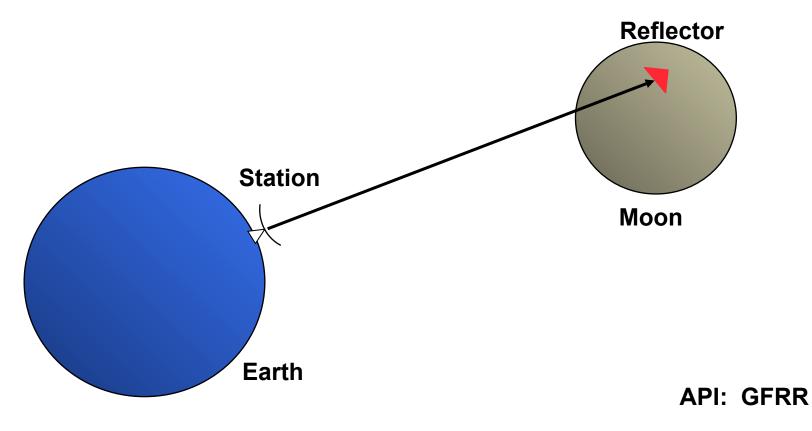
API: GFDIST

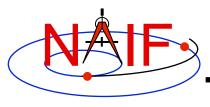


Range Rate Extremum Search

Navigation and Ancillary Information Facility

Find the times when the range rate of a lunar reflector, as seen by an Earth station, attains an absolute extremum.

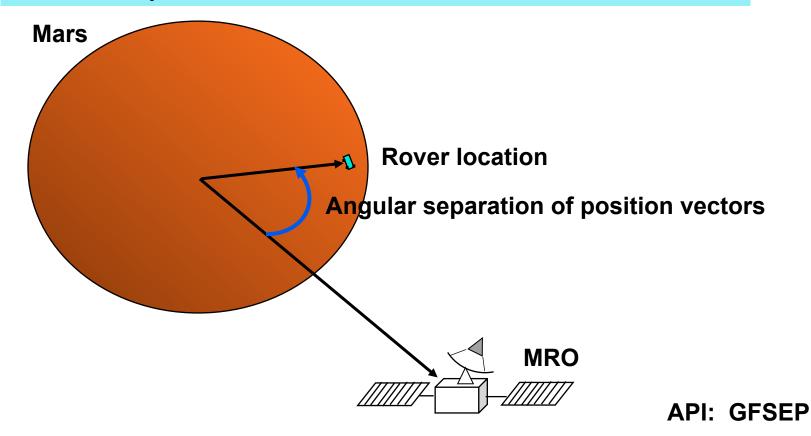




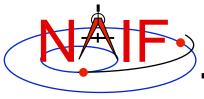
Angular Separation Inequality Search -1

Navigation and Ancillary Information Facility

Find the time period when the angular separation of the Mars-to-Mars Reconnaissance Orbiter (MRO) and Mars-to-Opportunity Rover position vectors is less than 3 degrees. Both targets are modeled as points.



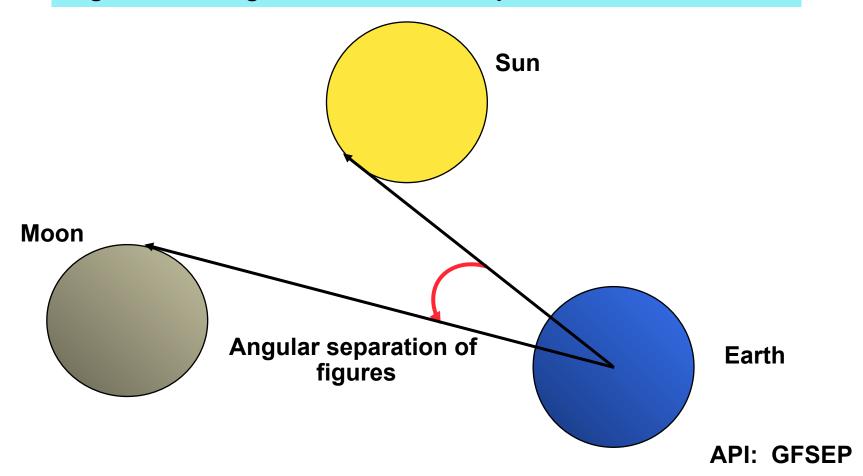
Geometry Finder Subsystem

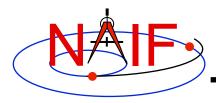


Angular Separation Inequality Search -2

Navigation and Ancillary Information Facility

Find the time period when the angular separation of the figures of the Moon and Sun, as seen from the Earth, is less than 1 degree. Both targets are modeled as spheres.

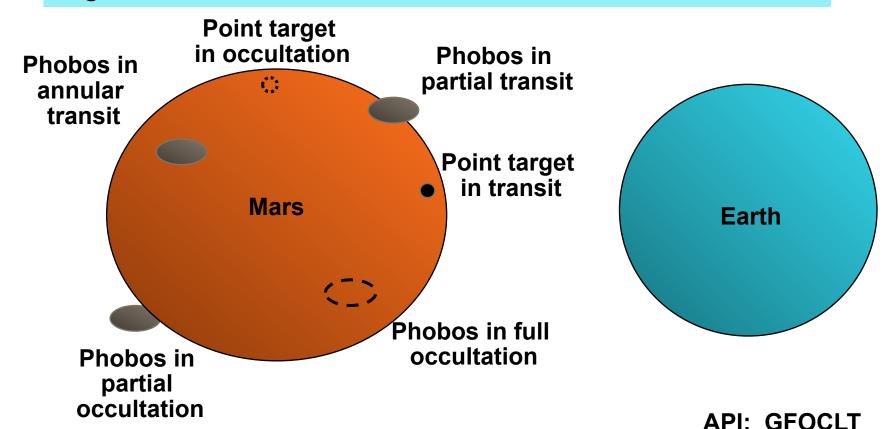


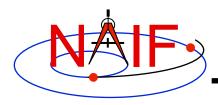


Occultation/Transit Search

Navigation and Ancillary Information Facility

Find the ingress and egress times of an occultation of Phobos or a spacecraft by Mars, as seen from Earth. Phobos and Mars are modeled as triaxial ellipsoids; a spacecraft is modeled as a point target.

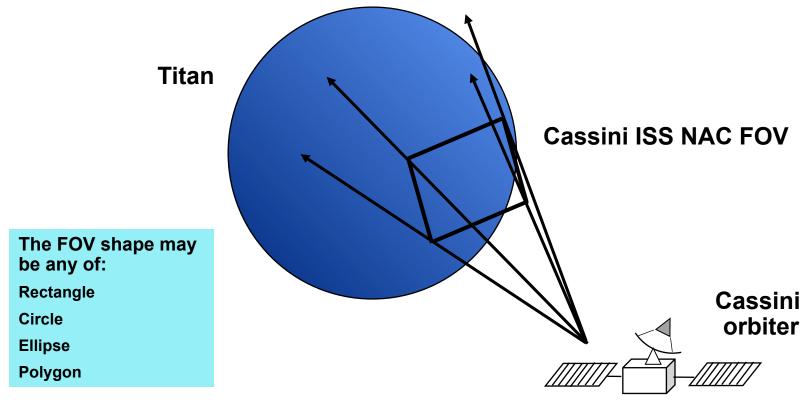




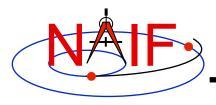
Target in FOV Search

Navigation and Ancillary Information Facility

Find the time period when Titan appears in the FOV of the Cassini ISS Narrow Angle Camera (NAC). The target is an ephemeris object; the target shape is modeled as an ellipsoid. (Point targets are also supported.)



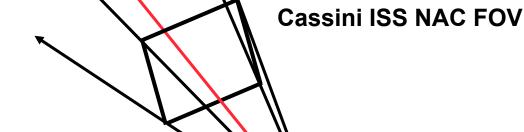
API: GFTFOV



Ray in FOV Search

Navigation and Ancillary Information Facility

Find the time period when the star having Hipparcos catalog number 6000 appears in the FOV of the Cassini ISS Narrow Angle Camera (NAC). The target direction is modeled as a ray, optionally corrected for stellar aberration.



The FOV shape may be any of:

Rectangle

Circle

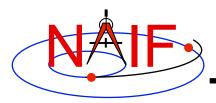
Ellipse

Polygon

orbiter

Cassini

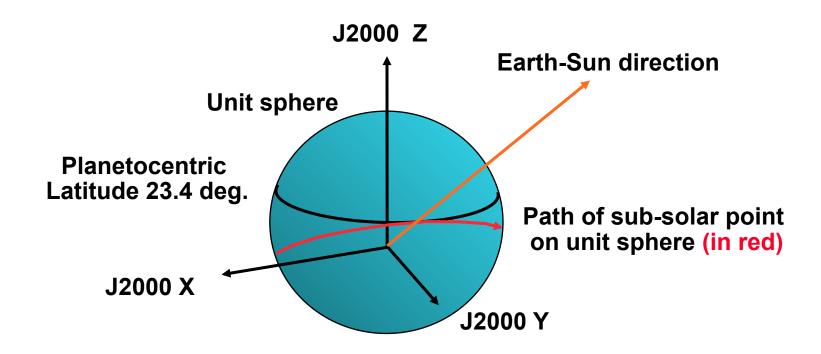
API: GFRFOV



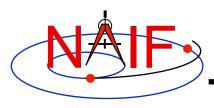
Position Coordinate Local Extremum Search

Navigation and Ancillary Information Facility

Find the time(s) at which the planetocentric latitude of the Earth-Sun vector, expressed in the J2000 frame, is at a local maximum.



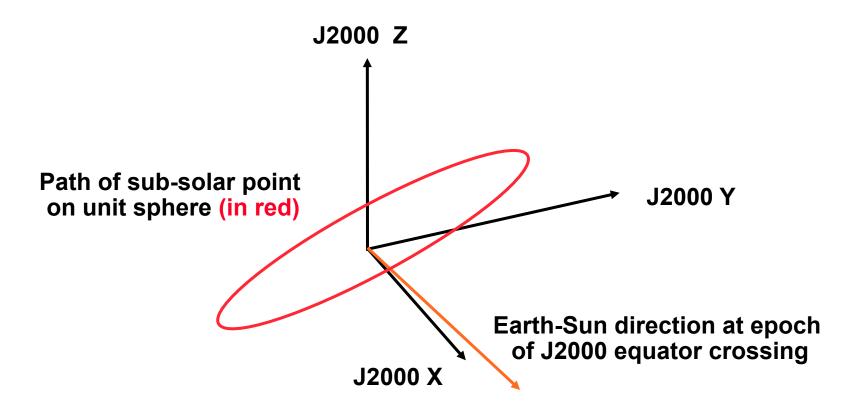
API: GFPOSC



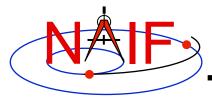
Position Coordinate Equality Search

Navigation and Ancillary Information Facility

Find the time(s) at which the Z component of the Earth-Sun vector, expressed in the J2000 frame, is 0.



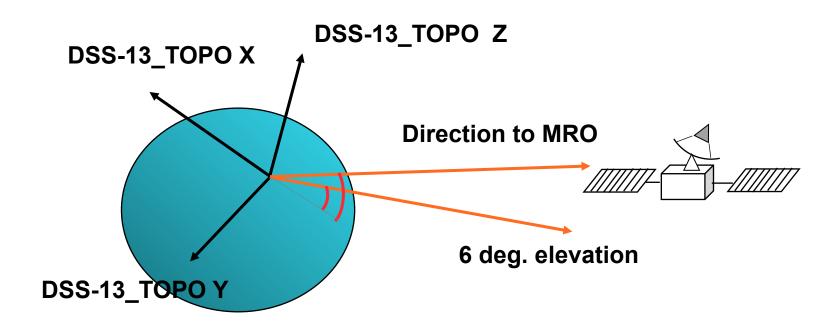
API: GFPOSC



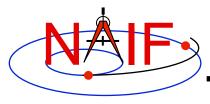
Position Coordinate Inequality Search -1

Navigation and Ancillary Information Facility

Find the time period when the elevation of the DSS-13 to Mars Reconnaissance Orbiter (MRO) spacecraft vector, expressed in the DSS-13 topocentric frame, is greater than 6 degrees.



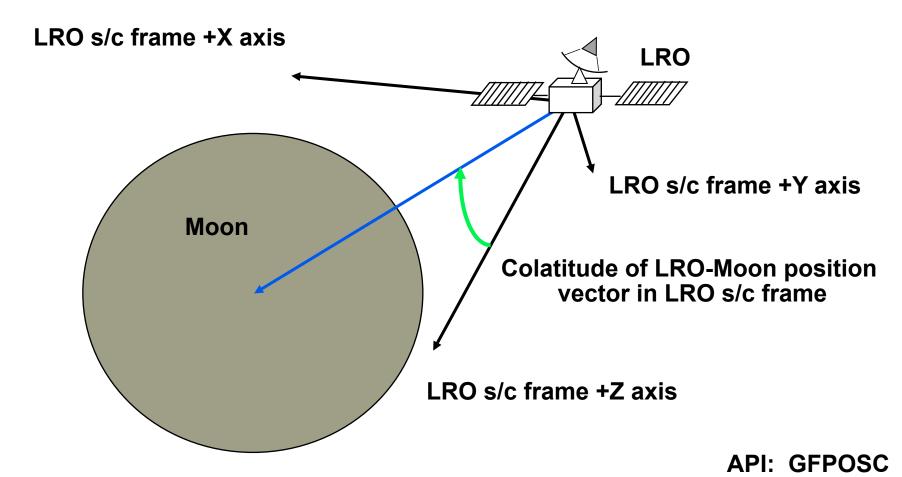
API: GFPOSC

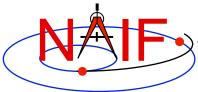


Position Coordinate Inequality Search -2

Navigation and Ancillary Information Facility

Find the time period when the Lunar Reconnaissance Orbiter's (LRO) off-nadir angle exceeds 5 degrees.

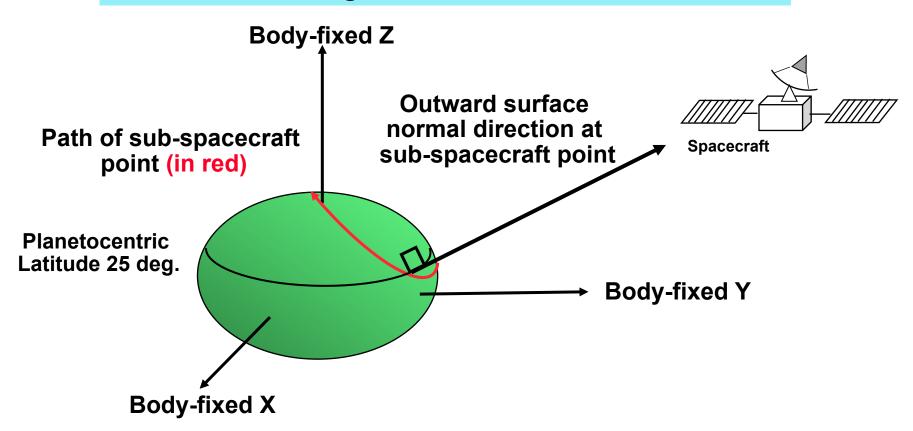




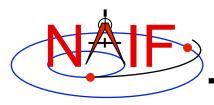
Sub-Observer Point Coordinate Equality Search

Navigation and Ancillary Information Facility

Find the time at which the planetocentric latitude of the sub-spacecraft point, using the "near point" definition, is 25 degrees.



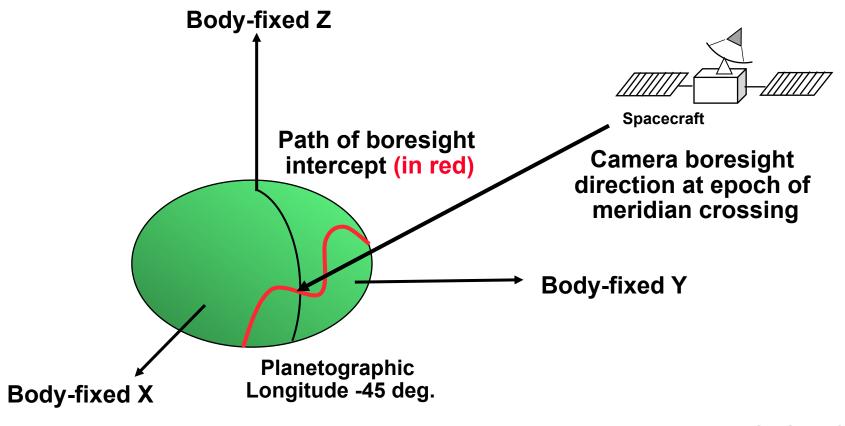
API: GFSUBC



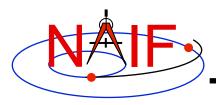
Surface Intercept Coordinate Equality Search

Navigation and Ancillary Information Facility

Find the time at which the planetographic longitude of a given camera boresight surface intercept is -45 degrees.



API: GFSNTC

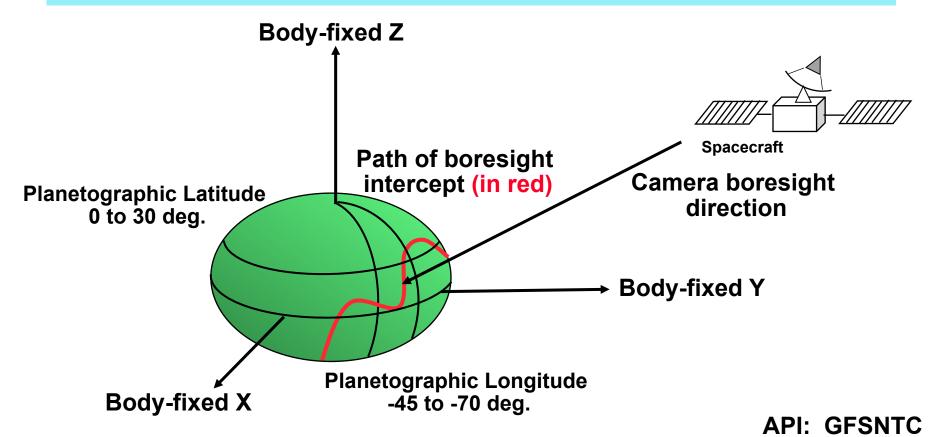


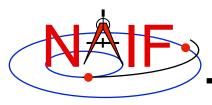
Surface Intercept "Box" Search

Navigation and Ancillary Information Facility

Find the time period when the planetographic longitude of a given camera boresight surface intercept is between -70 and -45 degrees, and the intercept latitude is between 0 and 30 degrees.

The solution requires four (cascading) inequality searches.



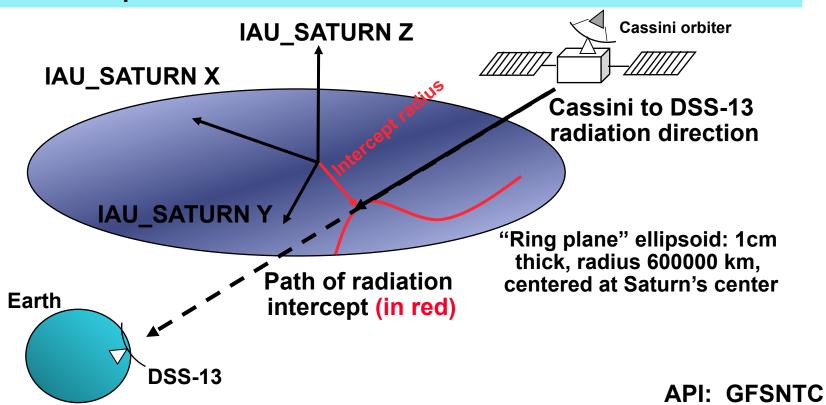


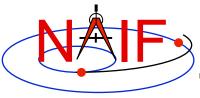
Surface Intercept Coordinate Equality Search

Navigation and Ancillary Information Facility

Find the time at which the ring plane intercept of the Cassini to DSS-13 vector, corrected for transmission light time (stellar aberration correction is unnecessary), has radius 300000km.

The solution requires a dynamic frame for which one axis points along the radiation path.

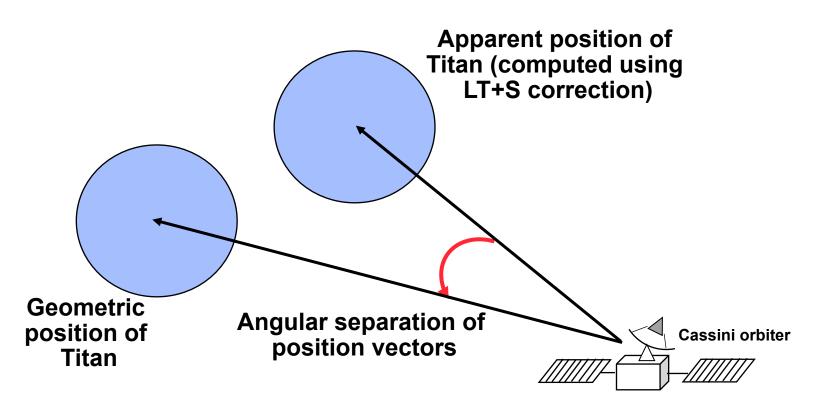




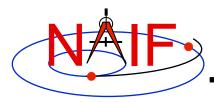
Suser-Defined Quantity Extremum Search

Navigation and Ancillary Information Facility

Find the time period when the angular separation of the geometric and apparent positions of Titan as seen from the Cassini orbiter attains an absolute maximum.



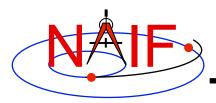
API: GFUDS



Navigation and Ancillary Information Facility

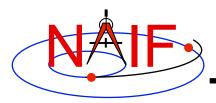
Geometric Search Types and Constraints

Geometry Finder Subsystem 36



Types of Geometric Quantities

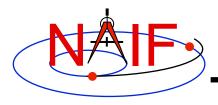
- The GF subsystem deals with two types of geometric quantities:
 - "Binary state functions": functions of time that can be "true" or "false." Examples:
 - » Occultation state, such as: "Titan is fully occulted by Saturn at time t"
 - » Visibility state: A target body or object modeled as a ray (for example, a star) is visible in a specified instrument FOV at time t
 - Scalar numeric functions of time, for example
 - » Observer-target distance
 - » Latitude or longitude of an observer-target vector, subspacecraft point, or ray-surface intercept point
 - » Angular separation of two target bodies as seen by an observer



Binary State Searches

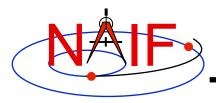
Navigation and Ancillary Information Facility

- Binary state searches find times when a specified binary state function takes the value "true."
 - SPICE window arithmetic can be used to find the times when a binary state function is "false."



Numeric Searches

- Numeric searches find times when a scalar numeric quantity satisfies a mathematical constraint. The supported constraints are:
 - The function
 - » equals a specified reference value.
 - » is less than a specified reference value.
 - » is greater than a specified reference value.
 - » is at a local maximum.
 - » is at a local minimum.
 - » is at an absolute maximum.
 - » is at an absolute minimum.
 - » is at an "adjusted" absolute maximum: the function is within a given tolerance of the absolute maximum.
 - » is at an "adjusted" absolute minimum: the function is within a given tolerance of the absolute minimum.
- Examples for a Distance search follow.



Solve Distance Equality

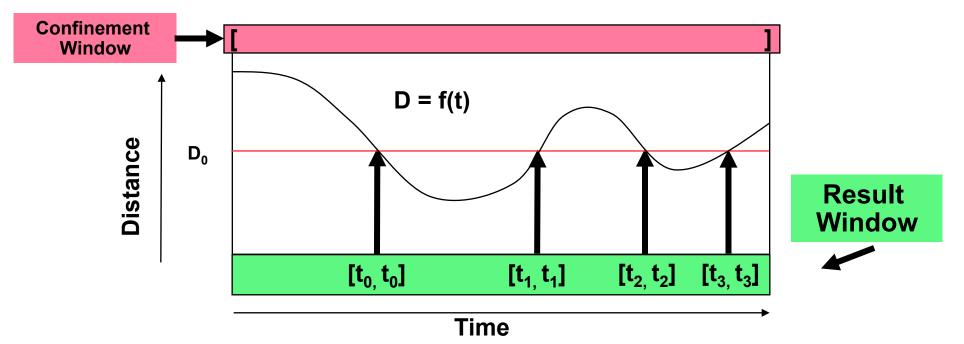
Navigation and Ancillary Information Facility

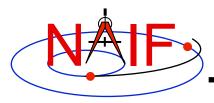
Find time window during which Distance = D_0 GF API input arguments defining constraint:

RELATE = '='

ADJUST = 0.D0

REFVAL = DO





Solve Distance < Inequality

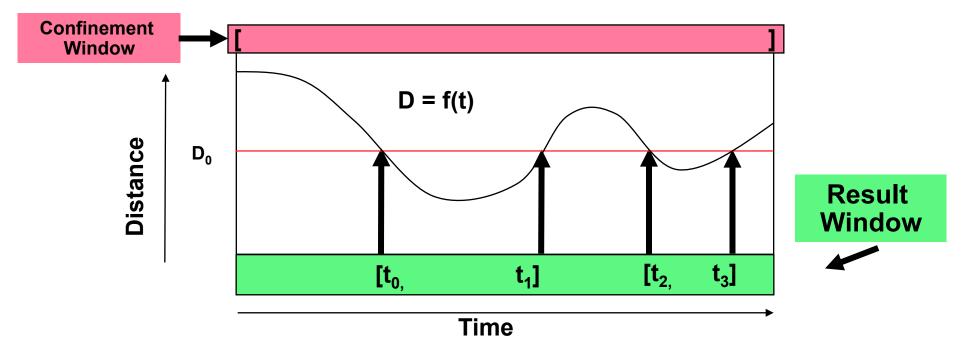
Navigation and Ancillary Information Facility

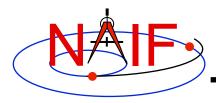
Find time window during which Distance $< D_0$ GF API input arguments defining constraint:

RELATE = '<'

ADJUST = 0.D0

REFVAL = DO





Solve Distance > Inequality

Navigation and Ancillary Information Facility

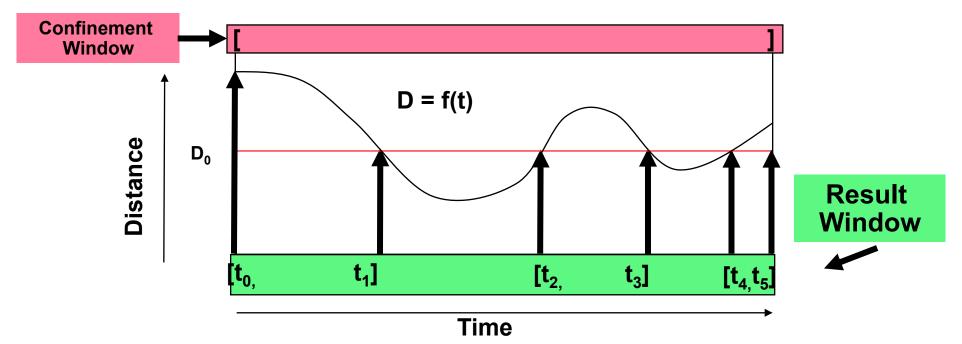
Find time window during which Distance > D₀

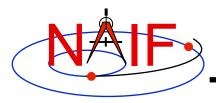
GF API input arguments defining constraint:

RELATE = '>'

ADJUST = 0.D0

REFVAL = DO





Find Local Minima

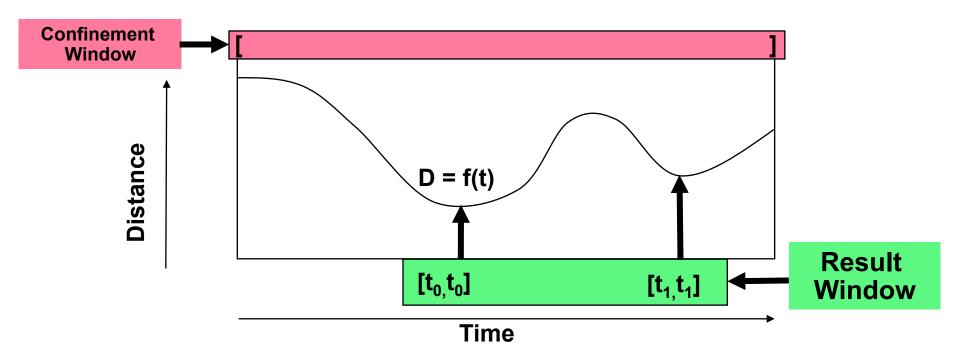
Navigation and Ancillary Information Facility

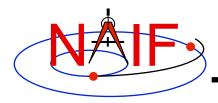
Find time window during which Distance is a local minimum.

GF API input arguments defining constraint:

RELATE = 'LOCMIN'

ADJUST = 0.D0 (REFVAL is not used in this case





Find Local Maxima

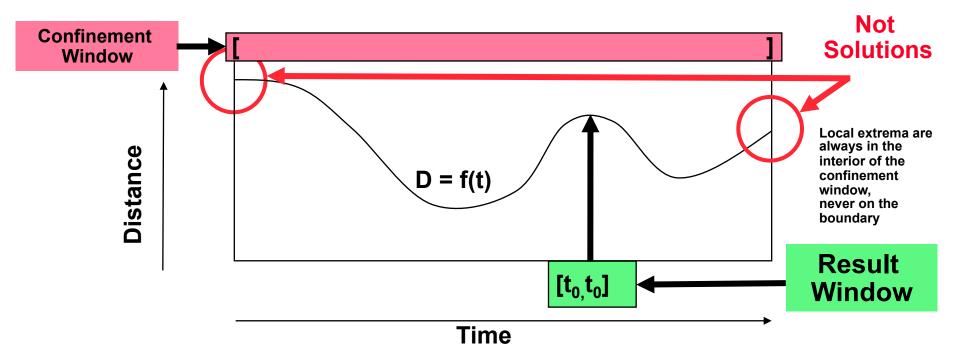
Navigation and Ancillary Information Facility

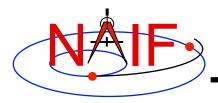
Find time window during which Distance is a local maximum.

GF API input arguments defining constraint:

RELATE = 'LOCMAX'

ADJUST = 0.D0 (REFVAL is not used in this case





Find Absolute Minimum

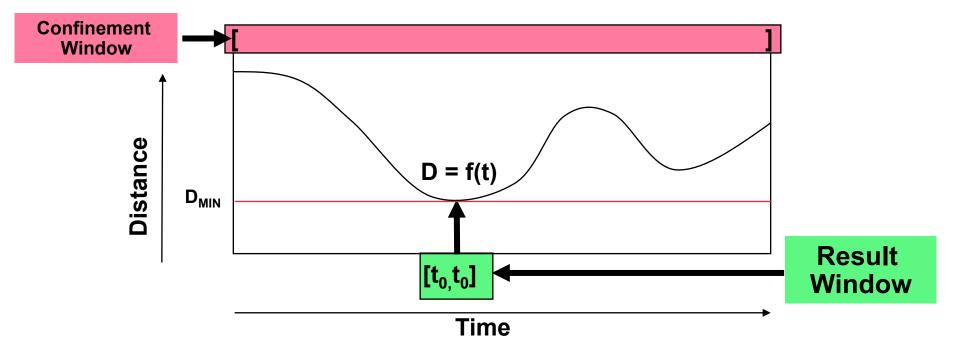
Navigation and Ancillary Information Facility

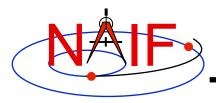
Find the time at which Distance is an absolute minimum.

GF API input arguments defining constraint:

RELATE = 'ABSMIN'

ADJUST = 0.D0 (REFVAL is not used in this case





Find Absolute Maximum

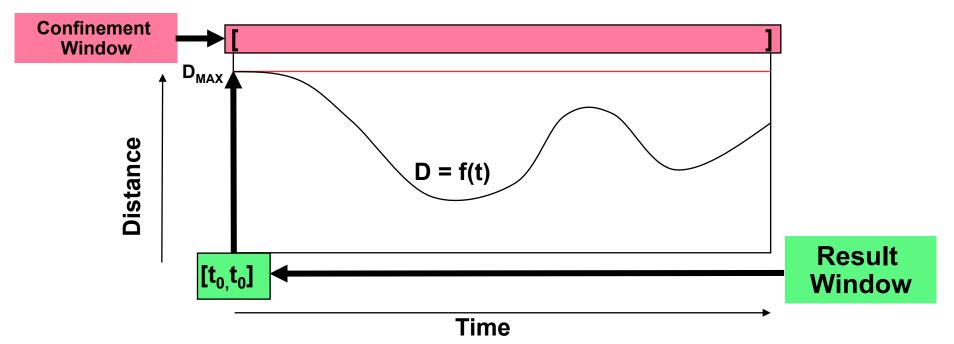
Navigation and Ancillary Information Facility

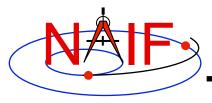
Find the time at which Distance is an absolute maximum.

GF API input arguments defining constraint:

RELATE = 'ABSMAX'

ADJUST = 0.D0 (REFVAL is not used in this case





Find Adjusted Absolute Minimum

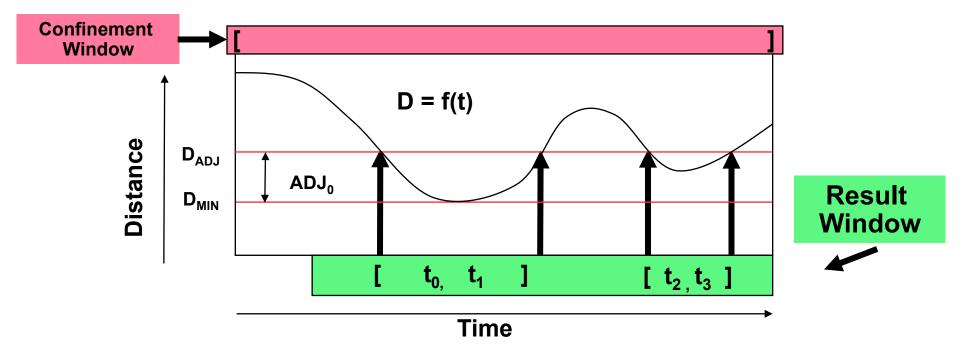
Navigation and Ancillary Information Facility

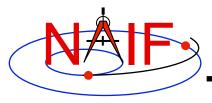
Find time window during which Distance $< D_{ADJ} = D_{MIN} + ADJ_0$ GF API input arguments defining constraint:

RELATE = 'ABSMIN'

 $ADJUST = ADJO \quad (ADJ0 > 0)$

REFVAL = 0.D0 (REFVAL is not used in this case but should be initialized for portability)





Find Adjusted Absolute Maximum

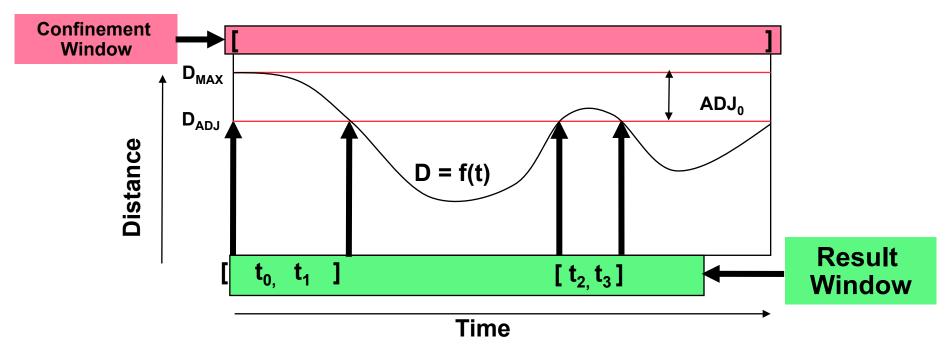
Navigation and Ancillary Information Facility

Find time window during which Distance > $D_{ADJ} = D_{MAX} - ADJ_0$ GF API input arguments defining constraint:

RELATE = 'ABSMAX'

 $ADJUST = ADJO \quad (ADJ0 > 0)$

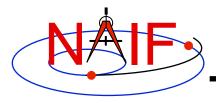
REFVAL = 0.D0 (REFVAL is not used in this case but should be initialized for portability)



Navigation and Ancillary Information Facility

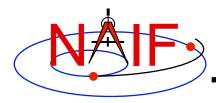
More Details

- GF mid-level APIs
- Root Finding, including step size selection
- Workspace
- API Example: GFDIST



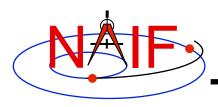
GF Mid-Level API Routines

- The current Fortran and C SPICE Toolkits provide some mid-level APIs that provide additional capabilities:
 - Progress reporting, which can be customized by the user
 - Interrupt handling which can be customized by the user
 - » In Fortran, no default interrupt detection is available
 - User-customizable search step and refinement routines
 - User-adjustable root finding convergence tolerance
- The GF mid-level search API routines are:
 - GFEVNT: All scalar numeric quantity searches
 - GFFOVE: Target or ray in FOV searches
 - GFOCCE: Occultation searches



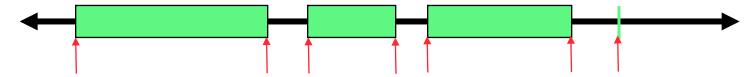
Navigation and Ancillary Information Facility

Root Finding

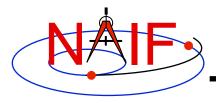


Root Finding

- To produce a final or intermediate result window, the GF subsystem must accurately locate the endpoints of the window's intervals. These endpoints are called "roots."
 - The green regions below (rectangles and vertical line segment) represent intervals of a window.
 - Roots are indicated by the red, vertical arrows.



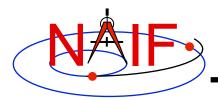
- Elsewhere, "root finding" often refers to solving f(x) = 0.
- In the GF setting, roots are boundaries of time intervals over which a specified constraint is met.
 - Roots can be times when a binary state function changes values.
- Most popular root finding methods, e.g. Newton, secant, bisection, require the user to first "bracket" a root: that is, determine two abscissa values such that a single root is located between those values.
- The GF subsystem solves a more difficult problem: it performs a global search for roots. That is, given correct inputs, it finds all roots within a user-specified confinement window.
 - The user is not asked to bracket the roots.



Step Size Selection

Navigation and Ancillary Information Facility

- The GF subsystem asks the user to specify a time step (often called the "step size") that will be used to bracket roots.
 - For binary state searches, the step size is used to bracket the endpoints of the intervals of the result window.
 - » The step size must be shorter than any event of interest, and shorter than any interval between events that are to be distinguished.
 - For numeric searches, the step size is used to bracket the endpoints of the intervals of the window on which the geometric quantity is monotonically decreasing.
 - » The step size must be shorter than any interval on which the function is monotonically increasing or decreasing.
 - In both cases, the step size must be large enough so the search completes in a reasonable amount of time.



Monotone Windows -1

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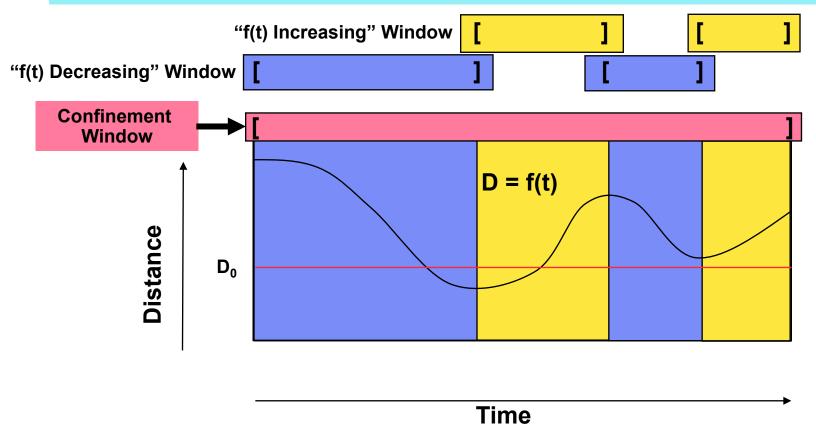
Example: monotone windows for a distance function

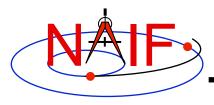
Note that:

Extrema occur only at window interval boundaries.

Each window interval contains at most one root of an equality condition.

Within each window interval, the solution of an inequality is a single (possibly empty) interval.



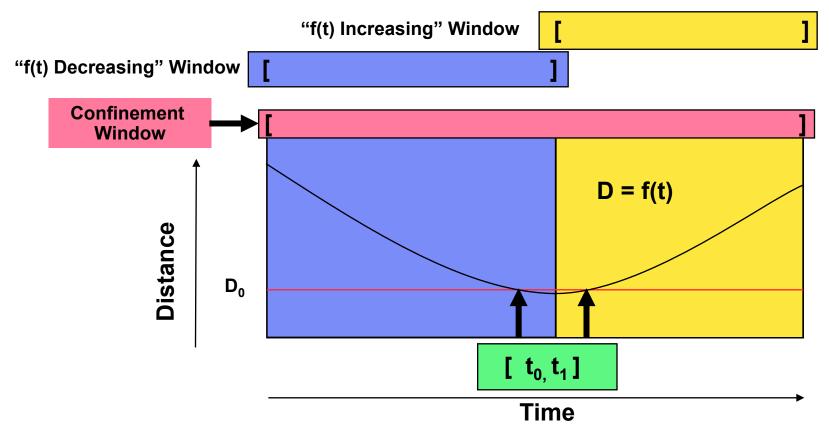


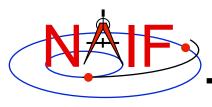
Monotone Windows-2

Navigation and Ancillary Information Facility

The shortest interval on which the function is monotonically increasing or decreasing may be LONGER than the event of interest.

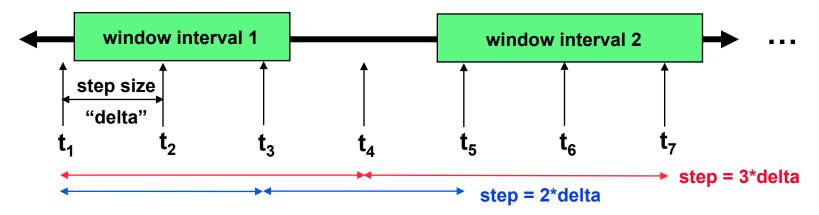
For example, consider the search for times when D < D_0 . The result window consists of the interval [t_0 , t_1] shown below.



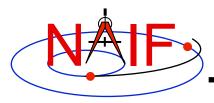


Bracketing Interval Endpoints

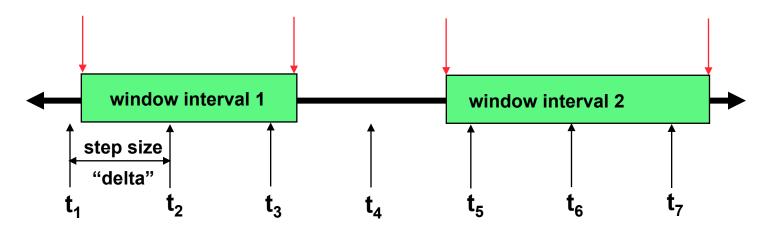
- In the diagram below, the green boxes denote intervals of a window.
- The start of the first interval is bracketed by the first and second times; the end of the first interval is bracketed by the third and fourth times. The start of the second interval is bracketed by the fourth and fifth times.



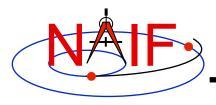
- The step size is a critical determinant of the completeness of the solution:
 - If the step size were equal to 3*delta, the first interval would not be seen.
 - If the step size were equal to 2*delta, the first and second intervals would not be seen as distinct.



Solving for Interval Endpoints

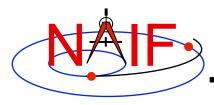


- Once an interval endpoint is bracketed, the GF subsystem performs a refinement search to locate the endpoint precisely (shown by the red arrows).
 - The default tolerance for convergence is 1.e-6 second.
- The refinement search is usually relatively fast compared to the interval bracketing search.



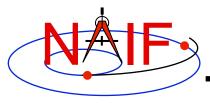
The Result Window

- For binary state searches, the window whose endpoints are found IS the result window.
 - The search is done once the endpoint refinement step has been completed for each interval over which the state is true.
- For numeric searches, once the monotone windows have been found, the result window still must be computed:
 - Local and absolute extrema can be found without further searching.
 - Equalities, inequalities, and adjusted absolute extrema require a second search pass in which each monotone interval is examined.
 - » These searches don't require sequential stepping and are usually relatively fast compared to the interval bracketing search.
- Since the roots are found by a search process, they are subject to approximation errors.
 - NOTE: The geometric condition may not be satisfied at or near the endpoints of the result window's intervals.
- Usually data errors are large enough so that the accuracy of the result is poorer than its precision.



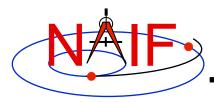
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Workspace



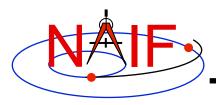
Specifying Workspace Dimensions

- GF numeric scalar searches can require relatively large amounts of memory to store intermediate results.
 - For Fortran Toolkits, user applications must declare a buffer of workspace windows.
 - For C, IDL, and MATLAB Toolkits, users need only specify the maximum number of workspace window intervals that are needed; these Toolkits will dynamically allocate the amount of memory required by the specified workspace window interval count.
- In most cases, users need not accurately compute the required amount of workspace; it's usually safe to specify a number much larger than the amount actually needed.
 - For example, if the result window is anticipated to contain 100 intervals, specifying a workspace window interval count of 10000 will very likely succeed.
 - See the GF Required Reading and the API documentation for details.



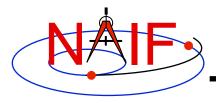
Navigation and Ancillary Information Facility

API Example: GFDIST Solve for Distance Constraints



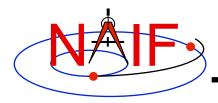
API Example: GFDIST

- GFDIST finds times when a specified constraint on the distance between two ephemeris objects is met.
 - The distance is the norm of a position vector
 - The position vector is defined using a subset of the inputs accepted by SPKPOS:
 - » Target
 - » Observer
 - » Aberration Correction
 - The constraint is a numeric relation: equality or inequality relative to a reference value, or attainment of a local or absolute extremum.
- The search is conducted within a specified confinement window.
- The search produces a result window which indicates the time period, within the confinement window, over which the constraint is met.



Language Differences

- Due to use of SPICE windows, some of the GFDIST set-up code differs substantially across languages.
 - We'll show how to perform the set-up unique to each language.
 - » Note: there's no set-up to do in the MATLAB case; hence there's no MATLAB-specific set-up slide.
 - The rest of the code is sufficiently parallel across languages to justify showing only the Fortran code.
 - Note however that the treatment of workspace differs across languages: only in Fortran does the user application have to pass the workspace array to the GF API routine.



Fortran Set-up

Navigation and Ancillary Information Facility

Fortran constant and variable declarations

Declare confinement window, result window, and workspace array

INCLUDE 'gf.inc' Include GF parameters such as NWDIST

INTEGER

PARAMETER

(LBCELL = -5)

INTEGER MAXWIN COCCOC)

Choose a "large" value for window size (called "MAXWIN" here), if you're not sure what size is required. The actual requirement depends on underlying geometry, confinement window, and search stop size.

PARAMETER (MAXWIN = 200000) window, and search step size.

DOUBLE PRECISION CNFINE (LBCELL: MAXWIN)

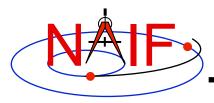
DOUBLE PRECISION RESULT (LBCELL: MAXWIN)

DOUBLE PRECISION WORK (LBCELL: MAXWIN, NWDIST)

Initialization...typically done once per program execution

Initialize confinement and result windows. Workspace need not be initialized here.

CALL SSIZED (MAXWIN, CNFINE)
CALL SSIZED (MAXWIN, RESULT)



C Set-up

Navigation and Ancillary Information Facility

C constant and variable declarations

Declare confinement and result windows, as well as size of workspace.

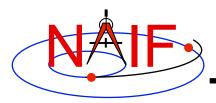
```
#include "SpiceUsr.h" and prototype declarations
...

Choose a "large" value for window size (called "MAXWIN" here), if you're not sure what size is required. Actual requirement depends on underlying geometry, confinement window, and search step size. The window size must be twice the maximum number of intervals the window is meant to hold.

SPICEDOUBLE_CELL (cnfine, MAXWIN);

SPICEDOUBLE_CELL (result, MAXWIN);

These macro calls declare CSPICE window structures and set their maximum sizes.
```



IDL Set-up

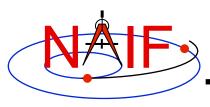
Navigation and Ancillary Information Facility

IDL window creation

lcy windows are created dynamically:
 cnfine = cspice_celld (MAXWIN)

Choose a "large" value for window size (called "MAXWIN" here), if you're not sure what size is required. Actual requirement depends on underlying geometry, confinement window, and search step size. The window size must be twice the maximum number of intervals the window is meant to hold.

The output result window is created by CSPICE_GFDIST; it does not require a constructor call by the user application.



All Languages: Additional Set-up

Navigation and Ancillary Information Facility

Initialization...typically done once per program execution

Tell your program which SPICE files to use ("loading" files)

CALL FURNSH ('spk_file_name')
CALL FURNSH ('leapseconds_file_name')

Better yet, replace these two calls with a single call to a "meta-kernel" containing the names of all kernel files to load.

The next step is to insert times into the confinement window. The simplest confinement window consists of a single time interval.

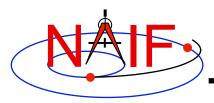
Convert UTC start and stop times to ephemeris time (TDB), if needed:

CALL STR2ET ('utc_start', tdb_0)

CALL STR2ET ('utc_stop', tdb_1)

Insert start and stop times into the confinement window:

CALL WNINSD (tdb_0, tdb_1, CNFINE)



Execute the Search -1

Navigation and Ancillary Information Facility

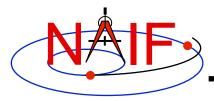
Search execution...done as many times as necessary during program execution

Choose:

- Geometric input arguments:
 - » Target
 - » Observer
 - » Aberration correction
- Constraint arguments:
 - » Relation
 - » Reference value, if applicable
 - » Adjustment value, if applicable
- Search step size

Then call GFDIST:

CALL GFDIST (target, 'correction', observer, 'relate', refval, adjust, step, cnfine, mw, nw, work, result)



Execute the Search -2

Navigation and Ancillary Information Facility

Search execution, continued

Extract intervals from the result window:

DO I = 1, WNCARD(RESULT)

[Fetch the endpoints of the lth interval of the result window.]

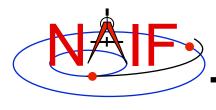
CALL WNFETD(RESULT, I, START, FINISH)

[use START, FINISH...]

END DO

Note:

- The result window may be empty.
- The constraint might not be satisfied at or near the endpoints of any interval of RESULT.
 - » Consider using the window contraction routine WNCOND to shrink the intervals of the result window slightly, so the constraint is met on the entire result window.
 - » Caution: DON'T use WNCOND for minimum, maximum, or equality searches---the result window will disappear! (WNCOND is ok for adjusted absolute extrema search results, though, since the result intervals are not singletons.)
 - » Caution: using WNCOND may not be desirable if the window is an intermediate result: subsequent, derived results might be made less accurate.



Arguments of GFDIST - 1

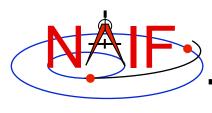
Navigation and Ancillary Information Facility

INPUTS

- TARGET* and OBSERVER*: Character names or NAIF IDs for the end point and origin of the position vector (Cartesian position and velocity vectors) whose length is the subject of the search. Below, we'll simply call this length "the distance."
 - The position vector points from observer to target.
- CORRECTION: Specification of what kind of aberration correction(s), if any, to apply in computing the distance.
 - Use 'LT+S' to use the apparent position of the target as seen by the observer. 'LT+S' invokes light time and stellar aberration corrections.
 - Use 'NONE' to use the uncorrected (aka "geometric") position, as given by the source SPK file or files.

See the headers of the subroutines GFDIST and SPKEZR, the document SPK Required Reading, or the "Fundamental Concepts" tutorial for details. See the SPK tutorial backup charts for examples of aberration correction magnitudes.

^{*} Character names work for the target and observer inputs only if built into SPICE or if registered using the SPICE ID-body name mapping facility. Otherwise use the SPICE numeric ID in quotes, as a character string.



Arguments of GFDIST - 2

Navigation and Ancillary Information Facility

INPUTS

- RELATE, REFVAL, ADJUST: parameters specifying a constraint to be met by the distance.
 - RELATE may be any of '=', '>', '<', 'LOCMAX', 'LOCMIN', 'ABSMAX', 'ABSMIN'
 - If RELATE is an equality or inequality operator, REFVAL is the corresponding double precision reference value. Units are km.
 - » For example, if the constraint is "distance = 4.D5 km," then RELATE is '=' and REFVAL is 4.D5.
 - If RELATE specifies an absolute maximum or minimum, ADJUST is the adjustment value. Units are km.
 - » Set ADJUST to 0.D0 for a simple absolute maximum or minimum.
 - » Set ADJUST to a positive value ADJ for either DISTANCE > absolute max -ADJ or DISTANCE < absolute min + ADJ.</p>
- STEP: search step size, expressed as TDB seconds.
- CNFINE: the confinement window over which the search will be performed.
- MW, NW, WORK: the maximum capacity of each workspace window, the number of workspace windows, and the workspace array.

OUTPUTS

 RESULT: the window of times over which the distance constraint is satisfied.