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STATISTICAL IMMERSIONS BETWEEN STATISTICAL MANIFOLDS OF CONSTANT CURVATURE

CHOL RIM MIN, SONG OK CHOE, YUN HO AN

ABSTRACT. The condition for the curvature of a statistical manifold to admit a kind of standard hypersurface is given. We study the statistical hypersurfces of some types of the statistical manifolds (M, ∇, g) , which enable $(M, \nabla^{(\alpha)}, g), \forall \alpha \in \mathbf{R}$ to admit the structure of a constant curvature.

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1. INTRODUCTION

Since Lauritzen introduced the notation of statistical manifolds in 1987 [5], the geometry of statistical manifolds has been developed in close relations with affine differential geometry and Hessian geometry as well as information geometry (see, for example, [2,4,8]). In this paper we study the hypersurface of statistical manifolds.

Let *M* be an *n*-dimensional manifold, ∇ a torsion-free affine connection on *M*, *g* a Riemannian metric on *M*, and *R* a curvature tensor field on *M*. We denote by *TM* the set of vector fields on *M*, and by $TM^{(r,s)}$ the set of tensor fields of type (r,s) on *M*.

Definition 1.1. A pair (∇, g) is called a *statistical structure* on M if (M, ∇, g) is a statistical manifold, that is, ∇ is a torsion-free affine connection and for all $X, Y, Z \in T(M)$, $(\nabla_X g)(Y, Z) = (\nabla_Y g)(X, Z)$.

Let ∇° be a Levi-Civita connection of g. Certainly, a pair (∇°, g) is a statistical structure, which is called a Riemannian statistical structure or a trivial statistical structure (see [3]). On the other hand, the statistical structure is also introduced from affine differential geometry which was proposed by Blasche (see [6]). Recently the relation between statistical structures and Hessian geometry has been studied (see [3,7]).

For all $\alpha \in \mathbf{R}$, a connection $\nabla^{(\alpha)}$ is defined by

$$\nabla^{(\alpha)} = \frac{1+\alpha}{2}\nabla + \frac{1-\alpha}{2}\nabla^*$$

Coresponding author Chol Rim Min, e-mail: mincholrim@yahoo.com.

where ∇ and ∇^* are dual connections on *M*. We study a statistical hypersurface of a statistical manifold (M, ∇, g) which enables $(M, \nabla^{(\alpha)}, g), \forall \alpha \in \mathbf{R}$ to admit the structure of a constant curvature.

In section 3, a statistical manifold (M, ∇, g) , which enables $(M, \nabla^{(\alpha)}, g), \forall \alpha \in \mathbf{R}$ to admit the structure of a constant curvature, is considered. In section 4, we study characteristics of statistical immersions between statistical manifolds (M, ∇, g) which enable $(M, \nabla^{(\alpha)}, g), \forall \alpha \in \mathbf{R}$ to admit the structure of a constant curvature.

2. Preliminaries

A statistical manifold (M, ∇, g) is said to be of constant curvature $k \in \mathbf{R}$ if

$$R(X,Y)Z = k\{g(Y,Z)X - g(X,Z)Y\}, \forall X,Y,Z \in TM$$
(2.1)

holds, where *R* is the curvature tensor field of ∇ . A pair (∇, g) is called a Hessian structure if a statistical manifold (M, ∇, g) is of constant curvature 0.

A Riemannian metric g on a flat manifold (M, g) is called a Hessian metric if g can be locally expressed by

$$g = Dd\varphi$$

that is,

$$g_{ij} = \frac{\partial^2 \varphi}{\partial x^i \partial x^j}$$

where $\{x^1, \dots, x^n\}$ is an affine coordinate system with respect to ∇ . Then (M, ∇, g) is called a Hessian manifold (see [7]).

Let (M, ∇, g) be a Hessian manifold and $K(X, Y) := \nabla_X Y - \nabla_X^\circ Y$ be the difference tensor between the Levi-Civita connection ∇° of g and ∇ . A covariant differential of differential tensor K is called a Hessian curvature tensor for (∇, g) . A Hessian manifold (M, ∇, g) is said to be of constant Hessian curvature $c \in \mathbf{R}$ if

$$(\nabla_X K)(Y,Z) = -\frac{c}{2} \{g(X,Y)Z + g(X,Z)Y\}, \forall X,Y,Z \in TM$$

holds (see [7]).

Example 2.1. ([3])

Let (H, \tilde{g}) be the upper half space:

$$H := \left\{ y = (y^1, \cdots, y^{n+1})^T \in \mathbf{R}^{n+1} \middle| y^{n+1} > 0 \right\}, \tilde{g} := (y^{n+1})^{-2} \sum_{i=1}^{n+1} dy^i dy^i.$$

We define an affine connection $\tilde{\nabla}$ on *H* by the following relations:

$$\begin{split} \tilde{\nabla}_{\frac{\partial}{\partial y^{n+1}}} \frac{\partial}{\partial y^{n+1}} &= (y^{n+1})^{-1} \frac{\partial}{\partial y^{n+1}}, \tilde{\nabla}_{\frac{\partial}{\partial y^i}} \frac{\partial}{\partial y^j} = 2\delta_{ij} (y^{n+1})^{-1} \frac{\partial}{\partial y^{n+1}}, \\ \tilde{\nabla}_{\frac{\partial}{\partial y^i}} \frac{\partial}{\partial y^{n+1}} &= \tilde{\nabla}_{\frac{\partial}{\partial y^{n+1}}} \frac{\partial}{\partial y^j} = 0, \end{split}$$

where $i, j = 1, \dots, n$. Then $(H, \tilde{\nabla}, \tilde{g})$ is a Hessian manifold of constant Hessian curvature 4.

Let $(\tilde{M}, \tilde{\nabla}, \tilde{g})$ be a statistical manifold and $f : M \to \tilde{M}$ be an immersion. We define g and ∇ on M by

$$g = f^* \tilde{g}, \quad g(\nabla_X Y, Z) = \tilde{g}(\tilde{\nabla}_X f_* Y, f_* Z), \quad \forall X, Y, Z \in TM.$$

Then the pair (∇, g) is a statistical structure on *M*, which is called the one by *f* from $(\tilde{\nabla}, \tilde{g})$ (see [3]).

Let (M, ∇, g) and $(\tilde{M}, \tilde{\nabla}, \tilde{g})$ be two statistical manifolds. An immersion $f : M \to \tilde{M}$ is called a statistical immersion if (∇, g) coincides with the induced statistical structure (see [3]).

Let $f : (M, \nabla, g) \to (\tilde{M}, \tilde{\nabla}, \tilde{g})$ be a statistical immersion of codimension one, and ξ a unit normal vector field of f. Then we define $h, h^* \in TM^{(0,2)}, \tau, \tau^* \in TM^*$ and $A, A^* \in TM^{(1,1)}$ by the following Gauss and Weingarten formulae:

$$\tilde{\nabla}_X f_* Y = f_* \nabla_X Y + h(X, Y) \xi, \quad \tilde{\nabla}_X \xi = -f_* A^* X + \tau^*(X) \xi,$$

 $\tilde{\nabla}_X^* f_* Y = f_* \nabla_X^* Y + h^* (X, Y) \xi, \quad \tilde{\nabla}_X^* \xi = -f_* A X + \tau(X) \xi, \quad \forall X, Y \in TM,$

where $\tilde{\nabla}^*$ is the dual connection of $\tilde{\nabla}$ with respect to \tilde{g} .

In addition, we define $II \in TM^{(0,2)}$ and $S \in TM^{(1,1)}$ by using the Riemannian Gauss and Weingarten formulae:

$$\tilde{\nabla}_X^* f_* Y = f_* \nabla_X^* Y + II(X, Y)\xi, \quad \tilde{\nabla}_X^* \xi = -f_* SX.$$

For more details on the Gauss, Codazzi and Ricci formulae on statistical hypersurfaces, we refer to [3].

3. The condition that a statistical manifold $(M, \nabla^{(\alpha)}, g)$ is of constant curvature for any $\alpha \in \mathbf{R}$

In this section we consider a condition that a statistical manifold $(M, \nabla^{(\alpha)}, g)$ is of constant curvature for any $\alpha \in \mathbf{R}$.

Theorem 3.1. A statistical manifold $(M, \nabla^{(\alpha)}, g)$ is of constant curvature for any $\alpha \in \mathbf{R}$ iff there exist $\alpha_1, \alpha_2 \in \mathbf{R}(|\alpha_1| \neq |\alpha_2|)$ such that statistical manifolds $(M, \nabla^{(\alpha_1)}, g)$ and $(M, \nabla^{(\alpha_2)}, g)$ are of constant curvature.

Proof. Necessity is obvious. We find sufficiency. Without loss of generality, we assume $\alpha_1 \neq 0$. Then since

$$\nabla^{(\alpha)} = \frac{\alpha_1 + \alpha}{2\alpha_1} \nabla^{(\alpha_1)} + \frac{\alpha_1 - \alpha}{2\alpha_1} \nabla^{(-\alpha_1)}$$

holds for all $\alpha \in \mathbf{R}$, the following relation

$$R^{(\alpha)}(X,Y)Z = \frac{\alpha_1 + \alpha}{2\alpha_1} R^{(\alpha_1)}(X,Y)Z + \frac{\alpha_1 - \alpha}{2\alpha_1} R^{(-\alpha_1)}(X,Y)Z + \frac{\alpha_1^2 - \alpha^2}{4\alpha_1^2} [K(Y,K(Z,X)) - K(X,K(Y,Z))]$$

holds, where $K(X, Y) := \nabla_X Y - \nabla_X^{\circ} Y$ is the difference tensor field of a statistical manifold.

From the relations

$$R^{(\alpha_1)}(X,Y)Z = k_1 \{ g(Y,Z)X - g(X,Z)Y \},\$$

$$R^{(\alpha_2)}(X,Y)Z = k_2\{g(Y,Z)X - g(X,Z)Y\},\$$

the relation

$$R^{(\alpha)}(X,Y)Z = \frac{k_2\alpha_1^2 - k_1\alpha_2^2 + (k_1 - k_2)\alpha^2}{\alpha_1^2 - \alpha_2^2} \{g(Y,Z)X - g(X,Z)Y\}$$

holds, that is, a statistical manifold $(M, \nabla^{(\alpha)}, g)$ is of constant curvature $\frac{k_2 \alpha_1^2 - k_1 \alpha_2^2 + (k_1 - k_2) \alpha^2}{\alpha_1^2 - \alpha_2^2}$. **Example 3.1.** Let (M, g) be a family of normal distributions:

$$M := \left\{ p(x,\theta) \left| p(x,\theta) = \frac{1}{\sqrt{2\pi(\theta^2)^2}} \exp\left\{ -\frac{1}{2(\theta^2)^2} (x-\theta^1)^2 \right\} \right\}, \quad g := 2(\theta^2)^{-2} \sum d\theta^i d\theta^i,$$
$$x \in \mathbf{R}, \quad \theta^1 \in \mathbf{R}, \quad \theta^2 > 0.$$

We define an α – connection by the following relations:

$$\begin{split} \nabla^{(\alpha)}_{\frac{\partial}{\partial \theta^1}} \frac{\partial}{\partial \theta^1} &= (-1+2\alpha)(\theta^2)^{-1} \frac{\partial}{\partial \theta^2}, \quad \nabla^{(\alpha)}_{\frac{\partial}{\partial \theta^2}} \frac{\partial}{\partial \theta^2} &= (1+\alpha)(\theta^2)^{-1} \frac{\partial}{\partial \theta^2}, \\ \nabla^{(\alpha)}_{\frac{\partial}{\partial \theta^1}} \frac{\partial}{\partial \theta^2} &= \nabla^{(\alpha)}_{\frac{\partial}{\partial \theta^2}} \frac{\partial}{\partial \theta^1} &= 0. \end{split}$$

Then the statistical manifold $(M, \nabla^{(0)}, g)$ is of constant curvature $(-\frac{1}{2})$, and the statistical manifold $(M, \nabla^{(1)}, g)$ is of constant curvature 0. Hence for all $\alpha \in \mathbf{R}$, the statistical manifold $(M, \nabla^{(\alpha)}, g)$ is of constant curvature $\frac{\alpha^2 - 1}{2}$.

Example 3.2. Let (M, g) be a family of random walk distributions ([1]):

$$M := \left\{ p(x;\theta^{1},\theta^{2}) \left| p(x;\theta^{1},\theta^{2}) = \sqrt{\frac{\theta^{2}}{2\pi x}} \exp\left\{ -\frac{\theta^{2}x}{2} + \frac{\theta^{2}}{\theta^{1}} - \frac{\theta^{2}}{2(\theta^{1})^{2}x} \right\}, \quad x,\mu,\lambda > 0 \right\},$$
$$g := \frac{\theta^{2}}{(\theta^{1})^{3}} (d\theta^{1})^{2} + \frac{1}{2(\theta^{2})^{2}} (d\theta^{2})^{2}.$$

We define an α – connection by the following relations:

$$\begin{split} \nabla^{(\alpha)}_{\frac{\partial}{\partial\theta^1}} \frac{\partial}{\partial\theta^1} &= \frac{-3(1+\alpha)}{2} (\theta^1)^{-1} \frac{\partial}{\partial\theta^1} + (-1+\alpha)(\theta^1)^{-3}(\theta^2)^2 \frac{\partial}{\partial\theta^2},\\ \nabla^{(\alpha)}_{\frac{\partial}{\partial\theta^1}} \frac{\partial}{\partial\theta^2} &= \nabla^{(\alpha)}_{\frac{\partial}{\partial\theta^2}} \frac{\partial}{\partial\theta^1} = \frac{(1+\alpha)}{2} (\theta^2)^{-1} \frac{\partial}{\partial\theta^1},\\ \nabla^{(\alpha)}_{\frac{\partial}{\partial\theta^2}} \frac{\partial}{\partial\theta^2} &= (-1+\alpha)(\theta^2)^{-1} \frac{\partial}{\partial\theta^2}. \end{split}$$

Then the statistical manifold $(M, \nabla^{(0)}, g)$ is of constant curvature $(-\frac{1}{2})$, and the statistical manifold $(M, \nabla^{(1)}, g)$ is of constant curvature 0. Hence for all $\alpha \in \mathbf{R}$, the statistical manifold $(M, \nabla^{(\alpha)}, g)$ is of constant curvature $\frac{\alpha^2 - 1}{2}$. Theorem 3.1 implies the following fact.

Corollary 3.1. If there exist $\alpha_1, \alpha_2 \in \mathbf{R}(|\alpha_1| \neq |\alpha_2|)$ such that the statistical manifold $(M, \nabla^{(\alpha_1)}, g)$ is of constant curvature k_1 and the statistical manifold $(M, \nabla^{(\alpha_2)}, g)$ is of constant curvature k_2 , and $k_1 \neq k_2$, then for $\alpha \in \mathbf{R}$ satisfying that $\alpha^2 = (k_2\alpha_1^2 - k_1\alpha_2^2)/(k_2 - k_1)$, the statistical manifold $(M, \nabla^{(\alpha)}, g)$ is flat.

Example 3.3. $k_1 = -1/2$, $k_2 = 0$, $\alpha_1 = 0$ and $\alpha_2 = 1$ hold in example 3.1 and example 3.2. Hence for $\alpha \in \mathbf{R}$ satisfying that $\alpha^2 = 1$, the statistical manifold $(M, \nabla^{(\alpha)}, g)$ is flat.

Theorem 3.2. *If the Hessian manifold* (M, ∇, g) *is of constant Hessian curvature, then for all* $\alpha \in \mathbf{R}$ *, the statistical manifold* $(M, \nabla^{(\alpha)}, g)$ *is of constant curvature.*

Proof. If the Hessian manifold (M, ∇, g) is of constant Hessian curvature, then for all $X, Y, Z \in TM$,

$$(\nabla K)(Y,Z;X) = -\frac{c}{2} \{g(X,Y)Z + g(X,Z)Y\}, c \in \mathbf{R}$$

holds. On the other hand, the curvature tensor R° of Levi-Civita connection ∇° is written by

$$R^{\circ}(X,Y)Z = R(X,Y)Z - (\nabla K)(Y,Z;X) + (\nabla K)(Z,X;Y) +K(X,K(Y,Z)) - K(Y,K(Z,X)),$$

where *R* is the curvature tensor of ∇ and $K(X, Y) = \nabla_X Y - \nabla_X^{\circ} Y$ is difference tensor. Then

$$(\nabla K)(Y,Z;X) - (\nabla K)(Z,X;Y) = 2\{K(X,K(Y,Z)) - K(Y,K(Z,X))\} + \frac{1}{2}\{R(X,Y)Z - R^*(X,Y)Z\}$$

implies

$$R^{\circ}(X,Y)Z = -\frac{c}{4}\{g(Y,Z)X - g(X,Z)Y\},\$$

where R^* is curvature tensor of dual connection ∇^* , that is, the statistical manifold (M, ∇°, g) is of constant curvature. On the other hand, the statistical manifold (M, ∇, g) is flat, that is, constant curvature 0. Therefore we finish the proof of theorem by applying Theorem 3.1.

Hitherto we found some conditions that for any $\alpha \in \mathbf{R}$, the statistical manifold $(M, \nabla^{(\alpha)}, g)$ is of constant curvature.

4. THE HYPERSURFACES OF STATISTICAL MANIFOLDS OF CONSTANT CURVATURE

We consider statistical hypersurfaces of some type of statistical manifolds, which enable for any $\alpha \in \mathbf{R}$ a statistical manifold $(M, \nabla^{(\alpha)}, g)$ to be of constant curvature.

Theorem 4.1. Let (M, ∇, g) be a trivial statistical manifold of constant curvature k, $(\tilde{M}, \tilde{\nabla}, \tilde{g})$ a statistical manifold of constant curvature \tilde{k} with a Riemannian manifold of constant curvature

 $\tilde{k} \ (\neq \tilde{k}) \ (\tilde{M}, \tilde{\nabla}^{\circ}, \tilde{g})$, and $f : M \to \tilde{M}$ a statistical immersion of codimension one. Then $f : M \to \tilde{M}$ is equiaffine, that is, τ^* vanishes.

Proof. If $(\tilde{M}, \tilde{\nabla}, \tilde{g})$ is a statistical manifold of constant curvature \tilde{k} with a Riemannian manifold of constant curvature $\overset{\circ}{\tilde{k}} (\neq \tilde{k}) (\tilde{M}, \tilde{\nabla}^{\circ}, \tilde{g})$, the following equation

$$(\tilde{\nabla}_X \tilde{K})(f_*Y, f_*Z) - (\tilde{\nabla}_Y \tilde{K})(f_*X, f_*Z)$$

= 2{ $\tilde{R}(f_*X, f_*Y)f_*Z - \tilde{R}^\circ(f_*X, f_*Y)f_*Z$ }
= 2($\tilde{k} - \overset{\circ}{\tilde{k}}$){ $\tilde{g}(f_*Y, f_*Z)f_*X - \tilde{g}(f_*X, f_*Z)f_*Y$ } (4.1)

holds by Eq.(2.2) and Eq.(2.3) in [3]. By above equation and equation Eq.(3.6) in [3], we have

$$-2(\tilde{k} - \hat{\tilde{k}})\{g(Y,Z)X - g(X,Z)Y\} = (\nabla_X K)(Y,Z) - (\nabla_Y K)(X,Z) -b(Y,Z)A^*X + b(X,Z)A^*Y + h(X,Z)B^*Y - h(Y,Z)B^*X 0 = (\nabla_X b)(Y,Z) - (\nabla_Y b)(X,Z) + \tau^*(X)b(Y,Z) - \tau^*(Y)b(X,Z) -\tau^*(Y)h(X,Z) + \tau^*(X)h(Y,Z) 0 = -\tau^*(Y)A^*X + -\tau^*(X)A^*Y - (\nabla_X B^*)Y + (\nabla_Y B^*)X + \tau^*(X)B^*Y - \tau^*(Y)B^*X (4.2)$$

$$0 = -h(X, B^*Y) + h(Y, B^*X) + (\nabla_X \tau^*)(Y) - (\nabla_Y \tau^*)(X) + b(Y, A^*X) - b(X, A^*Y).$$

By K = 0, $B^* = A^* - S$ and Gauss equation (3.3)₁ in [3], from Eq.(4.2)₁, we have

0

$$\begin{aligned} -2(\tilde{k} - \tilde{k})\{g(Y,Z)X - g(X,Z)Y\} &= -b(Y,Z)A^*X + b(X,Z)A^*Y \\ &+ h(X,Z)A^*Y - h(X,Z)SY - h(Y,Z)A^*X + h(Y,Z)SX \\ &= -b(Y,Z)A^*X + b(X,Z)A^*Y - h(X,Z)SY + h(Y,Z)SX + \tilde{R}(X,Y)Z - R(X,Y)Z. \end{aligned}$$

By b = h - II, $B^* = A^* - S$ and Riemannian Gauss equation (3.5)₁ in [3], we have

$$\begin{split} &-2(\tilde{k}-\tilde{k})\{g(Y,Z)X-g(X,Z)Y\}\\ &=-h(Y,Z)A^*X+II(Y,Z)A^*X+h(X,Z)A^*Y-II(X,Z)A^*Y\\ &-h(X,Z)SY+h(Y,Z)SX+\tilde{R}(X,Y)Z-R(X,Y)Z\\ &=-h(Y,Z)B^*X+h(X,Z)B^*Y+II(Y,Z)B^*X+II(Y,Z)SX\\ &-II(X,Z)B^*Y-II(X,Z)SY+\tilde{R}(X,Y)Z-R(X,Y)Z\\ &=-b(Y,Z)B^*X+b(X,Z)B^*Y+R^\circ(X,Y)Z-\tilde{R}^\circ(X,Y)Z+\tilde{R}(X,Y)Z-R(X,Y)Z. \end{split}$$

Since (M, ∇, g) is Riemannian manifold, clearly $R^{\circ}(X, Y)Z = R(X, Y)Z$. Hence we have

$$0 = (\tilde{k} - \tilde{\tilde{k}}) \{ g(Y, Z) X - g(X, Z) Y \} - b(Y, Z) B^* X + b(X, Z) B^* Y.$$

And since b(Y, Z) = g(BY, Z), b(X, Z) = g(BX, Z), from above equation we have

$$0 = (\tilde{k} - \tilde{k})\{g(Y, Z)X - g(X, Z)Y\} - g(BY, Z)B^*X + g(BX, Z)B^*Y.$$
From Eq.(4.2)₃, $B^* = A^* - S$ and Codazzi equation on A we get
$$(4.3)$$

$$0 = -\tau^{*}(Y)A^{*}X + \tau^{*}(X)A^{*}Y - (\nabla_{X}A^{*})Y + (\nabla_{X}S)Y + (\nabla_{Y}A^{*})X - (\nabla_{Y}S)X + \tau^{*}(X)B^{*}Y - \tau^{*}(Y)B^{*}X = (\nabla_{X}S)Y - (\nabla_{Y}S)X + \tau^{*}(X)B^{*}Y - \tau^{*}(Y)B^{*}X$$

and by $\nabla = \nabla^{\circ}$ and Codazzi equation on *S*, we also get

0

$$0 = \tau^*(X)B^*Y - \tau^*(Y)B^*X.$$
(4.4)

From Eq.(4.2)₄, $B^* = A^* - S$ and Ricci equation we have

$$b(X, B^*Y) - b(Y, B^*X) = 0,$$

and since $b(X, B^*Y) = g(BX, B^*Y)$ and $b(Y, B^*X) = g(BY, B^*X)$, we have $g(BX, B^*Y) - g(BY, B^*X) = 0.$

Since
$$g(BX, B^*Y) = g(B^*Y, BX) = b^*(BX, Y) = g(B^*BX, Y)$$
, we have

$$0 = -g([B, B^*]X, Y).$$
(4.5)

From Eq.(4.5), *B* and *B*^{*} are simultaneously diagonalizable. In the case that *B*^{*} is of the form $\lambda^* I$, we see easily that τ^* vanishes from Eq.(4.4) if

 $\lambda^* \neq 0$ and $\hat{\tilde{k}} = \tilde{k}$ from Eq.(4.3) otherwise. In the case that B^* is not of the form $\lambda^* I$, there are λ_1^*, λ_2^* with $\lambda_1^* \neq \lambda_2^*$ such that $B^* X_j = \lambda_j^* X_j$, where $g(X_i, X_j) = \delta_{ij}$, i, j = 1, 2. Besides there are λ_1, λ_2 such that $BX_j = \lambda_j X_j$. Eq.(4.3) implies that

$$(\tilde{k} - \tilde{k})\{g(X_j, Z)X_i - g(X_i, Z)X_j\} + \lambda_j\lambda_i^*g(X_j, Z)X_i - \lambda_i\lambda_j^*g(X_i, Z)X_j$$
$$= (\tilde{k} - \overset{\circ}{\tilde{k}} + \lambda_j\lambda_i^*)g(X_j, Z)X_i - (\tilde{k} - \overset{\circ}{\tilde{k}} + \lambda_i\lambda_j^*)g(X_i, Z)X_j = 0$$

and hence $\tilde{k} - \overset{\circ}{\tilde{k}} + \lambda_j \lambda_i^* = \tilde{k} - \overset{\circ}{\tilde{k}} + \lambda_i \lambda_j^* = 0$, which means that

$$\lambda_j \lambda_i^* = \lambda_i \lambda_j^* = -(\tilde{k} - \overset{\circ}{\tilde{k}}) \neq 0.$$

By Eq.(4.4) we have $\lambda_2^* \tau^*(X_1) X_2 - \lambda_1^* \tau^*(X_2) X_1 = 0$, which implies that τ^* vanishes. **Example 4.1.** Suppose \tilde{M} be \mathbb{R}^3 . We define Riemannian metric and an Affine connection by the following relations:

$$\begin{split} \tilde{g} &= a \sum d\theta^{i} d\theta^{i}, \\ \tilde{\nabla}_{\frac{\partial}{\partial \theta^{1}}} \frac{\partial}{\partial \theta^{1}} &= \tilde{b} \frac{\partial}{\partial \theta^{1}}, \tilde{\nabla}_{\frac{\partial}{\partial \theta^{2}}} \frac{\partial}{\partial \theta^{2}} &= \frac{\tilde{b}}{2} \frac{\partial}{\partial \theta^{1}}, \tilde{\nabla}_{\frac{\partial}{\partial \theta^{3}}} \frac{\partial}{\partial \theta^{3}} &= \frac{\tilde{b}}{2} \frac{\partial}{\partial \theta^{1}}, \\ \tilde{\nabla}_{\frac{\partial}{\partial \theta^{1}}} \frac{\partial}{\partial \theta^{2}} &= \tilde{\nabla}_{\frac{\partial}{\partial \theta^{2}}} \frac{\partial}{\partial \theta^{1}} &= \frac{\tilde{b}}{2} \frac{\partial}{\partial \theta^{2}}, \tilde{\nabla}_{\frac{\partial}{\partial \theta^{1}}} \frac{\partial}{\partial \theta^{3}} &= \tilde{\nabla}_{\frac{\partial}{\partial \theta^{3}}} \frac{\partial}{\partial \theta^{1}} &= \frac{\tilde{b}}{2} \frac{\partial}{\partial \theta^{2}}, \\ \tilde{\nabla}_{\frac{\partial}{\partial \theta^{2}}} \frac{\partial}{\partial \theta^{3}} &= \tilde{\nabla}_{\frac{\partial}{\partial \theta^{3}}} \frac{\partial}{\partial \theta^{2}} &= 0. \end{split}$$

Then $(\tilde{M}, \tilde{\nabla}, \tilde{g})$ is a statistical manifold of constant curvature $-\frac{\tilde{b}^2}{4a}$ with a trivial statistical manifold of constant curvature 0 $(\tilde{M}, \tilde{\nabla}^\circ, \tilde{g})$. Suppose M be \mathbb{R}^2 , and (∇, g) an induced statistical structure from $(\tilde{\nabla}, \tilde{g})$ by an immersion $f : (x, y) (\in \mathbb{R}^2) \mapsto (0, x, y)$. We remark that (M, ∇, g) is a trivial statistical manifold of constant curvature 0. Theorem 3.2 and Theorem 4.1 imply the following fact.

Corollary 4.1. Let (M, ∇, g) be a trivial statistical manifold of constant curvature k, $(\tilde{M}, \tilde{\nabla}, \tilde{g})$ a Hessian manifold of constant Hessian curvature \tilde{c} , and $f : M \to \tilde{M}$ a statistical immersion of codimension one. Then $f : M \to \tilde{M}$ is equiaffine, that is, τ^* vanishes.

We consider a shape operator of statistical immersion of a trivial statistical manifold of constant curvature into a Hessian manifold of constant Hessian curvature.

Lemma 4.1. Let (M, ∇, g) be a trivial statistical manifold of constant curvature k, $(\tilde{M}, \tilde{\nabla}, \tilde{g})$ a Hessian manifold of constant Hessian curvature \tilde{c} , and $f : M \to \tilde{M}$ a statistical immersion of codimension one. Then the following holds:

$$A^* = k\nu\tilde{c}^{-1}I, B^* = -\frac{1}{2}\nu I, h = \tilde{c}\nu^{-1}g, A = \tilde{c}\nu^{-1}I, B = [2\tilde{c}^2 - (2k + \tilde{c})\nu^2](2\nu\tilde{c})^{-1}I.$$

Proof. Combining Eq.(2.3) and Eq.(3.6) in [3] with Eq.(2.1), we have

$$\begin{aligned} & \frac{c}{2} \{ g(Y,Z)X - g(X,Z)Y \} = 2(k - \overset{\circ}{k}) \{ g(Y,Z)X - g(X,Z)Y \} \\ & -b(Y,Z)A^*X + b(X,Z)A^*Y + h(X,Z)B^*Y - h(Y,Z)B^*X \\ & 0 = h(X,K(Y,Z)) - h(Y,K(X,Z)) + (\nabla_X b)(Y,Z) - (\nabla_Y b)(X,Z) \\ & +\tau^*(X)b(Y,Z) - \tau^*(Y)b(X,Z) - \tau^*(Y)h(X,Z) + \tau^*(X)h(Y,Z) \quad (4.6) \\ & 0 = K(Y,A^*X) - K(X,A^*Y) - \tau^*(Y)A^*X + \tau^*(X)A^*Y \\ & -(\nabla_X B^*Y) + (\nabla_Y B^*)X + \tau^*(X)B^*Y - \tau^*(Y)B^*X \\ & 0 = -h(X,B^*Y) + h(Y,B^*X) + (\nabla_X \tau^*)(Y) - (\nabla_Y \tau^*)(X) + b(Y,A^*X) - b(X,A^*Y) \end{aligned}$$

Taking the trace of $(4.6)_1$ with respect to *X*, we have

$$-\tilde{c}g(Y,Z) = -trA^*b(Y,Z) + h(B^*Z,Y) + h(B^*Y,Z)$$

and taking the trace of $(4.6)_1$ with respect to *Y*, we have

$$-\frac{\tilde{c}}{2}(n+1)g(X,Z) = -b(A^*X,Z) + h(X,B^*Z) + trB^*h(X,Z).$$

Using the above equation and $Eq.(4.6)_4$, we have

$$-\frac{c}{2}(n+2)g(X,Y) = -b(A^*X,Y) + h(X,B^*Y) + trB^*h(Y,Y).$$

-h(X,Y)\nu - h(X,B^*Y) + (\nabla_X\tau^*)Y + b(Y,A^*X)
= trB^*h(X,Y) - h(X,Y)\nu + (\nabla_x\tau^*)Y

and since from Corollary 4.1 $\tau^* = 0$ holds, we have

$$(\nu - trB^*)h(X,Y) = \frac{\tilde{c}}{2}(n+2)g(X,Y).$$

Hence we have

$$h = \frac{\tilde{c}}{2}(n+2)(\nu - trB^*)^{-1}g.$$
(4.7)

If $\tilde{c} \neq 0$ holds, *h* is non-degenerated.

Since $\tilde{\nabla}$ is flat in Gaussian equation in [3], we obtain

$$k\{g(Y,Z)X - g(X,Z)Y\} = h(Y,Z)A^*X - h(X,Z)A^*Y$$

and taking the trace of above equation with respect to *X*, we have

$$k(n-1)g(Y,Z) = trA^*h(Y,Z) - h(A^*Y,Z) = h((trA^*I - A^*)Y,Z) = h((trA^*I - A^*)Y) = h((trA^*I - A^*)$$

Since the above equation and Eq.(4.7) imply that

$$k(n-1)I = \frac{\tilde{c}}{2}(n+2)(\nu - trB^*)^{-1}(trA^*I - A^*),$$

there is $a \in \mathbf{R}$ such that $A^* = aI$ and $trA^* = an$. Therefore the above equation implies that

$$k(n-1)I = \frac{c}{2}(n+2)(\nu - trB^*)^{-1}(na-a)I$$

and thus since

$$2k(\nu - trB^*) = \tilde{c}(n+2)a,$$

we have

$$A^* = 2k(\nu - trB^*)[\tilde{c}(n+2)]^{-1}I.$$
(4.8)

If $k \neq 0$ holds, then since A^* is non-degenerated, by Eq.(4.8) we have

$$B^* = -\frac{\nu}{2}I, \ trB^* = -\frac{n\nu}{2}$$

and

$$A^* = \frac{2k(\nu + \frac{n\nu}{2})}{\tilde{c}(n+2)}I = \frac{k\nu}{\tilde{c}}I, h = \frac{\tilde{c}}{2}(n+2)(\nu + \frac{n\nu}{2})^{-1}g = \frac{\tilde{c}}{\nu}g.$$

Since h(X, Y) = g(AX, Y), we have $A = \frac{\tilde{c}}{\nu}I$ and

$$B = B^* + (A - A^*) = -\frac{\nu}{2}I + (\frac{\tilde{c}}{\nu} - \frac{k\nu}{\tilde{c}})I = \frac{-\nu^2\tilde{c} + 2\tilde{c}^2 - 2k\nu^2}{2\nu\tilde{c}}I = \frac{2\tilde{c}^2 - (2k + \tilde{c})\nu^2}{2\nu\tilde{c}}I.$$

Theorem 4.2. Let (M, ∇, g) be a trivial statistical manifold of constant curvature k, $(\tilde{M}, \tilde{\nabla}, \tilde{g})$ a Hessian manifold of constant Hessian curvature \tilde{c} . If there is a statistical immersion of codimension one $f : M \to \tilde{M}$, $2k + \tilde{c}$ is of non-negative. Moreover, when \tilde{c} is positive, the Riemannian shape operator of $f : M \to \tilde{M}$ is given by $S = \pm \frac{1}{2}\sqrt{2k + \tilde{c}I}$.

Proof. By Lemma 4.1 and Eq.(4.2), we have

$$\frac{\tilde{c}}{4} \{g(Y,Z)X - g(X,Z)Y\} + \frac{2\tilde{c}^2 - (2k+\tilde{c})\nu^2}{2\nu\tilde{c}} (-\frac{\nu}{2}) \{g(Y,Z)X - g(X,Z)Y\} \\ = \left[\frac{\tilde{c}}{4} - \frac{2\tilde{c}^2 - (2k+\tilde{c})\nu^2}{4\tilde{c}}\right] \{g(Y,Z)X - g(X,Z)Y\} = 0$$

and thus conclude that

$$rac{ ilde{c}}{4}-rac{2 ilde{c}^2-(2k+ ilde{c})
u^2}{4 ilde{c}}=0.$$

Since $\tilde{c}^2 = (2k + \tilde{c})v^2$, we have $2k + \tilde{c} \ge 0$ and

$$\nu = \pm \frac{|\tilde{c}|}{\sqrt{2k + \tilde{c}}}.$$

Thus the Riemannian shape operator *S* is given by

$$S = A^* - B^* = \left(\frac{k\nu}{\tilde{c}} + \frac{\nu}{2}\right)I = \frac{2k + \tilde{c}}{2\tilde{c}} \left(\pm \frac{|\tilde{c}|}{\sqrt{2k + \tilde{c}}}\right)I = \pm \frac{|\tilde{c}|}{2\tilde{c}}\sqrt{2k + \tilde{c}}I.$$

When \tilde{c} is positive, we have $S = \pm \frac{1}{2}\sqrt{2k + \tilde{c}I}$.

Example 4.2. Let $(H, \tilde{\nabla}, \tilde{g})$ be the (n + 1)-dimensional upper half Hessian space of constant Hessian curvature 4 as in Example 2.1. For a constant $y_0 > 0$, write the following immersion by f:

$$(y^1, \cdots, y^n)^T (\in \mathbf{R}^n) \mapsto (y^1, \cdots, y^n, y_0)^T \in H.$$

Let (∇, g) be the statistical structure on \mathbb{R}^n induced by f from $(\tilde{\nabla}, \tilde{g})$. Then $(\mathbb{R}^n, \nabla, g)$ is a trivial statistical manifold of constant curvature 0 and f is a statistical immersion of a trivial statistical manifold of constant curvature into Hessian manifold of constant Hessian curvature.

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FACULTY OF MATHEMATICS,

KIM IL SUNG UNIVERSITY,

DEMOCRATIC PEOPLE'S REPUBLIC OF KOREA.

E-mail address: mincholrim@yahoo.com

E-mail address: choesongok@yahoo.com

E-mail address: anyunho@yahoo.com