# Computing Covariance and Correlation in Optimally Privacy-Protected Statistical Databases: Feasible Algorithms 

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#### Abstract

In many real-life situations, e.g., in medicine, it is necessary to process data while preserving the patients' confidentiality. One of the most efficient methods of preserving privacy is to replace the exact values with intervals that contain these values. For example, instead of an exact age, a privacy-protected database only contains the information that the age is, e.g., between 10 and 20 , or between 20 and 30 , etc. Based on this data, it is important to compute correlation and covariance between different quantities. For privacy-protected data, different values from the intervals lead, in general, to different estimates for the desired statistical characteristic. Our objective is then to compute the range of possible values of these estimates. Algorithms for effectively computing such ranges have been developed for situations when intervals come from the original surveys, e.g., when a person fills in whether his or her age is between 10 or 20 , between 20 and 30 , etc. These intervals, however, do not always lead to an optimal privacy protection; it turns out that more complex, computer-generated "intervalization" can lead to better privacy under the same accuracy, or, alternatively, to more accurate estimates of statistical characteristics under the same privacy constraints. In this paper, we extend the existing efficient algorithms for computing covariance and correlation based on privacy-protected data to this more general case of interval data.


## 1 Formulation of the Problem

Need for processing data in statistical databases. Often, we collect data for the purpose of finding possible dependencies between different quantities. For example, we collect all possible information about the medical patients with the hope of finding out which factors affect different illnesses and which factors affect the success of different cures. The resulting collection of records $r_{i}=\left(r_{i 1}, \ldots, r_{i p}\right)$, $1 \leq i \leq n$, is known as a statistical database since typically, statistical methods are used for look for possible dependencies; see, e.g., [7]. These statistical methods are usually based on computing statistical characteristics such as mean
$E_{j}=\frac{1}{n} \cdot \sum_{i=1}^{n} r_{i j}$, variance $V_{j}=\frac{1}{n} \cdot \sum_{i=1}^{n}\left(r_{i j}-E_{j}\right)^{2}$, standard deviation $\sigma_{j}=\sqrt{V_{j}}$, covariance $C_{j k}=\frac{1}{n} \cdot \sum_{i=1}^{n}\left(r_{i j}-E_{j}\right) \cdot\left(r_{i k}-E_{k}\right)$, and correlation $\rho_{j k}=\frac{C_{j k}}{\sigma_{j} \cdot \sigma_{k}}$.

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One of the most efficient methods of preserving privacy is to replace the exact values with intervals that contain these values. For example, instead of an exact age, a privacy-protected database only contains the information that the age is, e.g., between 10 and 20 , or between 20 and 30 , etc.

In general, for each of $p$ variables $x_{i}, 1 \leq i \leq p$, we fix some thresholds $t_{i, 1}<t_{i, 2}<\ldots<t_{i, n_{i}}$ (e.g., $0,10,20,30, \ldots$, for age), and replace each original value $x_{i}$ with the range $\left[t_{i, k}, t_{i, k+1}\right]$ that contains this value. In the above example, the actual age of 19 will be replaced by the range [10, 20].

Need to process corresponding interval data. Based on this interval data, it is important to compute the values of different statistical characteristics such as correlation and covariance between different quantities.

For privacy-protected data, for each statistical characteristic $C\left(v_{1}, \ldots, v_{m}\right)$, different values $v_{i}$ from the given intervals $\left[\underline{v}_{i}, \bar{v}_{i}\right]$ lead, in general, to different estimates $C\left(v_{1}, \ldots, v_{m}\right)$. Thus, it is necessary to compute the range of possible values of these estimates:

$$
\begin{gather*}
C\left(\left[\underline{v}_{1}, \bar{v}_{1}\right], \ldots,\left[\underline{v}_{m}, \bar{v}_{m}\right]\right) \stackrel{\text { def }}{=} \\
\left\{C\left(v_{1}, \ldots, v_{m}\right): v_{1} \in\left[\underline{v}_{1}, \bar{v}_{1}\right], \ldots, v_{m} \in\left[\underline{v}_{m}, \bar{v}_{m}\right]\right\} . \tag{1}
\end{gather*}
$$

What was known before. For most statistical characteristics, the problem of computing the range (1) under general interval uncertainty is NP-hard; see, e.g., [6]. However, for the above-described privacy-related case, feasible algorithms are possible for computing many statistical characteristics, in particular, covariance and correlation; see, e.g., [2-6].

Need to go beyond the threshold-based "intervalization". In the above thresholdbased "intervalization", we replace each data point $r=\left(r_{1}, \ldots, r_{p}\right)$ with a box

$$
\begin{equation*}
b=\left[\underline{b}_{1}, \bar{b}_{1}\right] \times \ldots \times\left[\underline{b}_{p}, \bar{b}_{p}\right] \tag{2}
\end{equation*}
$$

formed by the corresponding threshold intervals $\left[\underline{b}_{i}, \bar{b}_{i}\right]$. The larger the boxes, the wider the resulting interval (1) - i.e., the less accurate our estimates of the corresponding statistical characteristics. From this viewpoint, the boxes $b$ should be as narrow as possible. On the other hand, if they are too narrow, e.g., if some box contains only one record, then the privacy of this record is not well-protected. To properly protect privacy, we need to make sure for some sufficiently large integer $K$, each box $b$ contains at least $K$ records (this is called
$K$-anonymity; see, e.g., [8]), and that for each variable $x_{i}$, there are at least $\ell$ different values of this variable coming from records within this box (this is called $\ell$-diversity); see, e.g., [1].

Boxes do not have to come from thresholds. The only reasonable restriction is that they should form a subdivision in the sense that no two boxes should have a common interior point. Under the privacy-motivated restrictions of $K$-anonymity and $\ell$-diversity, we must look for a subdivision into boxes which leads to the narrowest possible range $C\left(\left[\underline{v}_{1}, \bar{v}_{1}\right], \ldots,\left[\underline{v}_{p}, \bar{v}_{p}\right]\right)$ of the desired characteristic. It turns out (see, e.g., $[9,10]$ ) that to attain this narrowest range, we need to use a general subdivision into boxes which is more complex than the above thresholdbased one. Namely, in the above threshold-based subdivision into boxes, if two records $\left(r_{1}, r_{2}, \ldots\right)$ and $\left(r_{1}^{\prime}, r_{2}^{\prime}, \ldots\right)$ have the same value of $r_{1}$ (i.e., if $\left.r_{1}^{\prime}=r_{1}\right)$, then the corresponding boxes have the same $x_{1}$-interval $\left[\underline{b}_{1}, \bar{b}_{1}\right]$. In other words, the selection of the $x_{1}$-interval of the corresponding box depends only on the value $r_{1}$ and does not depend on the values of all other quantities $r_{2}, \ldots$

In contrast, in the optimal subdivision into boxes, the same value of $r_{1}$, depending on the values of other quantities $r_{2}, \ldots$, we may need boxes with different $x_{1}$-intervals. For example, if for some $r_{2}, \ldots$, there are more records around the point $\left(r_{1}, r_{2}, \ldots\right)$, then, in the optimal subdivision into boxes, these records are assigned to a narrower box, with narrower $x_{1}$-intervals. On the other hand, for the same value $r_{1}$ and different values $r_{2}^{\prime}, \ldots$, there may be much fewer records around the point $\left(r_{1}, r_{2}^{\prime}, \ldots\right)$. In this case, in the optimal subdivision into boxes, these new records records are assigned to a wider box, with a wider $x_{1}$-interval.

Resulting problem and what we do in this paper. Since the optimal intervalization goes beyond a simple threshold-based one, it is necessary to extend algorithms for estimating covariance and correlation to such optimal intervalization. Such algorithms are presented in this paper.

## 2 Analysis of the Problem

First comment: computing the upper endpoint $\bar{C}_{j k}$ can be reduced to computing the lower endpoint $\underline{C}_{j k}$. One can easily check that if we replace each value $r_{i k}$ with its opposite $r_{i k}^{\prime}=-r_{i k}$, then the covariance $C_{j k}$ changes sign: $C_{j k}^{\prime}=-C_{j k}$. As a result, if we replace each original interval $\left[\underline{r}_{i k}, \bar{r}_{i k}\right]$ with its opposite $\left[-\bar{r}_{i k},-\underline{r}_{i k}\right]$, then the resulting range is the opposite to the original range: $\left[\underline{C}_{j k}^{\prime}, \bar{C}_{j k}^{\prime}\right]=\left[-\bar{C}_{j k},-\underline{C}_{j k}\right]$. This means, in particular, that $\underline{C}_{j k}^{\prime}=-\bar{C}_{j k}$ and therefore, that $\bar{C}_{j k}=-\underline{C}_{j k}^{\prime}$.

Thus, if we know how to compute lower endpoints, we can compute the lower endpoint $\underline{C}_{j k}^{\prime}$ for the modified database, and then compute $\bar{C}_{j k}$ as $\bar{C}_{j k}=-\underline{C}_{j k}^{\prime}$.

Because of this reduction, in the following text, we will only consider the problem of computing the lower endpoint $\underline{C}_{j k}$.

Known facts from calculus: reminder. Each statistical characteristic $C\left(v_{1}, \ldots, v_{m}\right)$ is a continuous function of its variables. It is known that the range of a continuous function on a connected box $\left[\underline{v}_{1}, \bar{v}_{1}\right] \times \ldots \times\left[\underline{v}_{m}, \bar{v}_{m}\right]$ is an interval $[\underline{C}, \bar{C}]$ whose endpoints are the smallest possible value $\underline{C}$ of the function $C\left(v_{1}, \ldots, v_{m}\right)$ on the box and its largest value $\bar{C}$. It is also known that for each continuous function on a closed box, its minimum and its maximum are attained at some points.

When a function $C\left(v_{1}, \ldots, v_{m}\right)$ attains its minimum on the box at a point $\left(v_{1}^{\min }, \ldots, v_{i}^{\min }, \ldots, v_{m}^{\min }\right)$, this means, in particular, that for every $i$, the onevariable function $f\left(v_{i}\right) \stackrel{\text { def }}{=} C\left(v_{1}^{\min }, \ldots, v_{i-1}^{\min }, v_{i}, v_{i+1}^{\min }, \ldots, v_{m}^{\min }\right)$ attains its minimum on the interval $\left[\underline{v}_{i}, \bar{v}_{i}\right]$ at $v_{i}=v_{i}^{\min }$.

In general, a function $f(x)$ of one variable attains its minimum on an interval $[\underline{x}, \bar{x}]$ either inside this interval or at one of its endpoints $\underline{x}$ or $\bar{x}$. If the function $f(x)$ attains its minimum at an inside point, then its derivative at this point is known to be equal to $0: f^{\prime}\left(x^{\mathrm{min}}\right)=0$. If $f(x)$ attains its minimum at $\underline{x}$, then we should have $f^{\prime}(\underline{x}) \geq 0$ because otherwise, if we had $f^{\prime}(\underline{x})<0$, then, for a small $\Delta x$, we would have $f(\widetilde{x}+\Delta x)<f(\underline{x})$, which contradicts to our assumption that the value $f(\underline{x})$ is the smallest. Similarly, if the function $f(x)$ attains its minimum at $\bar{x}$, we should have $f^{\prime}(\bar{x}) \leq 0$.

Let us apply these facts to minimizing covariance. For covariance, as one can easily check, $\frac{\partial C_{j k}}{\partial r_{i j}}=\frac{1}{n} \cdot\left(r_{i k}-E_{k}\right)$ and $\frac{\partial C_{j k}}{\partial r_{i k}}=\frac{1}{n} \cdot\left(r_{i j}-E_{j}\right)$. Thus, for the values $r_{i j}^{\min }$ and $r_{i k}^{\min }$ at which the minimum of $C_{j k}$ is attained, we have one of the three options:

- either $\underline{r}_{i j}<r_{i j}^{\min }<\bar{r}_{i j}$ and $\frac{\partial C_{j k}}{\partial r_{i j}}=0$, i.e., $r_{i k}^{\min }=E_{k}$;
- or $r_{i j}^{\min }=\underline{r}_{i j}$ and $r_{i k}^{\min } \geq E_{k}$;
- or $r_{i j}^{\min }=\bar{r}_{i j}$ and $r_{i k}^{\min } \leq E_{k}$.

Thus:

- if $r_{i k}^{\min }>E_{k}$, then the first and third cases are impossible, so we must have $r_{i j}^{\min }=\underline{r}_{i j}$;
- if $r_{i k}^{\min }<E_{k}$, then the first and second cases are impossible, so we must have $r_{i j}^{\min }=\bar{r}_{i j}$.

Therefore, if $E_{k}<\underline{r}_{i k}$, then, due to $\underline{r}_{i k} \leq r_{i k}^{\min }$, we get $E_{k}<r_{i k}^{\min }$ and therefore, $r_{i j}^{\text {min }}=\underline{r}_{i j}$. Similarly, if $\bar{r}_{i k}<E_{k}$, then $r_{i j}^{\text {min }}=\bar{r}_{i j}$.

Likewise, if $r_{i j}^{\min }>E_{j}$, then $r_{i k}^{\min }=\underline{r}_{i k}$, and if $r_{i j}^{\min }<E_{j}$, then $r_{i k}^{\min }=\bar{r}_{i k}$. So, if $E_{j}<\underline{r}_{i j}$, then $r_{i k}^{\min }=\underline{r}_{i k}$, and if $\bar{r}_{i j}<E_{j}$, then $r_{i k}^{\min }=\bar{r}_{i k}$.

Thus, if we know the location of $E_{j}$ in comparison to the interval $\left[\underline{r}_{i j}, \bar{r}_{i j}\right]$ and we know the location of $E_{k}$ in comparison with the interval $\left[\underline{r}_{i k}, \bar{r}_{i k}\right]$, then, with one exception, we can uniquely determine the minimizing values $r_{i j}^{\text {min }}$ and $r_{i k}^{\min }$. For example, if $E_{k}<\underline{r}_{i k}$ and $E_{j}<\underline{r}_{i j}$, then $r_{i j}^{\min }=\bar{r}_{i j}$ and $r_{i k}^{\min }=\bar{r}_{i k}$. If $E_{k}<\underline{r}_{i k}$ and $\underline{r}_{i j} \leq E_{j} \leq \bar{r}_{i j}$, then $r_{i j}^{\min }=\bar{r}_{i j} \geq E_{j}$, hence $r_{i k}^{\min }=\bar{r}_{i k}$.

The only exception is when $E_{j} \in\left[\underline{r}_{i j}, \bar{r}_{i j}\right]$ and $E_{k} \in\left[\underline{r}_{i k}, \bar{r}_{i k}\right]$. In this case, minimizing over $r_{i j}$, we have three calculus-motivated options:

- the first option is $r_{i k}^{\min }=E_{k}$;
- the second option is $r_{i j}^{\min }=\underline{r}_{i j}$ and $r_{i k}^{\min } \geq E_{k}$;
- the third option is $r_{i j}^{\min }=\bar{r}_{i j}$ and $r_{i k}^{\min } \leq E_{k}$.

These conditions describe a set of possible pairs $\left(r_{i j}^{\min }, r_{i k}^{\min }\right)$, a set formed by three line segments.

Similarly, minimizing over $r_{i k}$, we have three other calculus-motivated options:

- the first option is $r_{i j}^{\min }=E_{j}$;
- the second option is $r_{i k}^{\min }=\underline{r}_{i k}$ and $r_{i j}^{\min } \geq E_{j}$;
- the third option is $r_{i k}^{\min }=\bar{r}_{i k}$ and $r_{i j}^{\min } \leq E_{j}$,
which define a new three-segment set. The actual pair $\left(r_{i j}^{\min }, r_{i k}^{\min }\right)$ belongs to both these sets and thus, belongs to their intersection. This intersection consists of three points: $\left(\underline{r}_{i j}, \bar{r}_{i k}\right),\left(\bar{r}_{i j}, \underline{r}_{i k}\right)$, and $\left(E_{j}, E_{k}\right)$.

Let us show that the minimum cannot be attained at a point $\left(E_{j}, E_{k}\right)$. Indeed, let us show that if for some small $\Delta \neq 0$, we replace the value $r_{i j}=E_{j}$ with a new value $r_{i j}^{\prime}=E_{j}+\Delta$ and the value $r_{i k}=E_{k}$ with a new value $r_{i k}^{\prime}=E_{k}-\Delta$, then the covariance will decrease - which shows that the minimum is not attained when $r_{i j}=E_{j}$ and $r_{i k}=E_{k}$. To show this, we will use a known equivalent expression for the covariance $C_{j k}=M-E_{j} \cdot E_{k}$, where $M \stackrel{\text { def }}{=} \frac{1}{n} \cdot \sum_{i=1}^{n} r_{i j} \cdot r_{i k}$. When we replace the values $r_{i j}$ and $r_{i k}$ with the new values $r_{i j}^{\prime}$ and $r_{i k}^{\prime}$, then the mean $E_{j}$ is replaced with $E_{j}^{\prime}=E_{j}+\frac{\Delta}{n}$, the mean $E_{k}$ is replaced with $E_{k}^{\prime}=E_{k}-\frac{\Delta}{n}$. The product $r_{i j} \cdot r_{i k}=E_{j} \cdot E_{k}$ is replaced with

$$
\left(E_{j}+\Delta\right)\left(E_{k}-\Delta\right)=E_{j} \cdot E_{k}-\Delta \cdot E_{j}+\Delta \cdot E_{k}-\Delta^{2}
$$

Thus, the quantity $M$ is replaced with $M^{\prime}=M-\frac{1}{n} \cdot \Delta \cdot E_{j}+\frac{1}{n} \cdot \Delta \cdot E_{k}-\frac{1}{n} \cdot \Delta^{2}$. Hence, the new expression for the covariance takes the form

$$
C_{j k}^{\prime}=M^{\prime}-E_{j}^{\prime} \cdot E_{k}^{\prime}=M-\frac{1}{n} \cdot \Delta \cdot E_{j}+\frac{1}{n} \cdot \Delta \cdot E_{k}-\frac{1}{n} \cdot \Delta^{2}-\left(E_{j}+\frac{\Delta}{n}\right) \cdot\left(E_{k}+\frac{\Delta}{n}\right) .
$$

After opening parentheses, we can see that the terms proportional to $\Delta \cdot E_{j}$ and $\Delta \cdot E_{k}$ cancel out, so we get $C_{j k}^{\prime}=C_{j k}-\frac{1}{n} \cdot \Delta^{2}+\frac{1}{n^{2}} \cdot \Delta^{2}=C_{j k}-\frac{n-1}{n^{2}} \cdot \Delta^{2}<C_{j k}$. This proves that when the box $b$ contains the point $\left(E_{j}, E_{k}\right)$, then we have only two options for the minimizing values of $r_{i j}$ and $r_{i k}$.

Towards an algorithm. In the privacy-protected database, boxes form a subdivision, so for each possible location of the pair $\left(E_{j}, E_{k}\right)$, there is at most one box that contains this pair. This box contains several records; let us denote their number by $n_{b}$. In the minimizing selection, some of the pairs $\left(r_{i j}^{\min }, r_{i k}^{\min }\right)$ are equal to $\left(\underline{r}_{i j}, \bar{r}_{i k}\right)$ and some are equal to ( $\bar{r}_{i j}, \underline{r}_{i k}$ ). Covariance does not change if we re-order the records; thus, when computing covariance, we only care about how many of $n_{b}$ records are equal to $\left(\underline{r}_{i j}, \bar{r}_{i k}\right)$; let us denote this number by $m_{b}$. One can easily check that $M, E_{j}$, and $E_{k}$ are linear functions of $m_{b}$; thus, the covariance $C_{j k}=M-E_{j} \cdot E_{k}$ is a quadratic function of $m_{b}: C_{j k}=C_{2} \cdot m_{b}^{2}+C_{1} \cdot m_{b}+C_{0}$, for known values $C_{i}$.

To find the smallest possible value of $C_{j k}$, we want to find a value $m_{b}=$ $0,1, \ldots, n_{b}$ for which this expression is the smallest possible. This can be done by using the known properties of a quadratic function $C_{2} \cdot m_{b}^{2}+C_{1} \cdot m_{b}+C_{0}$ :

- when $C_{2}>0$, it decreases when $m_{b} \leq-\frac{C_{1}}{2 C_{2}}$ and increases after that;
- when $C_{2}<0$, it increases when $m_{b} \leq-\frac{C_{1}}{2 C_{2}}$ and decreases after that;
- when $C_{2}=0$, it increases if $C_{1}>0$ and decreases if $C_{1}<0$.

On the interval where this expression is increasing, we take the smallest possible value of $m_{b}$; on the interval where this expression is decreasing, we take the largest possible value of $m_{b}$.

Towards an algorithm: final touch. What is important is where the values $E_{j}$ and $E_{k}$ are in comparison with the endpoints of the corresponding intervals $\left[\underline{r}_{i j}, \bar{r}_{i j}\right]$ and $\left[\underline{r}_{i k}, \bar{r}_{i k}\right]$. Thus, to find possible ranges of $E_{j}$, we can sort all the endpoints $\underline{r}_{i j}$ and $\bar{r}_{i j}$ of the $x_{j}$-intervals of different boxes into an increasing sequence $T_{j, 1}<T_{j, 2}<\ldots$, and consider all possible "small boxes" $b=\left[T_{j, i_{j}}, T_{j, i_{j}+1}\right] \times$ [ $\left.T_{k, i_{k}}, T_{j, i_{k}+1}\right]$. Thus, we arrive at the following algorithm for computing the lower endpoint $\underline{C}_{j k}$ of the range of covariance.

## 3 Algorithm for Computing Covariance

What is given. We are given a finite collection of $B$ boxes $b_{a}=\left[\underline{b}_{a 1}, \bar{b}_{a 1}\right] \times \ldots \times$ $\left[\underline{b}_{a p}, \bar{b}_{a p}\right], 1 \leq a \leq B$. These boxes form a subdivision, i.e., no two boxes have a common interior point. For each of these boxes, we are given the number $n_{a}$ of records corresponding to this box. We are also given the indices $j$ and $k$ for which we want to find the range of covariance values.

Algorithm. First, we sort all $2 B j$-endpoints $\underline{b}_{a j}$ and $\bar{b}_{a j}$ of all $B$ boxes into an increasing sequence $T_{j, 1}<T_{j, 2}<\ldots$, and form $\leq 2 B$ "small" $j$-intervals $\left[T_{j, i_{j}}, T_{j, i_{j}+1}\right]$.

Then, we similarly sort all $2 B k$-endpoints $\underline{b}_{a k}$ and $\bar{b}_{a k}$ of all $B$ boxes into an increasing sequence $T_{k, 1}<T_{k, 2}<\ldots$, and form $\leq 2 B$ "small" $k$-intervals $\left[T_{k, i_{k}}, T_{k, i_{k}+1}\right]$. After that, we form "small boxes" by considering all possible
pairs $b=\left[T_{j, i_{j}}, T_{j, i_{j}+1}\right] \times\left[T_{k, i_{k}}, T_{j, i_{k}+1}\right]$ of a small $j$-interval and a small $k$ interval. In our algorithms, we will analyze these small boxes one by one.

Let us now consider computations corresponding to a fixed small box $b$. As we have shown, once the small box $b=\left[\underline{b}_{j}, \bar{b}_{j}\right] \times\left[\underline{b}_{k}, \bar{b}_{k}\right]$ is fixed, then for almost all original boxes (except for the original box $b_{a_{0}}$ that contains $b$ ), we can uniquely determine the minimizing values $r_{i j}^{\min }$ and $r_{i k}^{\min }$ :

- if $\bar{b}_{j} \leq \underline{b}_{a j}$ and $\bar{b}_{k} \leq \underline{b}_{a k}$, then $r_{i j}^{\min }=\underline{b}_{a j}$ and $r_{i k}^{\min }=\underline{b}_{a k}$;
- if $\bar{b}_{j} \leq \underline{b}_{a j}$ and $\underline{b}_{a k} \leq \underline{b}_{k} \leq \bar{b}_{k} \leq \bar{b}_{a k}$, then $r_{i j}^{\min }=\bar{b}_{a j}$ and $r_{i k}^{\min }=\underline{b}_{a k}$;
- if $\bar{b}_{j} \leq \underline{b}_{a j}$ and $\bar{b}_{a k} \leq \underline{b}_{k}$, then $r_{i j}^{\min }=\bar{b}_{a j}$ and $r_{i k}^{\min }=\underline{b}_{a k}$;
- if $\bar{b}_{a j} \leq \underline{b}_{j}$ and $\bar{b}_{k} \leq \underline{b}_{a k}$, then $r_{i j}^{\min }=\underline{b}_{a j}$ and $r_{i k}^{\min }=\bar{b}_{a k}$;
- if $\bar{b}_{a j} \leq \underline{b}_{j}$ and $\underline{b}_{a j} \leq \underline{b}_{k} \leq \bar{b}_{k} \leq \bar{b}_{a k}$, then $r_{i j}^{\min }=\underline{b}_{a j}$ and $r_{i k}^{\min }=\bar{b}_{a k}$;
- if $\bar{b}_{a j} \leq \underline{b}_{j}$ and $\bar{b}_{a k} \leq \underline{b}_{k}$, then $r_{i j}^{\min }=\bar{b}_{a j}$ and $r_{i k}^{\min }=\bar{b}_{a k}$;
- if $\underline{b}_{a j} \leq \underline{b}_{j} \leq \bar{b}_{j} \leq \bar{b}_{a j}$ and $\bar{b}_{k} \leq \underline{b}_{a k}$, then $r_{i j}^{\min }=\underline{b}_{a j}$ and $r_{i k}^{\min }=\bar{b}_{a k}$;
- if $\underline{b}_{a j} \leq \underline{b}_{j} \leq \bar{b}_{j} \leq \bar{b}_{a j}$ and $\bar{b}_{a k} \leq \underline{b}_{k}$, then $r_{i j}^{\min }=\bar{b}_{a j}$ and $r_{i k}^{\min }=\underline{b}_{a k}$.

This way, for each of the boxes $b_{a}\left(a \neq a_{0}\right)$, we can compute this box's contributions to the expressions $M, E_{j}$, and $E_{k}$ as, correspondingly,

$$
\frac{n_{a}}{n} \cdot r_{i j}^{\min } \cdot r_{i k}^{\min }, \frac{n_{a}}{n} \cdot r_{i j}^{\min }, \text { and } \frac{n_{a}}{n} \cdot r_{i k}^{\min }
$$

For the box $b_{a_{0}}=\left[\underline{b}_{a_{0} j}, \bar{b}_{a_{0} j}\right] \times\left[\underline{b}_{a_{0} k}, \bar{b}_{a_{0} k}\right]$, the corresponding contributions take the form

$$
\begin{gathered}
\frac{m_{a_{0}}}{n} \cdot \underline{b}_{a_{0} j} \cdot \bar{b}_{a_{0} k}+\frac{n_{a_{0}}-m_{a_{0}}}{n} \cdot \bar{b}_{a_{0} j} \cdot \underline{b}_{a_{0} k} \\
\frac{m_{a_{0}}}{n} \cdot \underline{b}_{a_{0} j}+\frac{n_{a_{0}}-m_{a_{0}}}{n} \cdot \bar{b}_{a_{0} j}, \text { and } \frac{m_{a_{0}}}{n} \cdot \bar{b}_{a_{0} k}+\frac{n_{a_{0}}-m_{a_{0}}}{n} \cdot \underline{b}_{a_{0} k}
\end{gathered}
$$

with an unknown $m_{a_{0}}$. By adding the contributions corresponding to different boxes and forming $C_{j k}=M-E_{j} \cdot E_{k}$, we get an expression for $C_{j k}$ which is quadratic in $m_{a_{0}}$. By using techniques described in the previous section, we can compute the minimum of this expression over all possible integer values $m_{a_{0}}$ from 0 to $n_{a_{0}}$. This minimum $C_{j k}(b)$ is the smallest possible value of the covariance under the assumption that the pair $\left(E_{j}, E_{k}\right)$ belongs to the small box $b$.

To find the desired value $\underline{C}_{j k}$, we can then compute the smallest of the values $C_{j k}(b)$ corresponding to all possible small boxes $b$.

Computational time for this algorithm. Sorting takes time $O(B \cdot \log (B))$. After sorting, we get $\leq 2 B j$-intervals and $\leq 2 B k$-intervals, so we get $O\left(B^{2}\right)$ small boxes - pairs of such intervals.

In the main part of the algorithm, for each of $O\left(B^{2}\right)$ small boxes $b$ and for each of $B$ original boxes $b_{a}$, we need finitely many computational steps. Thus, the total number of computational steps for the main part is bounded by $O\left(B^{2}\right) \cdot B \cdot$ const $=O\left(B^{3}\right)$. The total computation time is thus equal to $O(B \cdot \log (B))+O\left(B^{3}\right)$, i.e., to $O\left(B^{3}\right)$. This algorithm requires cubic time and is, therefore, feasible.

Comment. According to [9], in some cases, better estimates for covariance come from weighted estimates $C_{j k}^{w}=\sum_{i=1}^{n} w_{i} \cdot\left(r_{i j}-E_{j}^{w}\right) \cdot\left(r_{i k}-E_{k}^{w}\right)$, where

$$
E_{j}^{w}=\sum_{i=1}^{n} w_{i} \cdot r_{i j}, \quad E_{k}^{w}=\sum_{i=1}^{n} w_{i} \cdot r_{i k}
$$

and $w_{i}$ are appropriate weights for which $w_{i} \geq 0$ and $\sum_{i=1}^{n} w_{i}=1$. The weight $w_{i}$ of a record depends only on the box $b_{a}$ that contains this record. In other words, for some values $W_{a}, w_{i}=W_{a}$ for all the records $r_{i}$ from the box $b_{a}$. In these terms, the equality $\sum_{i=1}^{n} w_{i}=1$ means that $\sum_{a} n_{a} \cdot W_{a}=1$. The formula for $C_{j k}^{w}$ can be represented in an equivalent form, as $C_{j k}^{w}=M^{w}-E_{j}^{w} \cdot E_{k}^{w}$, where $M_{j k}^{w}=\sum_{i=1}^{n} w_{i} \cdot r_{i j} \cdot r_{i k}$.

An analysis similar to the one from Section 2 shows that, in effect, the algorithm from Section 3 can be applied for computing the range of this characteristic as well; the only difference is that after selecting the values $r_{i j}^{\min }$ and $r_{i k}^{\min }$, we need to use the weighted expressions $M^{w}, E_{j}^{w}$, and $E_{k}^{w}$ instead of original equal-weight expressions for $M, E_{j}$, and $E_{k}$.

## 4 Algorithms for Computing Correlation

Correlation: reminder. The Pearson's correlation coefficient $\rho$ describes the degree of dependence between the inputs: if the coefficient $\rho$ is close to 1 or to -1 , this means that there is a strong dependence; if this coefficient is close to 0 , this means that most probably, there is no dependence.

Correlation under interval uncertainty: practical meaning of lower and upper bounds. Under interval uncertainty, instead of a single value $\rho$, we get an interval $[\underline{\rho}, \bar{\rho}]$ of possible values. For positive values $\rho$, the upper endpoint $\bar{\rho}$ describes to what extent it is possible that there is a dependence between the inputs, while the lower endpoint $\underline{\rho}$ describes to what extent, based on the available data, we can guarantee that there is a dependence. Similarly, for negative values $\rho$, the lower endpoint $\underline{\rho}$ describes to what extent it is possible that there is a dependence between the inputs, while the upper endpoint $\bar{\rho}$ describes to what extent, based on the available data, we can guarantee that there is a dependence.

Which endpoints are most important for statistical databases. As we have mentioned, one of the main purposes of statistical databases is to discover possible new dependencies - dependencies which can then be checked and utilized. From this viewpoint, the most important endpoints are: the upper endpoint for the positive correlation, and the lower endpoint for the negative correlation.

Computing correlation: what is known. The relative importance of different bounds is good news: while in general, computing correlation under interval uncertainty is NP-hard (see, e.g., [6]), a feasible (i.e., polynomial-time) algorithm is possible for computing the upper endpoint $\bar{\rho}$ for positive correlations and the lower endpoint $\rho$ for negative correlations; see, e.g., [2].

The known algorithm is rather slow. This algorithm is polynomial-time: for inputs consisting of $n$ records, its computation time is bounded by $O\left(n^{5}\right)$.

However, from the practical viewpoint, even for a small database with $n=$ 1000 records, this means $10^{15}$ arithmetic operations: two weeks on a Gigaflop machine; for $n=10^{4}$ records, this already means an unrealistic amount of $10^{20}$ operations.

For statistical databases with privacy-motivated boxes, the known algorithm can be made somewhat faster. In the algorithm from [2], we consider possible quadruples (pairs of pairs) of vertices. In the privacy-motivated case, we have $\leq 4 B$ vertices, where $B$ is the number of different boxes. Thus, the total number of quadruples of vertices is $O\left(B^{4}\right)$.

According to [2], once the quadruple is fixed, then, within each box $b_{a}$, we select the same optimizing values $r_{i j}^{\max }$ and $r_{i k}^{\max }$ (or $r_{i j}^{\min }$ and $r_{i k}^{\min }$ ) for all the records from this box. Thus, once the quadruple is fixed, we need to perform only finitely many computations within each box - and then, as we did for covariance, multiply the results by $n_{a}$. For each of $O\left(B^{4}\right)$ quadruples, we therefore need $O(B)$ computational steps, to the total of $O\left(B^{4}\right) \cdot O(B)=O\left(B^{5}\right)$.

This number of steps is still large, but since the number of boxes is much smaller than the number of records, this number of steps is much smaller than $O\left(n^{5}\right)$ - and thus, more realistic.

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