

ESP32-PICO-D4 Datasheet



Espressif Systems

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About This Guide

This document provides an introduction to the specifications of the ESP32-PICO-D4 module.

The document structure is as follows:

| Chapter | Title | Subject |
|-----------|----------------------------|---|
| Chapter 1 | Overview | An overview of the ESP32-PICO-D4 module. |
| Chapter 2 | Pin Definitions | Pinout and pin descriptions. |
| Chapter 3 | Functional Description | Description of functional modules and protocols. |
| Chapter 4 | Peripherals and Sensors | Description of ESP32-PICO-D4 peripherals. |
| Chapter 5 | Electrical Characteristics | Electrical characteristics and specifications of ESP32-PICO-D4. |
| Chapter 6 | Schematics | Schematics of ESP32-PICO-D4. |
| Chapter 7 | Peripheral Schematics | Peripheral schematics of ESP32-PICO-D4. |
| Chapter 8 | Package Information | Package information of ESP32-PICO-D4. |
| Chapter 9 | Learning Resources | ESP32-related must-read materials and must-have resources. |

Release Notes

| Date | Version | Release notes |
|---------|---------|----------------|
| 2017.08 | V1.0 | First release. |

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1. Overview

The ESP32-PICO-D4 is a System-in-Package (SIP) module that is based on ESP32, providing complete Wi-Fi and Bluetooth functionalities. The module has a size as small as $7.0\pm 0.1\text{ mm}\times 7.0\pm 0.1\text{ mm}\times 0.94\pm 0.1\text{ mm}$, thus requiring minimal PCB area. The module integrates a 4-MB SPI flash.

At the core of this module is the ESP32 chip*, which is a single 2.4 GHz Wi-Fi and Bluetooth combo chip designed with TSMC's 40 nm ultra-low power technology. ESP32-PICO-D4 integrates all peripheral components seamlessly, including a crystal oscillator, flash, filter capacitors and RF matching links in one single package. Given that no other peripheral components are involved, module welding and testing is not required either. As such, ESP32-PICO-D4 reduces the complexity of supply chain and improves control efficiency.

With its ultra-small size, robust performance and low-energy consumption, ESP32-PICO-D4 is well suited for any space-limited or battery-operated applications, such as wearable electronics, medical equipment, sensors and other IoT products.

Note:

* For details on ESP32, please refer to the document [ESP32 Datasheet](#).

Table 1 provides the specifications of the ESP32-PICO-D4 module.

Table 1: ESP32-PICO-D4 Specifications

| Categories | Items | Specifications |
|---------------------------|---|--|
| Wi-Fi | Protocols | 802.11 b/g/n/e/i (802.11n up to 150 Mbps) A-MPDU and A-MSDU aggregation and $0.4\ \mu\text{s}$ guard interval support |
| | Frequency range | 2.4 ~ 2.5 GHz |
| Bluetooth | Protocols | Bluetooth V4.2 BR/EDR and BLE specification |
| | Radio | NZIF receiver with -97 dBm sensitivity |
| | | Class-1, class-2 and class-3 transmitter AFH |
| Audio | CVSD and SBC | |
| Hardware | Module interface | SD card, UART, SPI, SDIO, LED PWM, Motor PWM, I2S, I2C, IR |
| | | GPIO, capacitive touch sensor, ADC, DAC, LNA pre-amplifier |
| | On-chip sensor | Hall sensor, temperature sensor |
| | On-board clock | 40 MHz crystal |
| | Operating voltage/Power supply | 2.3 ~ 3.6V |
| | Operating current | Average: 80 mA |
| | Minimum current delivered by power supply | 500 mA |
| | Operating temperature range | $-40^{\circ}\text{C} \sim 85^{\circ}\text{C}$ |
| Ambient temperature range | Normal temperature | |
| Package size | $7.0\pm 0.1\text{ mm} \times 7.0\pm 0.1\text{ mm} \times 0.94\pm 0.1\text{ mm}$ | |

| Categories | Items | Specifications |
|------------|----------------------|--|
| Software | Wi-Fi mode | Station/SoftAP/SoftAP+Station/P2P |
| | Security | WPA/WPA2/WPA2-Enterprise/WPS |
| | Encryption | AES/RSA/ECC/SHA |
| | Firmware upgrade | UART Download / OTA (via network / download and write firmware via host) |
| | Software development | Supports Cloud Server Development / SDK for custom firmware development |
| | Network protocols | IPv4, IPv6, SSL, TCP/UDP/HTTP/FTP/MQTT |
| | User configuration | AT instruction set, cloud server, Android/iOS app |

2. Pin Definitions

2.1 Pin Layout

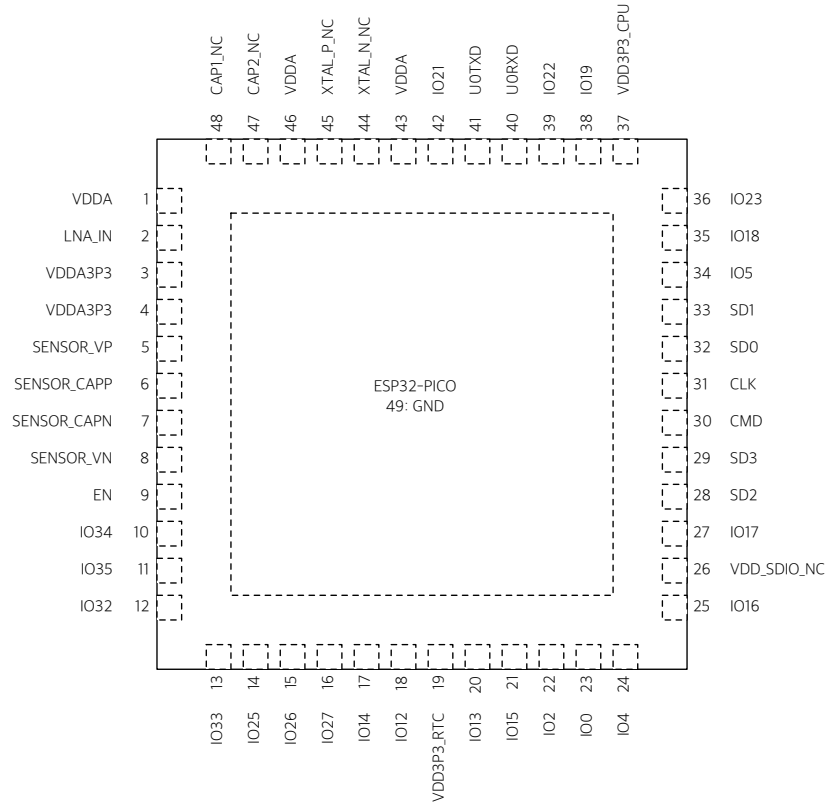


Figure 1: ESP32-PICO-D4 Pin Layout

2.2 Pin Description

The ESP32-PICO-D4 module has 49 pins. See pin definitions in Table 2.

Table 2: Pin Description

| Name | No. | Type | Function |
|-------------|-----|------|--|
| Analog | | | |
| VDDA | 1 | P | Analog power supply (2.3V ~ 3.6V) |
| LNA_IN | 2 | I/O | RF input and output |
| VDDA3P3 | 3 | P | Amplifier power supply (2.3V ~ 3.6V) |
| VDDA3P3 | 4 | P | Amplifier power supply (2.3V ~ 3.6V) |
| SENSOR_VP | 5 | I | GPIO36, ADC_PRE_AMP, ADC1_CH0, RTC_GPIO0 Note: Connects a 270 pF capacitor from SENSOR_VP to SENSOR_CAPP, when used as ADC_PRE_AMP. |
| SENSOR_CAPP | 6 | I | GPIO37, ADC_PRE_AMP, ADC1_CH1, RTC_GPIO1 Note: Connects 270 pF capacitor from SENSOR_VP to SENSOR_CAPP, when used as ADC_PRE_AMP. |

| Name | No. | Type | Function |
|-------------|-----|------|--|
| SENSOR_CAPN | 7 | I | GPIO38, ADC1_CH2, ADC_PRE_AMP, RTC_GPIO2 Note: Connects 270 pF capacitor from SENSOR_VN to SENSOR_CAPN, when used as ADC_PRE_AMP. |
| SENSOR_VN | 8 | I | GPIO39, ADC1_CH3, ADC_PRE_AMP, RTC_GPIO3 Note: Connects a 270 pF capacitor from SENSOR_VN to SENSOR_CAPN, when used as ADC_PRE_AMP. |
| EN | 9 | I | Chip Enable (Active High) High: On; chip works properly Low: Off; chip works at the minimum power Note: Do not leave CHIP_PU pin floating |
| IO34 | 10 | I | ADC1_CH6, RTC_GPIO4 |
| IO35 | 11 | I | ADC1_CH7, RTC_GPIO5 |
| IO32 | 12 | I/O | 32K_XP (32.768 kHz crystal oscillator input), ADC1_CH4, TOUCH9, RTC_GPIO9 |
| IO33 | 13 | I/O | 32K_XN (32.768 kHz crystal oscillator output), ADC1_CH5, TOUCH8, RTC_GPIO8 |
| IO25 | 14 | I/O | GPIO25, DAC_1, ADC2_CH8, RTC_GPIO6, EMAC_RXD0 |
| IO26 | 15 | I/O | GPIO26, DAC_2, ADC2_CH9, RTC_GPIO7, EMAC_RXD1 |
| IO27 | 16 | I/O | GPIO27, ADC2_CH7, TOUCH7, RTC_GPIO17, EMAC_RX_DV |
| IO14 | 17 | I/O | ADC2_CH6, TOUCH6, RTC_GPIO16, MTMS, HSPICLK, HS2_CLK, SD_CLK, EMAC_TXD2 |
| IO12 | 18 | I/O | ADC2_CH5, TOUCH5, RTC_GPIO15, MTDI, HSPIQ, HS2_DATA2, SD_DATA2, EMAC_TXD3 |
| VDD3P3_RTC | 19 | P | RTC IO power supply input (1.8V ~ 3.6V) |
| IO13 | 20 | I/O | ADC2_CH4, TOUCH4, RTC_GPIO14, MTCK, HSPID, HS2_DATA3, SD_DATA3, EMAC_RX_ER |
| IO15 | 21 | I/O | ADC2_CH3, TOUCH3, RTC_GPIO13, MTDO, HSPICS0, HS2_CMD, SD_CMD, EMAC_RXD3 |
| IO2 | 22 | I/O | ADC2_CH2, TOUCH2, RTC_GPIO12, HSPIWP, HS2_DATA0, SD_DATA0 |
| IO0 | 23 | I/O | ADC2_CH1, TOUCH1, RTC_GPIO11, CLK_OUT1, EMAC_TX_CLK |
| IO4 | 24 | I/O | ADC2_CH0, TOUCH0, RTC_GPIO10, HSPIHD, HS2_DATA1, SD_DATA1, EMAC_TX_ER |
| IO16 | 25 | I/O | GPIO16, HS1_DATA4, U2RXD, EMAC_CLK_OUT |
| VDD_SDIO_NC | 26 | - | NC |
| IO17 | 27 | I/O | GPIO17, HS1_DATA5, U2TXD, EMAC_CLK_OUT_180 |
| SD2 | 28 | I/O | GPIO9, SD_DATA2, SPIHD, HS1_DATA2, U1RXD |
| SD3 | 29 | I/O | GPIO10, SD_DATA3, SPIWP, HS1_DATA3, U1TXD |
| CMD | 30 | I/O | GPIO11, SD_CMD, SPICS0, HS1_CMD, U1RTS |
| CLK | 31 | I/O | GPIO6, SD_CLK, SPICLK, HS1_CLK, U1CTS |
| SD0 | 32 | I/O | GPIO7, SD_DATA0, SPIQ, HS1_DATA0, U2RTS |
| SD1 | 33 | I/O | GPIO8, SD_DATA1, SPID, HS1_DATA1, U2CTS |
| IO5 | 34 | I/O | GPIO5, VSPICS0, HS1_DATA6, EMAC_RX_CLK |
| IO18 | 35 | I/O | GPIO18, VSPICLK, HS1_DATA7 |

| Name | No. | Type | Function |
|------------|-----|------|--|
| IO23 | 36 | I/O | GPIO23, VSPID, HS1_STROBE |
| VDD3P3_CPU | 37 | P | CPU IO power supply input (1.8V ~ 3.6V) |
| IO19 | 38 | I/O | GPIO19, VSPIQ, U0CTS, EMAC_TXD0 |
| IO22 | 39 | I/O | GPIO22, VSPIWP, U0RTS, EMAC_TXD1 |
| U0RXD | 40 | I/O | GPIO3, U0RXD, CLK_OUT2 |
| U0TXD | 41 | I/O | GPIO1, U0TXD, CLK_OUT3, EMAC_RXD2 |
| IO21 | 42 | I/O | GPIO21, VSPIHD, EMAC_TX_EN |
| VDDA | 43 | P | Analog power supply (2.3V ~ 3.6V) |
| XTAL_N_NC | 44 | - | NC |
| XTAL_P_NC | 45 | - | NC |
| VDDA | 46 | P | Digital power supply for PLL (2.3V ~ 3.6V) |
| CAP2_NC | 47 | - | NC |
| CAP1_NC | 48 | - | NC |
| GND | 49 | P | Ground |

Note:

Pins IO16, IO17, CMD, CLK, SD0 and SD1 are used for connecting the embedded flash, and are not recommended for other uses.

2.3 Strapping Pins

ESP32 has five strapping pins, which can be see in Section 6 Schematics:

- MTDI
- GPIO0
- GPIO2
- MTDO
- GPIO5

Software can read the value of these five bits from the register "GPIO_STRAPPING".

During the chip power-on reset, the latches of the strapping pins sample the voltage level as strapping bits of "0" or "1", and hold these bits until the chip is powered down or shut down. The strapping bits configure the device boot mode, the operating voltage of VDD_SDIO and other system initial settings.

Each strapping pin is connected with its internal pull-up/pull-down during the chip reset. Consequently, if a strapping pin is unconnected or the connected external circuit is high-impedance, the internal weak pull-up/pull-down will determine the default input level of the strapping pins.

To change the strapping bit values, users can apply the external pull-down/pull-up resistances, or apply the host MCU's GPIOs to control the voltage level of these pins when powering on ESP32.

After reset, the strapping pins work as the normal functions pins.

Refer to Table 3 for detailed boot modes configuration by strapping pins.

Table 3: Strapping Pins

| Voltage of Internal LDO (VDD_SDIO) | | | | | |
|--|-----------|---|--|--|---|
| Pin | Default | 3.3V | | 1.8V | |
| MTDI | Pull-down | 0 | | 1 | |
| Bootling Mode | | | | | |
| Pin | Default | SPI Boot | | Download Boot | |
| GPIO0 | Pull-up | 1 | | 0 | |
| GPIO2 | Pull-down | Don't-care | | 0 | |
| Debugging Log on U0TXD During Bootling | | | | | |
| Pin | Default | U0TXD Toggling | | U0TXD Silent | |
| MTDO | Pull-up | 1 | | 0 | |
| Timing of SDIO Slave | | | | | |
| Pin | Default | Falling-edge Input Falling-edge Output | Falling-edge Input Rising-edge Output | Rising-edge Input Falling-edge Output | Rising-edge Input Rising-edge Output |
| MTDO | Pull-up | 0 | 0 | 1 | 1 |
| GPIO5 | Pull-up | 0 | 1 | 0 | 1 |

Note:

Firmware can configure register bits to change the settings of "Voltage of Internal LDO (VDD_SDIO)" and "Timing of SDIO Slave", after bootling.

3. Functional Description

This chapter describes the modules integrated in ESP32-PICO-D4, and their functions.

3.1 CPU and Internal Memory

ESP32 contains two low-power Xtensa® 32-bit LX6 microprocessors. The internal memory includes:

- 448 KB of ROM for booting and core functions.
- 520 KB (8 KB RTC FAST Memory included) of on-chip SRAM for data and instruction.
 - 8 KB of SRAM in RTC, which is called RTC FAST Memory and can be used for data storage; it is accessed by the main CPU during RTC Boot from the Deep-sleep mode.
- 8 KB of SRAM in RTC, which is called RTC SLOW Memory and can be accessed by the co-processor during the Deep-sleep mode.
- 1 kbit of eFuse, of which 256 bits are used for the system (MAC address and chip configuration) and the remaining 768 bits are reserved for customer applications, including Flash-Encryption and Chip-ID.

3.2 External Flash and SRAM

ESP32 supports up to four 16-MB external QSPI flash and SRAM with hardware encryption based on AES to protect developer's programs and data.

ESP32 can access the external QSPI flash and SRAM through high-speed caches.

- Up to 16 MB of external flash are memory-mapped onto the CPU code space, supporting 8, 16 and 32-bit access. Code execution is supported.
- Up to 8 MB of external flash/SRAM are memory-mapped onto the CPU data space, supporting 8, 16 and 32-bit access. Data-read is supported on the flash and SRAM. Data-write is supported on the SRAM.

The ESP32-PICO-D4 module integrates 4 MB of external SPI flash. The 4-MB SPI flash can be memory-mapped onto the CPU code space, supporting 8, 16 and 32-bit access. Code execution is supported. The integrated SPI flash is connected to GPIO6, GPIO7, GPIO8, GPIO9, GPIO10 and GPIO11. These six pins cannot be used as regular GPIO.

3.3 Crystal Oscillators

ESP32-PICO-D4 integrates 40 MHz crystal oscillator.

3.4 RTC and Power Consumption

With the advanced power management technologies, ESP32 can switch between different power modes (see Table 4).

- Power mode
 - Active mode: The chip radio is powered on. The chip can receive, transmit, or listen.
 - Modem-sleep mode: The CPU is operational and the clock is configurable. The Wi-Fi/Bluetooth baseband and radio are disabled.
 - Light-sleep mode: The CPU is paused. The RTC memory and RTC peripherals, as well as the ULP-coprocessor are running. Any wake-up events (MAC, host, RTC timer, or external interrupts) will wake up the chip.
 - Deep-sleep mode: Only RTC memory and RTC peripherals are powered on. Wi-Fi and Bluetooth connection data are stored in RTC memory. The ULP-coprocessor can work.
 - Hibernation mode: The internal 8-MHz oscillator and ULP-coprocessor are disabled. The RTC recovery memory is powered down. Only one RTC timer on the slow clock and some RTC GPIOs are active. The RTC timer or the RTC GPIOs can wake up the chip from the Hibernation mode.
- Sleep Pattern
 - Association sleep pattern: The power mode switches between the Active mode, Modem- and Light-sleep mode during this sleep pattern. The CPU, Wi-Fi, Bluetooth, and radio are woken up at predetermined intervals to keep Wi-Fi/BT connections alive.
 - ULP sensor-monitored pattern: The main CPU is in the Deep-sleep mode. The ULP co-processor does sensor measurements and wakes up the main system, based on the measured data from sensors.

Table 4: Functionalities Depending on the Power Modes

| Power mode | Active | Modem-sleep | Light-sleep | Deep-sleep | Hibernation |
|--------------------------------|---------------------------|-------------|-------------|------------------------------|-------------|
| Sleep pattern | Association sleep pattern | | | ULP sensor-monitored pattern | - |
| CPU | ON | ON | PAUSE | OFF | OFF |
| Wi-Fi/BT baseband and radio | ON | OFF | OFF | OFF | OFF |
| RTC memory and RTC peripherals | ON | ON | ON | ON | OFF |
| ULP co-processor | ON | ON | ON | ON/OFF | OFF |

The power consumption varies with different power modes/sleep patterns, and work status, of functional modules. Please see Table 5 for details.

Table 5: Power Consumption by Power Modes

| Power mode | Description | Power consumption |
|---------------------|--|---|
| Active (RF working) | Wi-Fi Tx packet 14 dBm ~ 19.5 dBm | Please refer to ESP32 Datasheet . |
| | Wi-Fi / BT Tx packet 0 dBm | |
| | Wi-Fi / BT Rx and listening | |
| | Association sleep pattern (by Light-sleep) | 1 mA ~ 4 mA @DTIM3 |

| Power mode | Description | Power consumption |
|-------------|--|------------------------------------|
| Modem-sleep | The CPU is powered on. | Max speed 240 MHz: 30 mA ~ 50 mA |
| | | Normal speed 80 MHz: 20 mA ~ 25 mA |
| | | Slow speed 2 MHz: 2 mA ~ 4 mA |
| Light-sleep | - | 0.8 mA |
| Deep-sleep | The ULP co-processor is powered on. | 150 μ A |
| | ULP sensor-monitored pattern | 100 μ A @1% duty |
| | RTC timer + RTC memory | 10 μ A |
| Hibernation | RTC timer only | 5 μ A |
| Power off | CHIP_PU is set to low level, the chip is powered off | 0.1 μ A |

Note:

- During Deep-sleep, when ULP co-processor is powered on, peripherals such as GPIO and I2C are able to work.
- When the system works in the ULP sensor-monitored pattern, the ULP co-processor works with the ULP sensor periodically; ADC works with a duty cycle of 1%, so the power consumption is 100 μ A.

4. Peripherals and Sensors

4.1 Peripherals and Sensors Description

Table 6: Peripherals and Sensors Description

| Interface | Signal | Pin | Function |
|--------------------------------------|-----------|-----------|---|
| ADC | ADC1_CH0 | SENSOR_VP | Two 12-bit SAR ADCs |
| | ADC1_CH3 | SENSOR_VN | |
| | ADC1_CH4 | IO32 | |
| | ADC1_CH5 | IO33 | |
| | ADC1_CH6 | IO34 | |
| | ADC1_CH7 | IO35 | |
| | ADC2_CH0 | IO4 | |
| | ADC2_CH1 | IO0 | |
| | ADC2_CH2 | IO2 | |
| | ADC2_CH3 | IO15 | |
| | ADC2_CH4 | IO13 | |
| | ADC2_CH5 | IO12 | |
| | ADC2_CH6 | IO14 | |
| | ADC2_CH7 | IO27 | |
| | ADC2_CH8 | IO25 | |
| ADC2_CH9 | IO26 | | |
| Ultra Low Noise Analog Pre-Amplifier | SENSOR_VP | IO36 | Provides about 60 dB gain by using larger capacitors on PCB |
| | SENSOR_VN | IO39 | |
| DAC | DAC_1 | IO25 | Two 8-bit DACs |
| | DAC_2 | IO26 | |
| Touch Sensor | TOUCH0 | IO4 | Capacitive touch sensors |
| | TOUCH1 | IO0 | |
| | TOUCH2 | IO2 | |
| | TOUCH3 | IO15 | |
| | TOUCH4 | IO13 | |
| | TOUCH5 | IO12 | |
| | TOUCH6 | IO14 | |
| | TOUCH7 | IO27 | |
| | TOUCH8 | IO33 | |
| | TOUCH9 | IO32 | |
| SD/SDIO/MMC Host Controller | HS2_CLK | MTMS | Supports SD memory card V3.01 standard |
| | HS2_CMD | MTDO | |
| | HS2_DATA0 | IO2 | |
| | HS2_DATA1 | IO4 | |
| | HS2_DATA2 | MTDI | |
| | HS2_DATA3 | MTCK | |

| Interface | Signal | Pin | Function |
|-----------|--------------------|------------|--|
| Motor PWM | PWM0_OUT0~2 | Any GPIOs* | Three channels of 16-bit timers generate PWM waveforms; each has a pair of output signals. Three fault detection signals. Three event capture signals. Three sync signals. |
| | PWM1_OUT_IN0~2 | | |
| | PWM0_FLT_IN0~2 | | |
| | PWM1_FLT_IN0~2 | | |
| | PWM0_CAP_IN0~2 | | |
| | PWM1_CAP_IN0~2 | | |
| | PWM0_SYNC_IN0~2 | | |
| | PWM1_SYNC_IN0~2 | | |
| LED PWM | ledc_hs_sig_out0~7 | Any GPIOs* | 16 independent channels @80 MHz clock/RTC CLK. Duty accuracy: 16 bits. |
| | ledc_ls_sig_out0~7 | | |
| UART | U0RXD_in | Any GPIOs* | Two UART devices with hardware flow-control and DMA |
| | U0CTS_in | | |
| | U0DSR_in | | |
| | U0TXD_out | | |
| | U0RTS_out | | |
| | U0DTR_out | | |
| | U1RXD_in | | |
| | U1CTS_in | | |
| | U1TXD_out | | |
| | U1RTS_out | | |
| | U2RXD_in | | |
| | U2CTS_in | | |
| | U2TXD_out | | |
| | U2RTS_out | | |
| I2C | I2CEXT0_SCL_in | Any GPIOs* | Two I2C devices in slave or master modes |
| | I2CEXT0_SDA_in | | |
| | I2CEXT1_SCL_in | | |
| | I2CEXT1_SDA_in | | |
| | I2CEXT0_SCL_out | | |
| | I2CEXT0_SDA_out | | |
| | I2CEXT1_SCL_out | | |
| | I2CEXT1_SDA_out | | |

| Interface | Signal | Pin | Function |
|--------------------|--------------------|------------|---|
| I2S | I2S0I_DATA_in0~15 | Any GPIOs* | Stereo input and output from/to the audio codec, and parallel LCD data output |
| | I2S0O_BCK_in | | |
| | I2S0O_WS_in | | |
| | I2S0I_BCK_in | | |
| | I2S0I_WS_in | | |
| | I2S0I_H_SYNC | | |
| | I2S0I_V_SYNC | | |
| | I2S0I_H_ENABLE | | |
| | I2S0O_BCK_out | | |
| | I2S0O_WS_out | | |
| | I2S0I_BCK_out | | |
| | I2S0I_WS_out | | |
| | I2S0O_DATA_out0~23 | | |
| | I2S1I_DATA_in0~15 | | |
| | I2S1O_BCK_in | | |
| | I2S1O_WS_in | | |
| | I2S1I_BCK_in | | |
| | I2S1I_WS_in | | |
| | I2S1I_H_SYNC | | |
| | I2S1I_V_SYNC | | |
| | I2S1I_H_ENABLE | | |
| | I2S1O_BCK_out | | |
| | I2S1O_WS_out | | |
| I2S1I_BCK_out | | | |
| I2S1I_WS_out | | | |
| I2S1O_DATA_out0~23 | | | |
| Remote Controller | RMT_SIG_IN0~7 | Any GPIOs* | Eight channels of IR transmitter and receiver for various waveforms |
| | RMT_SIG_OUT0~7 | | |

| Interface | Signal | Pin | Function |
|---------------------|---------------|------------|---|
| Parallel QSPI | SPIHD | SHD/SD2 | Supports Standard SPI, Dual SPI, and Quad SPI that can be connected to the external flash and SRAM |
| | SPIWP | SWP/SD3 | |
| | SPICS0 | SCS/CMD | |
| | SPICLK | SCK/CLK | |
| | SPIQ | SDO/SD0 | |
| | SPID | SDI/SD1 | |
| | HSPICLK | IO14 | |
| | HSPICS0 | IO15 | |
| | HSPIQ | IO12 | |
| | HSPID | IO13 | |
| | HSPIHD | IO4 | |
| | HSPIWP | IO2 | |
| | VSPICLK | IO18 | |
| | VSPICS0 | IO5 | |
| | VSPIQ | IO19 | |
| | VSPID | IO23 | |
| VSPIHD | IO21 | | |
| VSPIWP | IO22 | | |
| General Purpose SPI | HSPIQ_in/_out | Any GPIOs* | Standard SPI consists of clock, chip-select, MOSI and MISO. These SPIs can be connected to LCD and other external devices. They support the following features: <ul style="list-style-type: none"> • both master and slave modes; • 4 sub-modes of the SPI format transfer that depend on the clock phase (CPHA) and clock polarity (CPOL) control; • CLK frequencies by a divider; • up to 64 bytes of FIFO and DMA. |
| | HSPIQ_in/_out | | |
| | HSPIQ_in/_out | | |
| | HSPIQ_in/_out | | |
| | HSPIQ_in/_out | | |
| | HSPIQ_in/_out | | |
| | HSPIQ_in/_out | | |
| | HSPIQ_in/_out | | |
| | HSPIQ_in/_out | | |
| | HSPIQ_in/_out | | |
| | HSPIQ_in/_out | | |
| JTAG | MTDI | IO12 | JTAG for software debugging |
| | MTCK | IO13 | |
| | MTMS | IO14 | |
| | MTDO | IO15 | |

| Interface | Signal | Pin | Function |
|--------------|------------------|------------|--|
| SDIO Slave | SD_CLK | IO6 | SDIO interface that conforms to the industry standard SDIO 2.0 card specification. |
| | SD_CMD | IO11 | |
| | SD_DATA0 | IO7 | |
| | SD_DATA1 | IO8 | |
| | SD_DATA2 | IO9 | |
| | SD_DATA3 | IO10 | |
| EMAC | EMAC_TX_CLK | IO0 | Ethernet MAC with MII/RMII interface |
| | EMAC_RX_CLK | IO5 | |
| | EMAC_TX_EN | IO21 | |
| | EMAC_TXD0 | IO19 | |
| | EMAC_TXD1 | IO22 | |
| | EMAC_TXD2 | IO14 | |
| | EMAC_TXD3 | IO12 | |
| | EMAC_RX_ER | IO13 | |
| | EMAC_RX_DV | IO27 | |
| | EMAC_RXD0 | IO25 | |
| | EMAC_RXD1 | IO26 | |
| | EMAC_RXD2 | TXD0 | |
| | EMAC_RXD3 | IO15 | |
| | EMAC_CLK_OUT | IO16 | |
| | EMAC_CLK_OUT_180 | IO17 | |
| | EMAC_TX_ER | IO4 | |
| | EMAC_MDC_out | Any GPIOs* | |
| | EMAC_MDI_in | Any GPIOs* | |
| | EMAC_MDO_out | Any GPIOs* | |
| | EMAC_CRS_out | Any GPIOs* | |
| EMAC_COL_out | Any GPIOs* | | |

Note:

- Functions of Motor PWM, LED PWM, UART, I2C, I2S, general purpose SPI and Remote Controller can be configured for any GPIO, except for GPIO6, GPIO7, GPIO8, GPIO9, GPIO10 and GPIO11.
- Items marked as "Any GPIOs*" do not include GPIO16 and GPIO17. Users should note that pins CMD, CLK, SD0 and SD1 are used for connecting the embedded flash, and are not recommended for other uses.

5. Electrical Characteristics

Note:

The specifications in this chapter have been tested under the following general condition: $V_{DD} = 3.3V$, $T_A = 27^{\circ}C$, unless otherwise specified.

5.1 Absolute Maximum Ratings

Table 7: Absolute Maximum Ratings

| Parameter | Symbol | Min | Typ | Max | Unit |
|---|-----------|------------------------|-----|------------------------|-------------|
| Power supply ¹ | VDD | 2.3 | 3.3 | 3.6 | V |
| Minimum current delivered by power supply | I_{VDD} | 0.5 | - | - | A |
| Input low voltage | V_{IL} | -0.3 | - | $0.25 \times V_{IO}^2$ | V |
| Input high voltage | V_{IH} | $0.75 \times V_{IO}^2$ | - | $V_{IO}^2 + 0.3$ | V |
| Input leakage current | I_{IL} | - | - | 50 | nA |
| Input pin capacitance | C_{pad} | - | - | 2 | pF |
| Output low voltage | V_{OL} | - | - | $0.1 \times V_{IO}^2$ | V |
| Output high voltage | V_{OH} | $0.8 \times V_{IO}^2$ | - | - | V |
| Maximum output drive capability | I_{MAX} | - | - | 40 | mA |
| Storage temperature range | T_{STR} | -40 | - | 85 | $^{\circ}C$ |
| Operating temperature range | T_{OPR} | -40 | - | 85 | $^{\circ}C$ |

1. The power supplies include VDDA, VDD3P3, VDD3P3_RTC, VDD3P3_CPU, VDD_SDIO. The VDD_SDIO also supports 1.8V mode.
2. V_{IO} is the power supply for a specific pad. More details can be found in the [ESP32 Datasheet](#), Appendix IO_MUX. For example, the power supply for SD_CLK is the VDD_SDIO.

5.2 Wi-Fi Radio

Table 8: Wi-Fi Radio Characteristics

| Description | Min | Typical | Max | Unit |
|----------------------------------|------|---------|------|----------|
| Input frequency | 2412 | - | 2484 | MHz |
| Output impedance | - | 50 | - | Ω |
| Input reflection | - | - | -10 | dB |
| Tx power | | | | |
| Output power of PA for 72.2 Mbps | 13 | 14 | 15 | dBm |
| Output power of PA for 11b mode | 19.5 | 20 | 20.5 | dBm |
| Sensitivity | | | | |
| DSSS, 1 Mbps | - | -98 | - | dBm |
| CCK, 11 Mbps | - | -91 | - | dBm |
| OFDM, 6 Mbps | - | -93 | - | dBm |

| Description | Min | Typical | Max | Unit |
|----------------------------|-----|---------|-----|------|
| OFDM, 54 Mbps | - | -75 | - | dBm |
| HT20, MCS0 | - | -93 | - | dBm |
| HT20, MCS7 | - | -73 | - | dBm |
| HT40, MCS0 | - | -90 | - | dBm |
| HT40, MCS7 | - | -70 | - | dBm |
| MCS32 | - | -89 | - | dBm |
| Adjacent channel rejection | | | | |
| OFDM, 6 Mbps | - | 37 | - | dB |
| OFDM, 54 Mbps | - | 21 | - | dB |
| HT20, MCS0 | - | 37 | - | dB |
| HT20, MCS7 | - | 20 | - | dB |

5.3 Bluetooth LE Radio

5.3.1 Receiver

Table 9: Receiver Characteristics – BLE

| Parameter | Conditions | Min | Typ | Max | Unit |
|------------------------------------|---------------------|-----|-----|-----|------|
| Sensitivity @30.8% PER | - | - | -97 | - | dBm |
| Maximum received signal @30.8% PER | - | 0 | - | - | dBm |
| Co-channel C/I | - | - | +10 | - | dB |
| Adjacent channel selectivity C/I | F = F0 + 1 MHz | - | -5 | - | dB |
| | F = F0 - 1 MHz | - | -5 | - | dB |
| | F = F0 + 2 MHz | - | -25 | - | dB |
| | F = F0 - 2 MHz | - | -35 | - | dB |
| | F = F0 + 3 MHz | - | -25 | - | dB |
| | F = F0 - 3 MHz | - | -45 | - | dB |
| Out-of-band blocking performance | 30 MHz ~ 2000 MHz | -10 | - | - | dBm |
| | 2000 MHz ~ 2400 MHz | -27 | - | - | dBm |
| | 2500 MHz ~ 3000 MHz | -27 | - | - | dBm |
| | 3000 MHz ~ 12.5 GHz | -10 | - | - | dBm |
| Intermodulation | - | -36 | - | - | dBm |

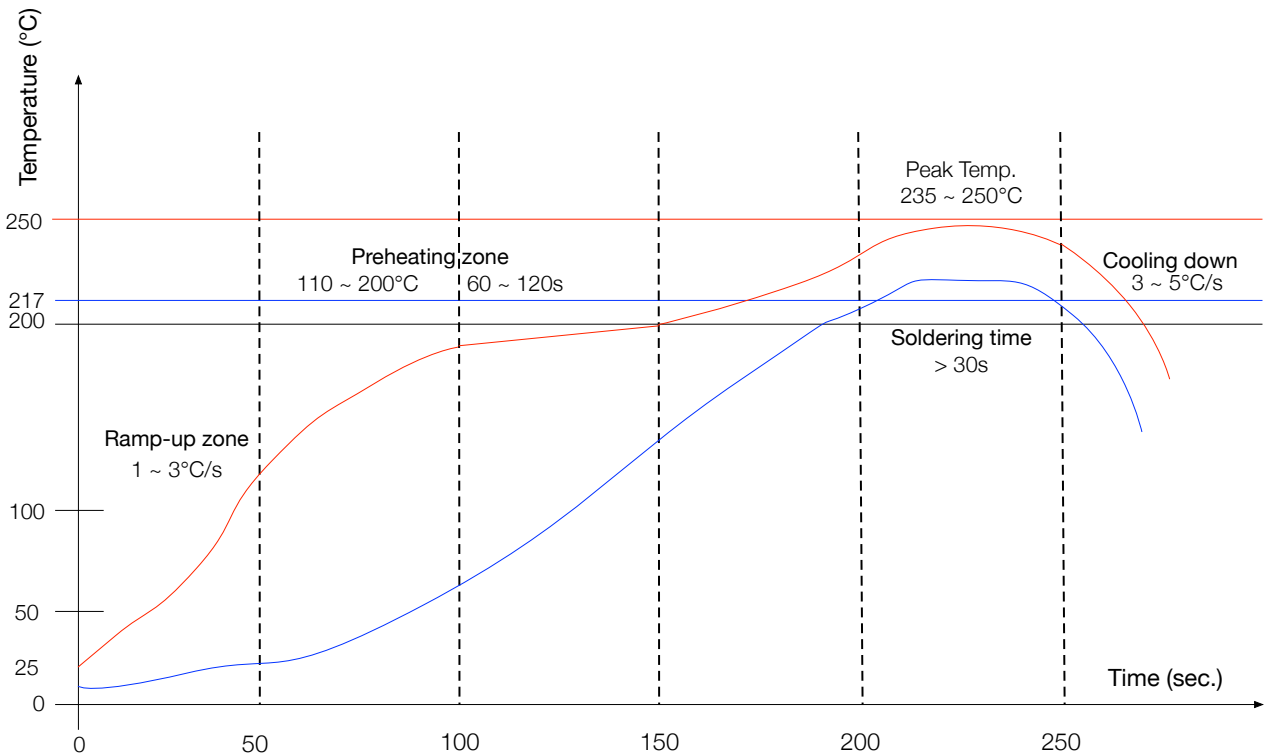
5.3.2 Transmit

Table 10: Transmit Characteristics - BLE

| Parameter | Conditions | Min | Typ | Max | Unit |
|------------------------|------------|-----|-----|-----|------|
| RF transmit power | - | - | 0 | - | dBm |
| Gain control step | - | - | ±3 | - | dBm |
| RF power control range | - | -12 | - | +12 | dBm |

| Parameter | Conditions | Min | Typ | Max | Unit |
|-----------------------------------|------------------|-----|-------|-----|----------------|
| Adjacent channel transmit power | F = F0 + 1 MHz | - | -14.6 | - | dBm |
| | F = F0 - 1 MHz | - | -12.7 | - | dBm |
| | F = F0 + 2 MHz | - | -44.3 | - | dBm |
| | F = F0 - 2 MHz | - | -38.7 | - | dBm |
| | F = F0 + 3 MHz | - | -49.2 | - | dBm |
| | F = F0 - 3 MHz | - | -44.7 | - | dBm |
| | F = F0 + > 3 MHz | - | -50 | - | dBm |
| | F = F0 - > 3 MHz | - | -50 | - | dBm |
| Δf_{1avg} | - | - | - | 265 | kHz |
| Δf_{2max} | - | 247 | - | - | kHz |
| $\Delta f_{2avg}/\Delta f_{1avg}$ | - | - | -0.92 | - | - |
| ICFT | - | - | -10 | - | kHz |
| Drift rate | - | - | 0.7 | - | kHz/50 μ s |
| Drift | - | - | 2 | - | kHz |

5.4 Reflow Profile



Ramp-up zone (升温区): Temp. <150°C, Time 60 ~ 90s, Ramp-up rate 1 ~ 3°C/s.
 Preheating zone (预热恒温区): Temp. 150 ~ 200°C, Time 60 ~ 120s, Ramp-up rate 0.3 ~ 0.8°C/s.
 Reflow soldering zone (回流焊接区): Peak Temp. 235 ~ 250°C (<245°C recommended), Time 30 ~ 70s.
 Cooling down zone (冷却区): Temp. 217 ~ 170°C, Ramp-down rate 3 ~ 5°C/s.
 Sn&Ag&Cu Lead-free solder (SAC305)/焊料为锡银铜合金无铅焊料

Figure 2: Reflow Profile

6. Schematics

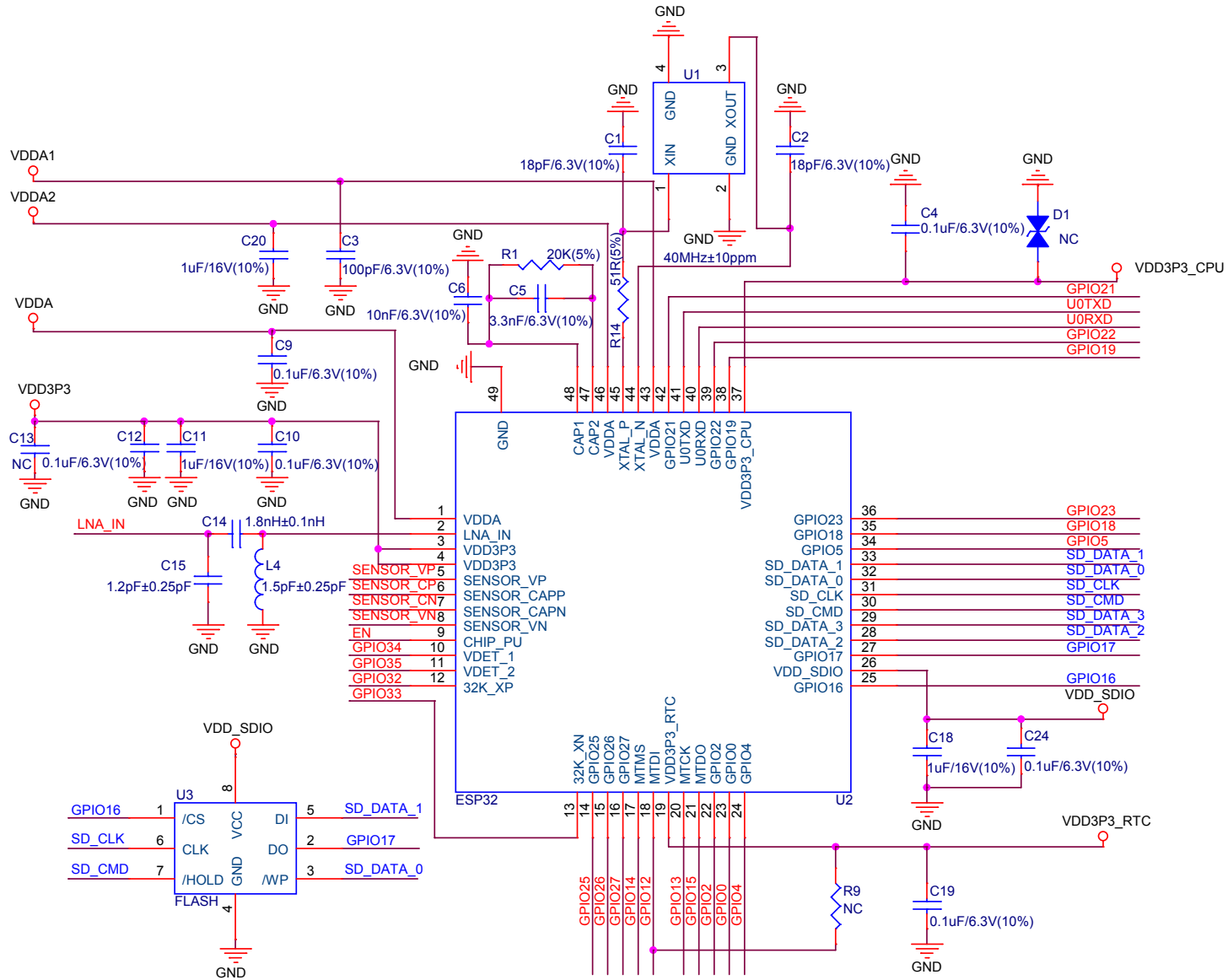


Figure 3: ESP32-PICO-D4 Module Schematics

7. Peripheral Schematics

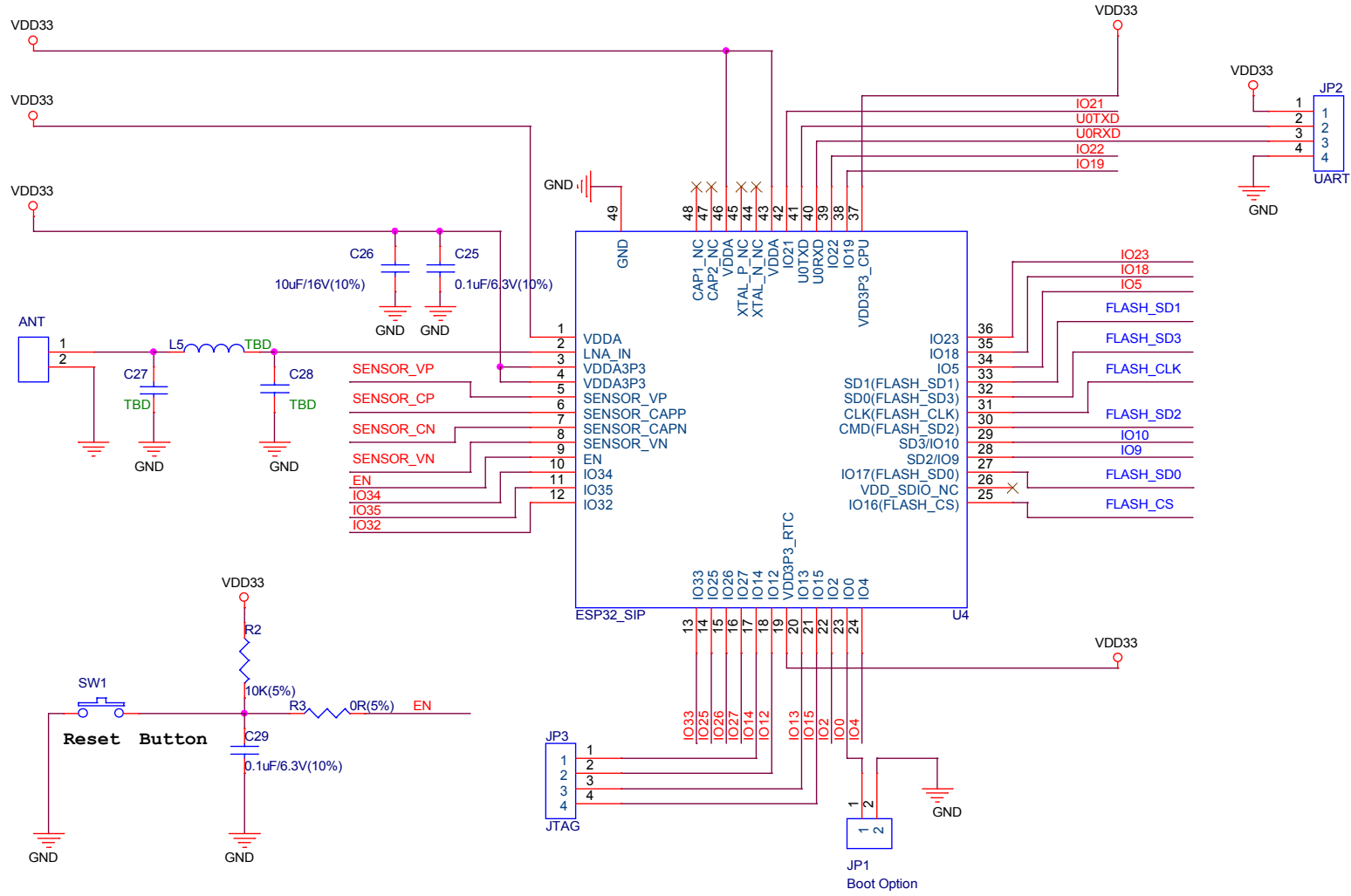
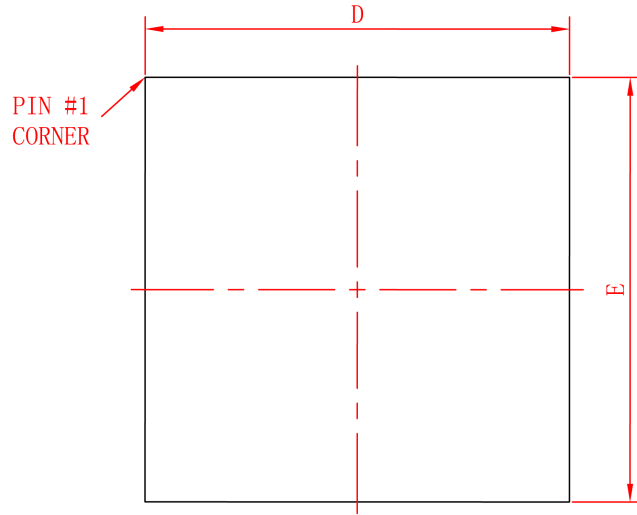
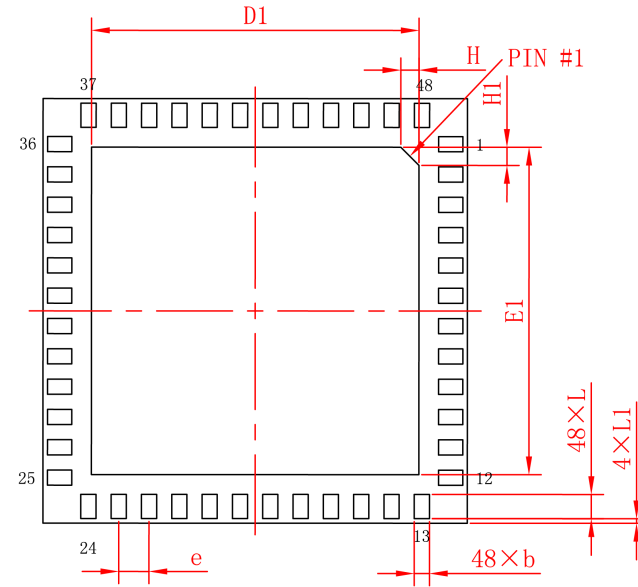


Figure 4: ESP32-PICO-D4 Module Peripheral Schematics

8. Package Information

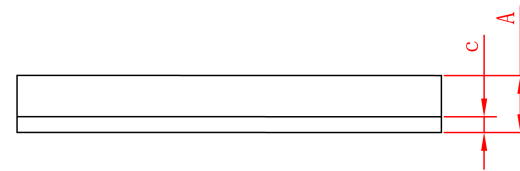


Top View



Bottom View

| symbol | Dimension in mm | | | Dimension in inch | | |
|--------|-----------------|-------|-------|-------------------|-------|-------|
| | MIN | NOM | MAX | MIN | NOM | MAX |
| A | 0.840 | 0.940 | 1.040 | 0.033 | 0.037 | 0.041 |
| c | 0.220 | 0.260 | 0.300 | 0.009 | 0.010 | 0.012 |
| D | 6.900 | 7.000 | 7.100 | 0.272 | 0.276 | 0.280 |
| E | 6.900 | 7.000 | 7.100 | 0.272 | 0.276 | 0.280 |
| D1 | 5.300 | 5.400 | 5.500 | 0.209 | 0.213 | 0.217 |
| E1 | 5.300 | 5.400 | 5.500 | 0.209 | 0.213 | 0.217 |
| H | --- | 0.300 | --- | --- | 0.012 | --- |
| H1 | --- | 0.300 | --- | --- | 0.012 | --- |
| L | 0.325 | 0.400 | 0.475 | 0.013 | 0.016 | 0.019 |
| L1 | 0.000 | 0.075 | 0.150 | 0.000 | 0.003 | 0.006 |
| e | --- | 0.500 | --- | --- | 0.020 | --- |
| b | 0.200 | 0.250 | 0.300 | 0.008 | 0.010 | 0.012 |



Side View

Figure 5: ESP32-PICO-D4 Package

9. Learning Resources

9.1 Must-Read Documents

The following link provides related documents of ESP32.

- [ESP32 Datasheet](#)
This document provides introduction to the specifications of the ESP32 hardware, including overview, pin definitions, functional description, peripheral interface, electrical characteristics, etc.
- [ESP32 Technical Reference Manual](#)
The manual provides detailed information on how to use the ESP32 memory and peripherals.
- [ESP32 Hardware Resources](#)
The zip files include the schematics, PCB layout, Gerber and BOM list of ESP32 modules and development boards.
- [ESP32 Hardware Design Guidelines](#)
The guidelines outline recommended design practices when developing standalone or add-on systems based on the ESP32 series of products, including ESP32, the ESP-WROOM-32 module, and ESP32-DevKitC—the development board.
- [ESP32 AT Instruction Set and Examples](#)
This document introduces the ESP32 AT commands, explains how to use them and provides examples of several common AT commands.

9.2 Must-Have Resources

Here are the ESP32-related must-have resources.

- [ESP32 BBS](#)
This is an Engineer-to-Engineer (E2E) Community for ESP32 where you can post questions, share knowledge, explore ideas, and help solve problems with fellow engineers.
- [ESP32 Github](#)
ESP32 development projects are freely distributed under Espressif's MIT license on Github. It is established to help developers get started with ESP32 and foster innovation and the growth of general knowledge about the hardware and software surrounding ESP32 devices.
- [ESP32 Tools](#)
This is a web-page where users can download ESP32 Flash Download Tools and the zip file "ESP32 Certification and Test".
- [ESP32 IDF](#)
This web-page links users to the official IoT development framework for ESP32.
- [ESP32 Resources](#)
This webpage provides the links to all the available ESP32 documents, SDK and tools.